

Circe Version 2.0: Beam Spectra for Simulating Linear Collider and Photon Collider Physics*

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Abstract

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Program Summary:

- **Title of program:** Circe, Version 2.0 (August 2002)
- **Program obtainable from**
<http://theorie.physik.uni-wuerzburg.de/~ohl/circe2/>.
- **Licensing provisions:** Free software under the GNU General Public License.
- **Programming languages used:** originally FORTRAN77, transferred to FORTRAN90, Objective Caml[8] (available from <http://caml.inria.fr/ocaml/>).
- **Number of program lines in distributed program** \approx 800 lines of FORTRAN90 (excluding comments) for the library; \approx 4000 lines of Objective Caml for the utility program
- **Computer/Operating System:** Any with a FORTRAN90 programming environment.
- **Memory required to execute with typical data:** Negligible on the scale of typical applications calling the library.
- **Typical running time:** A negligible fraction of the running time of applications calling the library.
- **Purpose of program:** Provide efficient, realistic and reproducible parameterizations of the correlated e^\pm - and γ -beam spectra for linear colliders and photon colliders.
- **Nature of physical problem:** The intricate beam dynamics in the interaction region of a high luminosity linear collider at $\sqrt{s} = 500\text{GeV}$ result in non-trivial energy spectra of the scattering electrons, positrons and photons. Physics simulations require efficient, reproducible, realistic and easy-to-use parameterizations of these spectra.
- **Method of solution:** Parameterization, curve fitting, adaptive sampling, Monte Carlo event generation.
- **Keywords:** Event generation, beamstrahlung, linear colliders, photon colliders.

1 Introduction

The expeditious construction of a high-energy, high-luminosity e^+e^- Linear Collider (LC) to complement the Large Hadron Collider (LHC) has been identified as the next world wide project for High Energy Physics (HEP). The dynamics of the dense colliding beams providing the high luminosities required by such a facility is highly non-trivial and detailed simulations have to be performed to predict the energy spectra provided by these beams. The microscopic simulations of the beam dynamics require too much computer time and memory for direct use in physics programs. Nevertheless, the results of such simulations have to be available as input for physics studies, since these spectra affect the sensitivity of experiments for the search for deviations from the standard model and to new physics.

Circe Version 1.x (**Circe1** for short) [1] has become a de-facto standard for inclusion of realistic energy spectra of TeV-scale e^+e^- LCs in physics calculations and event generators. It is supported by the major multi purpose event generators [2, 3] and has been used in many dedicated analyses. **Circe** provides a fast, concise and convenient parameterization of the results of such simulations.

Circe1 assumed strictly factorized distributions with a very restricted functional form (see [1] for details). This approach was sufficient for exploratory studies of physics at TeV-scale e^+e^- LCs. Future studies of physics at e^+e^- LCs will require a more detailed description and the estimation of non-factorized contributions. In particular, all distributions at laser backscattering $\gamma\gamma$ colliders [4] and at multi-TeV e^+e^- LCs are correlated and can not be approximated by **Circe1** at all. In addition, the proliferation of accelerator designs since the release of **Circe1** has made the maintenance of parameterizations as FORTRAN77 BLOCK DATA unwieldy.

Circe Version 2.0 (**Circe2** for short) successfully addresses these shortcomings of **Circe1**, as can be seen in figure 1. It should be noted that the large z region and the blown-up $z \rightarrow 0$ region are taken from the *same* pair of datasets. In section 6.2 below, figures 3 to 9 demonstrate the interplay of **Circe2**'s features. The algorithms implemented¹ in **Circe2** should suffice for all studies until e^+e^- LCs and photon colliders come on-line and probably beyond. The implementation **Circe2** bears no resemblance at all with the implementation of **Circe1**.

Circe2 describes the distributions by two-dimensional grids that are optimized using an algorithm derived from VEGAS [5]. The implementation was

¹A small number of well defined extensions that has have not been implemented yet are identified in section 3 below.

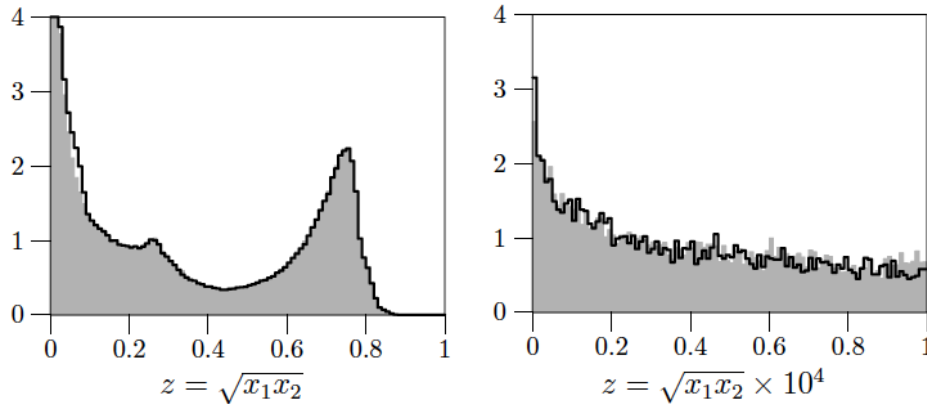


Figure 1: Comparison of a simulated realistic $\gamma\gamma$ luminosity spectrum (helicities: $(+, +)$) for a 500 GeV photon collider at TESLA [7] (filled area) with its **Circe2** parameterization (solid line) using 50 bins in both directions. The 10^4 -fold blow-up of the $z \rightarrow 0$ region is taken from the same pair of datasets as the plot including the large z region.

modeled on the implementation in VAMP [6], but changes were required for sampling static event sets instead of distributions given as functions. The problem solved by **Circe2** is rather different from the Monte Carlo integration with importance or stratified sampling that is the focus of VEGAS and VAMP. In the case of VEGAS/VAMP the function is given as a mathematical function, either analytically or numerically. In this case, while the adapted grid is being refined, resources can be invested for studying the function more closely in problematic regions. **Circe2** does not have this luxury, because it must reconstruct (“guess”) a function from a *fixed* and *finite* sample. Therefore it cannot avoid to introduce biases, either through a fixed global functional form (as in **Circe1**) through step functions (histograms). **Circe2** combines the two approaches and uses automatically adapted histograms mapped by a patchwork of functions.

1.1 Notes on the Implementation

The FORTRAN90 library is extremely simple (about 800 lines) and performs only two tasks: one small set of subroutines efficiently generates pairs of random numbers distributed according to two dimensional histograms with factorized non-uniform bins stored in a file. A second set of functions calculates the value of the corresponding distributions.

In the original implementation, FORTRAN77 has been chosen solely for practical reasons: at the time of the original writing, the majority of programs expected to use the `Circe2` have been legacy applications written in FORTRAN77. The simple functionality of the FORTRAN90 library can however be reproduced trivially in any other programming language that will be needed in the future.

The non-trivial part of constructing an optimized histogram from an arbitrary distribution is performed by a utility program `circe2_tool` written in Objective Caml [8] (or O’Caml for short). O’Caml is available as Free Software for almost all computers and operating systems currently used in high energy physics. Bootstrapping the O’Caml compiler is straightforward and quick. Furthermore, parameterizations are distributed together with `Circe2`, and most users will not even need to compile `circe2_tool`. Therefore there are no practical problems in using a modern programming language like O’Caml that allows—in the author’s experience—a both more rapid and safer development than FORTRAN77 or C++.

1.2 Overview

The remainder of this paper is organized as follows. For the benefit of users of the library, the Application Program Interface (API) is described immediately in section 3 after defining the notation in section 2. Section 4 shows some examples using the procedures described in section 3.

A description of the inner workings of `Circe2` that is more detailed than required for using the library starts in section 5. An understanding of the algorithms employed is helpful for preparing beam descriptions using the program `circe2_tool` which is described in section 6. Details of the implementation of `circe2_tool` can be found in section 7, where also the benefits provided by modern functional programming languages for program organization in the large are discussed.

2 Physics

The customary parametrization of polarization in beam physics [9, 10] is in terms of density matrices for the leptons

$$\rho_{e^\pm}(\zeta) = \frac{1}{2} (1 + \zeta_i \sigma_i) \quad (1)$$

and the so-called Stokes’ parameters for photons

$$\rho_\gamma(\xi) = \frac{1}{2} (1 + \xi_i \sigma_i) \quad (2)$$

where the pseudo density matrix 2×2 -matrix ρ_γ for a pure polarization state ϵ_μ is given by

$$[\rho_\gamma]_{ij} = \langle (\epsilon e_i)(\epsilon^* e_j) \rangle \quad (3)$$

using two unit vectors $e_{1/2}$ orthogonal to the momentum. Keeping in mind the different interpretations of ζ and ξ , we will from now on unify the mathematical treatment and use the two interchangeably, since the correct interpretation will always be clear from the context. Using the notation $\sigma_0 = 1$, the joint polarization density matrix for two colliding particles can be written

$$\rho(\chi) = \sum_{a,a'=0}^3 \frac{\chi_{aa'}}{4} \sigma_a \otimes \sigma_{a'} \quad (4)$$

with $\chi_{0,0} = \text{tr } \rho(\chi) = 1$. Averaging density matrices will in general lead to correlated density matrices, even if the density matrices that are being averaged are factorized or correspond to pure states.

The most complete description B of a pair of colliding beams is therefore provided by a probability density and a density matrix for each pair (x_1, x_2) of energy fractions:

$$\begin{aligned} B : [0, 1] \times [0, 1] &\rightarrow \mathbf{R}^+ \times M \\ (x_1, x_2) &\mapsto (D(x_1, x_2), \rho(x_1, x_2)) \end{aligned} \quad (5)$$

where $\rho(x_1, x_2)$ will conveniently be given using the parametrization (4). Sophisticated event generators can use $D(x_1, x_2)$ and $\rho(x_1, x_2)$ to account for all spin correlations with the on-shell transition matrix T

$$d\sigma = \int dx_1 \wedge dx_2 D(x_1, x_2) \text{tr} (P_\Omega T(x_1 x_2 s) \rho(x_1, x_2) T^\dagger(x_1 x_2 s)) \text{ dLIPS} \quad (6)$$

2.1 Polarization Averaged Distributions

Physics applications that either ignore polarization (this is often not advisable, but can be a necessary compromise in some cases) or know that polarization will play no significant role can ignore the density matrix, which amounts to summing over all polarization states. If the microscopic simulations that have been used to obtain the distributions described by `Circe2` do not keep track of polarization, 93% of disk space can be saved by supporting simplified interfaces that ignore polarization altogether.

2.2 Helicity Distributions

Between the extremes of polarization averaged distributions on one end and full correlated density matrices on the other end, there is one particularly

important case for typical applications, that deserves a dedicated implementation.

In the approximation of projecting on the subspace consisting of circular polarizations

$$\rho(\chi) = \frac{1}{4} (\chi_{0,0} \cdot 1 \otimes 1 + \chi_{0,3} \cdot 1 \otimes \sigma_3 + \chi_{3,0} \cdot \sigma_3 \otimes 1 + \chi_{3,3} \cdot \sigma_3 \otimes \sigma_3) \quad (7)$$

the density matrix can be rewritten as a convex combination of manifest projection operators build out of $\sigma_{\pm} = (1 \pm \sigma_3)/2$:

$$\rho(\chi) = \chi_{++} \cdot \sigma_+ \otimes \sigma_+ + \chi_{+-} \cdot \sigma_+ \otimes \sigma_- + \chi_{-+} \cdot \sigma_- \otimes \sigma_+ + \chi_{--} \cdot \sigma_- \otimes \sigma_- \quad (8)$$

The coefficients are given by

$$\chi_{++} = \frac{1}{4} (\chi_{0,0} + \chi_{0,3} + \chi_{3,0} + \chi_{3,3}) \geq 0 \quad (9a)$$

$$\chi_{+-} = \frac{1}{4} (\chi_{0,0} - \chi_{0,3} + \chi_{3,0} - \chi_{3,3}) \geq 0 \quad (9b)$$

$$\chi_{-+} = \frac{1}{4} (\chi_{0,0} + \chi_{0,3} - \chi_{3,0} - \chi_{3,3}) \geq 0 \quad (9c)$$

$$\chi_{--} = \frac{1}{4} (\chi_{0,0} - \chi_{0,3} - \chi_{3,0} + \chi_{3,3}) \geq 0 \quad (9d)$$

and satisfy

$$\chi_{++} + \chi_{+-} + \chi_{-+} + \chi_{--} = \text{tr } \rho(\chi) = 1 \quad (10)$$

Of course, the $\chi_{\epsilon_1 \epsilon_2}$ are recognized as the probabilities for finding a particular combination of helicities for particles moving along the $\pm \vec{e}_3$ direction and we can introduce partial probability distributions

$$D_{p_1 p_2}^{\epsilon_1 \epsilon_2}(x_1, x_2) = \chi_{\epsilon_1 \epsilon_2} \cdot D_{p_1 p_2}(x_1, x_2) \geq 0 \quad (11)$$

that are to be combined with the polarized cross sections

$$\frac{d\sigma}{d\Omega}(s) = \sum_{\epsilon_1, \epsilon_2 = \pm} \int dx_1 \wedge dx_2 D^{\epsilon_1 \epsilon_2}(x_1, x_2) \left(\frac{d\sigma}{d\Omega} \right)^{\epsilon_1 \epsilon_2}(x_1 x_2 s) \quad (12)$$

This case deserves special consideration because it is a good approximation for a majority of applications and, at the same time, it is the most general case that allows an interpretation as classical probabilities. The latter feature allows the preparation of separately tuned probability densities for all four helicity combinations. In practical applications this turns out to be useful because the power law behaviour of the extreme low energy tails turns out to have a mild polarization dependence.

load beam	from file	<code>cir2ld</code>	(p. 9)
	from <code>block data</code>	<code>cir2lb</code>	(optional, p. 16)
distributions	luminosity	<code>cir2lm</code>	(p. 11)
	probability density	<code>cir2dn</code>	(p. 14)
	density matrix	<code>cir2dm</code>	(extension, p. 16)
event generation	flavors/helicities	<code>cir2ch</code>	(p. 12)
	(x_1, x_2)	<code>cir2gn</code>	(p. 12)
	general polarization	<code>cir2gp</code>	(extension, p. 14)
internal	current beam	<code>/cir2cm/</code>	(p. 16)
	beam data base	<code>cir2bd</code>	(optional, p. 16)
	(cont'd)	<code>/cir2cd/</code>	(optional, p. 16)

Table 1: Summary of all functions, procedures and comon blocks.

3 API

All floating point numbers in the interfaces are declared as `double precision`. In most applications, the accuracy provided by single precision floating point numbers is likely to suffice. However most application programs will use double precision floating point numbers anyway so the most convenient choice is to use double precision in the interfaces as well.

In all interfaces, the integer particle codes follow the conventions of the Particle Data Group [11]. In particular

`p = 11`: electrons

`p = -11`: positrons

`p = 22`: photons

while other particles are unlikely to appear in the context of `Circe2` before the design of μ -colliders enters a more concrete stage. Similarly, in all interfaces, the sign of the helicities are denoted by integers

`h = 1`: helicity +1 for photons or +1/2 for leptons (electrons and positrons)

`h = -1`: helicity -1 for photons or -1/2 for leptons (electrons and positrons)

As part of tis API, we also define a few extensions, which will be available in future versions, but have not been implemented yet. This allows application programs to anticipate these extensions.

3.1 Initialization

Before any of the event generation routines or the functions computing probability densities can be used, beam descriptions have to be loaded. This is accomplished by the routine `cir2ld` (mnemonic: *LoaD*), which must have been called at least once before any other procedure is invoked:

```
subroutine cir2ld (file, design, roots, ierror)
```

`character*(*) file` (input): name of a `Circe2` parameter file in the format described in table 2. Conventions for filenames are system dependent and the names of files will consequently be installation dependent. This can not be avoided.

`character*(*) design` (input): name of the accelerator design. The name must not be longer than 72 characters. It is expected that design names follow the following naming scheme for e^+e^- LCs

TESLA: TESLA superconducting design (DESY)

XBAND: NLC/JLC X-band design (KEK, SLAC)

CLIC: CLIC two-beam design (CERN)

Special operating modes should be designated by a qualifier

/GG: laser backscattering $\gamma\gamma$ collider (e. g. 'TESLA/GG')

/GE: laser backscattering γe^- collider

/EE: e^-e^- collider

If there is more than one matching beam description, the *last* of them is used. If `design` contains a '*', only the characters *before* the '*' matter in the match. E. g.:

`design = 'TESLA'` matches only 'TESLA'

`design = 'TESLA*'` matches any of 'TESLA (Higgs factory)', 'TESLA (GigaZ)', 'TESLA', etc.

`design = '*'` matches everything and is a convenient shorthand for the case that there is only a single design per file

NB: '*' is not a real wildcard: everything after the first '*' is ignored.

`double precision roots` (input): \sqrt{s} /GeV of the accelerator. This must match within $\Delta\sqrt{s} = 1$ GeV. There is currently no facility for interpolation between fixed energy designs (see section 4.3, however).

`integer ierror` (input/output): if `ierror` > 0 on input, comments will be echoed to the standard output stream. On output, if no errors have been encountered `cir2ld` guarantees that `ierror` = 0. If `ierror` < 0, an error has occurred:

```

ierror = -1: file not found
ierror = -2: no match for design and  $\sqrt{s}$ 
ierror = -3: invalid format of parameter file
ierror = -4: parameter file too large

```

A typical application, assuming that a file named `photon_colliders.circe` contains beam descriptions for photon colliders (including TESLA/GG) is

```

integer ierror
...
ierror = 1
call cir2ld ('photon_colliders.circe', 'TESLA/GG', 500D0, ierror)
if (ierror .lt. 0)
  print *, 'error: cir2ld failed: ', ierror
  stop
end if
...

```

In order to allow application programs to be as independent from operating system dependent file naming conventions, the file formal has been designed so beam descriptions can be concatenated and application programs can hide file names from the user completely, as in

```

subroutine ldbeam (design, roots, ierror)
implicit none
character*(*) design
double precision roots
integer ierror
call cir2ld ('beam_descriptions.circe', design, roots, ierror)
if (ierror .eq. -1)
  print *, 'ldbeam: internal error: file not found'
  stop
end if
end

```

The other extreme uses one file per design and uses the '*' wildcard to make the `design` argument superfluous.

```
subroutine ldfile (name, roots, ierror)
implicit none
character*(*) name
double precision roots
integer ierror
call cir2ld (name, '*', roots, ierror)
end
```

Note that while it is in principle possible to use a data file intended for helicity states for polarization averaged distributions instead, no convenience procedures for this purpose are provided.

3.2 Luminosities

One of the results of the simulations that provide the input for `Circe2` are the partial luminosities for all combinations of flavors and helicities. The luminosities for a combination of flavors and helicities can be inspected with the function `cir2lm` (*LuMinosity*). The return value is given in the convenient units

$$\text{fb}^{-1} \nu^{-1} = 10^{32} \text{cm}^{-2} \text{sec}^{-1} \quad (13)$$

where $\nu = 10^7 \text{ sec} \approx \text{year}/\pi$ is an “effective year” of running with about 30% up-time

```
function cir2lm (p1, h1, p2, h2)

integer :: p1 (input): particle code for the first particle
integer :: h1 (input): helicity of the first particle
integer :: p2 (input): particle code for the second particle
integer :: h2 (input): helicity of the second particle
```

For the particle codes and helicities the special value 0 can be used to imply a sum over all flavors and helicities. E.g. the total luminosity is obtained with

```
lumi = cir2lm (0, 0, 0, 0)
```

and the $\gamma\gamma$ luminosity summed over all helicities

```
lumigg = cir2lm (22, 0, 22, 0)
```

3.3 Sampling and Event Generation

Given a combination of flavors and helicities, the routine `cir2gn` (*GeNerate*) can be called repeatedly to obtain a sample of pairs (x_1, x_2) distributed according to the currently loaded beam description:

```
subroutine cir2gn (p1, h1, p2, h2, x1, x2, rng)

  integer p1 (input): particle code for the first particle
  integer h1 (input): helicity of the first particle
  integer p2 (input): particle code for the second particle
  integer h2 (input): helicity of the second particle
  double precision x1 (output): fraction of the beam en-
    ergy carried by the first particle
  double precision x2 (output): fraction of the beam en-
    ergy carried by the second particle
  external rng: subroutine

    subroutine rng (u)
      double precision u
      u = ...
    end

    generating a uniform deviate, i.e. a random number uni-
    formly distributed in  $[0, 1]$ .
```

If the combination of flavors and helicities has zero luminosity for the selected accelerator design parameters, *no error code* is available (`x1` and `x2` are set to a very large negative value in this case). Applications should use `cir2lm` to test that the luminosity is non vanishing.

Instead of scanning the luminosities for all possible combinations of flavors and helicities, applications can call the procedure `cir2ch` (*CHannel*) which chooses a “channel” (a combination of flavors and helicities) for the currently loaded beam description with the relative probabilities given by the luminosities:

```
subroutine cir2ch (p1, h1, p2, h2, rng)

  integer p1 (output): particle code for the first particle
  integer h1 (output): helicity of the first particle
  integer p2 (output): particle code for the second particle
```

`integer h2` (output): helicity of the second particle
`external rng`: subroutine generating a uniform deviate (as above)

Many applications will use these two functions only in the combination

```
subroutine circe2 (p1, h1, p2, h2, x1, x2, rng)
integer p1, h1, p2, h2
double precision x1, x2
external rng
call cir2ch (p1, h1, p2, h2, rng)
call cir2gn (p1, h1, p2, h2, x1, x2, rng)
end
```

after which randomly distributed `p1`, `h1`, `p2`, `h2`, `x1`, and `x2` are available for further processing.

NB: a function like `circe2` has not been added to the default FORTRAN90 API, because `cir2gn` and `circe2` have the same number and types of arguments, differing only in the input/output direction of four of the arguments. This is a source of errors that a FORTRAN90 compiler can not help the application programmer to spot. The current design should be less error prone and is only minimally less convenient because of the additional procedure call

```
integer p1, h1, p2, h2
double precision x1, x2
integer n, nevent
external rng
...
do 10 n = 1, nevent
  call cir2ch (p1, h1, p2, h2, rng)
  call cir2gn (p1, h1, p2, h2, x1, x2, rng)
...
10 continue
...
```

Implementations in more modern programming languages (Fortran90/95, C++, Java, O'Caml, etc.) can and will provide a richer API with reduced name space pollution and danger of confusion.

3.3.1 Extensions: General Polarizations

Given a pair of flavors, triples (x_1, x_2, ρ) of momentum fractions together with density matrices for the polarizations distributed according to the cur-

rently loaded beam descriptions can be obtained by repeatedly calling `cir2gp` (*GeneratePolarized*):

```
subroutine cir2gp (p1, p2, x1, x2, pol, rng)

  integer p1 (input): particle code for the first particle
  integer p2 (input): particle code for the second particle
  double precision x1 (output): fraction of the beam en-
    ergy carried by the first particle
  double precision x2 (output): fraction of the beam en-
    ergy carried by the second particle
  double precision pol(0:3,0:3) (output): the joint den-
    sity matrix of the two polarizations is parametrized by a
    real  $4 \times 4$ -matrix
```

$$\rho(\chi) = \sum_{a,a'=0}^3 \frac{\chi_{aa'}}{4} \sigma_a \otimes \sigma_{a'} \quad (14)$$

using the notation $\sigma_0 = 1$. We have `pol(0,0) = 1` since $\text{tr } \rho = 1$.

```
external rng: subroutine generating a uniform deviate
```

This procedure has not been implemented in version 2.0 and will be provided in release 2.1.

3.4 Distributions

The normalized luminosity density $D_{p_1 p_2}(x_1, x_2)$ for the given flavor and helicity combination for the currently loaded beam description satisfies

$$\int dx_1 \wedge dx_2 D_{p_1 p_2}(x_1, x_2) = 1 \quad (15)$$

and is calculated by `cir2dn` (*DistributionN*):

```
double precision function cir2dn (p1, h1, p2, h2, x1, x2)

  integer p1 (input): particle code for the first particle
  integer h1 (input): helicity of the first particle
  integer p2 (input): particle code for the second particle
  integer h2 (input): helicity of the second particle
```

double precision x1 (input): fraction of the beam energy
carried by the first particle

double precision x2 (input): fraction of the beam energy
carried by the second particle

If any of the helicities is 0 and the loaded beam description is not summed over polarizations, the result is *not* the polarization summed distribution and 0 is returned instead. Application programs must either sum by themselves or load a more efficient abbreviated beam description.

Circe1 users should take note that the densities are now normalized *individually* and no longer relative to a master e^+e^- distribution. Users of **Circe1** should also take note that the special treatment of δ -distributions at the endpoints has been removed. The corresponding contributions have been included in small bins close to the endpoints. For small enough bins, this approach is sufficiently accurate and avoids the pitfalls of the approach of **Circe1**.

◆ Applications that convolute the **Circe2** distributions with other distributions can benefit from accessing the map employed by **Circe2** internally through **cir2mp** (*MaP*):

```
subroutine cir2mp (p1, h1, p2, h2, x1, x2, m1, m2, d)
  integer p1 (input): particle code for the first particle
  integer h1 (input): helicity of the first particle
  integer p2 (input): particle code for the second particle
  integer h2 (input): helicity of the second particle
  double precision x1 (input): fraction of the beam en-
    ergy carried by the first particle
  double precision x2 (input): fraction of the beam en-
    ergy carried by the second particle
  integer m1 (output): map
  integer m2 (output): map
  double precision d (output):
```

3.4.1 Extensions: General Polarizations

The product of the normalized luminosity density $D_{p_1 p_2}(x_1, x_2)$ and the joint polarization density matrix for the given flavor and helicity combination for the currently loaded beam description is calculated by **cir2dm** (*DensityMatrices*):

double precision function cir2dm (p1, p2, x1, x2, pol)

integer p1 (input): particle code for the first particle

integer p2 (input): particle code for the second particle

double precision x1 (input): fraction of the beam energy
carried by the first particle

double precision x2 (input): fraction of the beam energy
carried by the second particle

double precision pol(0:3,0:3) (output): the joint den-
sity matrix multiplied by the normalized probability den-
sity. The density matrix is parametrized by a real 4×4 -
matrix

$$D_{p_1 p_2}(x_1, x_2) \cdot \rho(\chi) = \sum_{a, a'=0}^3 \frac{1}{4} \chi_{p_1 p_2, aa'}(x_1, x_2) \sigma_a \otimes \sigma_{a'} \quad (16)$$

using the notation $\sigma_0 = 1$. We have $\text{pol}(0,0) = D_{p_1 p_2}(x_1, x_2)$
since $\text{tr } \rho = 1$.

*This procedure has not been implemented in version 2.0 and will be provided
in release 2.1.*

3.5 Private Parts

The following need not concern application programmer, except that there
must be no clash with any other global name in the application program:

common /cir2cm/: the internal data store for Circe2, which *must not*
be accessed by application programs.

3.6 Optional API

The following is part of a separate library that can be loaded optionally. The
beam description can be loaded from the block data segment cir2bd by
cir2lb (*LoadBlockdata*):

subroutine cir2lb (design, roots, ierror)

common /cir2cd/: an optional and very big internal data store for
Circe2, which *must not* be accessed by application programs.

block data cir2bd: data for /cir2bd/

*This procedure has not been implemented yet and will be provided in a future
release.*

4 Examples

In this section, we collect some simple yet complete examples using the API described in section 3. In all examples, the role of the physics application is played by a `write` statement, which would be replaced by an appropriate event generator for hard scattering physics or background events. The examples assume the existence of either a file `default.circe` describing polarized $\sqrt{s} = 500 \text{ GeV}$ beams or an abbreviated file `default_polavg.circe` where the helicities are summed over.

4.1 Unweighted Event Generation

`Circe2` has been designed for the efficient generation of unweighted events, i.e. event samples that are distributed according to the given probability density. Examples of weighted events are discussed in section 4.2 below.

4.1.1 Mixed Flavors and Helicities

The most straightforward application uses a stream of events with a mixture of flavors and helicities in *random* order. If the application can consume events without the need for costly reinitializations when the flavors are changed, a simple loop around `cir2ch` and `cir2gn` suffices:

```
program demo1
  use kinds
  use circe2
  implicit none
  integer :: p1, h1, p2, h2, n, nevent, ierror
  real(kind=double) :: x1, x2
  external random
  nevent = 20
  ierror = 1
  call cir2ld ('default.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  write (*, '(A7,4(1X,A4),2(1X,A10))') &
    '#', 'pdg1', 'hel1', 'pdg2', 'hel2', 'x1', 'x2'
  do n = 1, nevent
    call cir2ch (p1, h1, p2, h2, random)
    call cir2gn (p1, h1, p2, h2, x1, x2, random)
    write (*, '(I7,4(1X,I4),2(1X,F10.8))') n, p1, h1, p2, h2, x1, x2
  end do
end program demo1
```

The following minimalistic linear congruential random number generator can be used for demonstrating the interface, but it is known to produce correlations and *must* be replaced by a more sophisticated one in real applications:

```
subroutine random (r)
  use kinds
  real(kind=double) :: r
  integer, parameter :: M = 259200, A = 7141, C = 54773
  integer, save :: n = 0
  n = mod (n*A + C, M)
  r = real (n, kind=double) / real (M, kind=double)
end subroutine random
```

4.1.2 Separated Flavors and Helicities

If the application can not switch efficiently among flavors and helicities, another approach is more useful. It walks through the flavors and helicities sequentially and uses the partial luminosities `cir2lm` to determine the correct number of events for each combination:

```
program demo2
  use kinds
  use circe2
  implicit none
  integer :: i1, i2, h1, h2, i, n, nevent, nev, ierror
  integer, dimension(3), save :: pdg = (/ 22, 11, -11 /)
  real(kind=double) :: x1, x2, lumi
  external random
  nevent = 20
  ierror = 1
  call cir2ld ('default.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  lumi = cir2lm (0, 0, 0, 0)
  write (*, '(A7,4(1X,A4),2(1X,A10))') &
    '#', 'pdg1', 'hel1', 'pdg2', 'hel2', 'x1', 'x2'
  i = 0
  do i1 = 1, 3
    do i2 = 1, 3
      do h1 = -1, 1, 2
        do h2 = -1, 1, 2
          nev = nevent * cir2lm (pdg(i1), h1, pdg(i2), h2) / lumi
          do n = 1, nev
            call cir2gn (pdg(i1), h1, pdg(i2), h2, x1, x2, random)
            i = i + 1
          end do
        end do
      end do
    end do
  end do
```

```

        write (*, '(I7,4(1X,I4),2(1X,F10.8))') &
            i, pdg(i1), h1, pdg(i2), h2, x1, x2
    end do
end do
end do
end do
end do
end program demo2

```

More care can be taken to guarantee that the total number of events is not reduced by rounding `new` towards 0, but the error will be negligible for reasonably high statistics anyway.

4.1.3 Polarization Averaged

If the helicities are to be ignored, the abbreviated file `default_polavg.circe` can be read. The code remains unchanged, but the variables `h1` and `h2` will always be set to 0.

```

program demo3
  use kinds
  use circe2
  implicit none
  integer :: p1, h1, p2, h2, n, nevent, ierror
  real(kind=double) :: x1, x2
  external random
  nevent = 20
  ierror = 1
  call cir2ld ('default_polavg.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  write (*, '(A7,2(1X,A4),2(1X,A10))') &
      '#', 'pdg1', 'pdg2', 'x1', 'x2'
  do n = 1, nevent
    call cir2ch (p1, h1, p2, h2, random)
    call cir2gn (p1, h1, p2, h2, x1, x2, random)
    write (*, '(I7,2(1X,I4),2(1X,F10.8))') n, p1, p2, x1, x2
  end do
end program demo3

```

4.1.4 Flavors and Helicity Projections

There are three ways to produce samples with a fixed subset of flavors or helicities. As an example, we generate a sample of two photon events with $L = 0$. The first approach generates the two channels $++$ and $--$ sequentially:

```

program demo4
  use kinds
  use circe2
  implicit none
  real(kind=double) :: x1, x2, lumipp, lumimm
  integer :: n, nevent, npp, nmm, ierror
  external random
  nevent = 20
  ierror = 1
  call cir2ld ('default.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  lumipp = cir2lm (22, 1, 22, 1)
  lumimm = cir2lm (22, -1, 22, -1)
  npp = nevent * lumipp / (lumipp + lumimm)
  nmm = nevent - npp
  write (*, '(A7,2(1X,A10))') '#', 'x1', 'x2'
  do n = 1, npp
    call cir2gn (22, 1, 22, 1, x1, x2, random)
    write (*, '(I7,2(1X,F10.8))') n, x1, x2
  end do
  do n = 1, nmm
    call cir2gn (22, -1, 22, -1, x1, x2, random)
    write (*, '(I7,2(1X,F10.8))') n, x1, x2
  end do
end program demo4

```

a second approach alternates between the two possibilities

```

program demo5
  use kinds
  use circe2
  implicit none
  real(kind=double) :: x1, x2, u, lumipp, lumimm
  integer :: n, nevent, ierror
  external random
  nevent = 20
  ierror = 1
  call cir2ld ('default.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  lumipp = cir2lm (22, 1, 22, 1)
  lumimm = cir2lm (22, -1, 22, -1)
  write (*, '(A7,2(1X,A10))') '#', 'x1', 'x2'
  do n = 1, nevent
    call random (u)

```

```

        if (u * (lumipp + lumimm) .lt. lumipp) then
            call cir2gn (22, 1, 22, 1, x1, x2, random)
        else
            call cir2gn (22, -1, 22, -1, x1, x2, random)
        endif
        write (*, '(I7,2(1X,F10.8))') n, x1, x2
    end do
end program demo5

```

finally, the third approach uses rejection to select the desired flavors and helicities

```

program demo6
    use kinds
    use circe2
    implicit none
    integer :: p1, h1, p2, h2, n, nevent, ierror
    real(kind=double) :: x1, x2
    external random
    nevent = 20
    ierror = 1
    call cir2ld ('default.circe', '*', 500D0, ierror)
    if (ierror .lt. 0) stop
    write (*, '(A7,2(1X,A10))') '#', 'x1', 'x2'
    n = 0
    do
        call cir2ch (p1, h1, p2, h2, random)
        call cir2gn (p1, h1, p2, h2, x1, x2, random)
        if ((p1 .eq. 22) .and. (p2 .eq. 22) .and. &
            ((h1 .eq. 1) .and. (h2 .eq. 1)) .or. &
            ((h1 .eq. -1) .and. (h2 .eq. -1)))) then
            n = n + 1
            write (*, '(I7,2(1X,F10.8))') n, x1, x2
        end if
        if (n .ge. nevent) exit
    end do
end program demo6

```

All generated distributions are equivalent, but the chosen subsequences of random numbers will be different. It depends on the application and the channels under consideration, which approach is the most appropriate.

4.2 Distributions and Weighted Event Generation

If no events are to be generated, `cir2dn` can be used to calculate the probability density $D(x_1, x_2)$ at a given point. This can be used for numerical integration other than Monte Carlo or for importance sampling in the case that the distribution to be folded with D is more rapidly varying than D itself.

Depending on the beam descriptions, these distributions are available either for fixed helicities

```
program demo7
  use kinds
  use circe2
  implicit none
  integer :: n, nevent, ierror
  real(kind=double) :: x1, x2, w
  nevent = 20
  ierror = 1
  call cir2ld ('default.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  write (*, '(A7,3(1X,A10))') '#', 'x1', 'x2', 'weight'
  do n = 1, nevent
    call random (x1)
    call random (x2)
    w = cir2dn (22, 1, 22, 1, x1, x2)
    write (*, '(I7,2(1X,F10.8),1X,E10.4)') n, x1, x2, w
  end do
end program demo7
```

or summed over all helicities if the beam description is polarization averaged:

```
program demo8
  use kinds
  use circe2
  implicit none
  integer n, nevent, ierror
  real(kind=double) :: x1, x2, w
  nevent = 20
  ierror = 1
  call cir2ld ('default_polavg.circe', '*', 500D0, ierror)
  if (ierror .lt. 0) stop
  write (*, '(A7,3(1X,A10))') '#', 'x1', 'x2', 'weight'
  do n = 1, nevent
    call random (x1)
```

```

        call random (x2)
        w = cir2dn (22, 0, 22, 0, x1, x2)
        write (*, '(I7,2(1X,F10.8),1X,E10.4)') n, x1, x2, w
    end do
end program demo8

```

If the beam description is not polarization averaged, the application can perform the averaging itself (note that each distribution is normalized):

```

program demo9
    use kinds
    use circe2
    implicit none
    integer :: n, nevent, ierror
    real(kind=double) :: x1, x2, w
    real(kind=double) :: lumi, lumipp, lumimp, lumipm, lumimm
    nevent = 20
    ierror = 1
    call cir2ld ('default.circe', '*', 500D0, ierror)
    if (ierror .lt. 0) stop
    lumipp = cir2lm (22, 1, 22, 1)
    lumipm = cir2lm (22, 1, 22, -1)
    lumimp = cir2lm (22, -1, 22, 1)
    lumimm = cir2lm (22, -1, 22, -1)
    lumi = lumipp + lumimp + lumipm + lumimm
    write (*, '(A7,3(1X,A10))') '#', 'x1', 'x2', 'weight'
    do n = 1, nevent
        call random (x1)
        call random (x2)
        w = ( lumipp * cir2dn (22, 1, 22, 1, x1, x2) &
              + lumipm * cir2dn (22, 1, 22, -1, x1, x2) &
              + lumimp * cir2dn (22, -1, 22, 1, x1, x2) &
              + lumimm * cir2dn (22, -1, 22, -1, x1, x2)) / lumi
        write (*, '(I7,2(1X,F10.8),1X,E10.4)') n, x1, x2, w
    end do
end program demo9

```

The results produced by the preceeding pair of examples will differ point-by-point, because the polarized and the polarization summed distribution will be binned differently. However, all histograms of the results with reasonable bin sizes will agree.

4.3 Scans and Interpolations

Currently there is no supported mechanism for interpolating among distributions for the discrete parameter sets. The most useful application of such a facility would be a scan of the energy dependence of an observable

$$\mathcal{O}(s) = \int dx_1 dx_2 d\Omega D(x_1, x_2, s) \frac{d\sigma}{d\Omega}(x_1, x_2, s, \Omega) O(x_1, x_2, s, \Omega) \quad (17a)$$

which has to take into account the s -dependence of the distribution $D(x_1, x_2, s)$. Full simulations of the beam dynamics for each value of s are too costly and `Circe1` [1] supported linear interpolation

$$\bar{D}(x_1, x_2, s) = \frac{(s - s_-)D(x_1, x_2, s_+) + (s_+ - s)D(x_1, x_2, s_-)}{s_+ - s_-} \quad (17b)$$

as an economical compromise. However, since \mathcal{O} in (17) is a strictly *linear* functional of D , it is mathematically equivalent to interpolating \mathcal{O} itself

$$\bar{\mathcal{O}}(s) = \frac{(s - s_-)\tilde{\mathcal{O}}(s, s_+) + (s_+ - s)\tilde{\mathcal{O}}(s, s_-)}{s_+ - s_-} \quad (18a)$$

where

$$\tilde{\mathcal{O}}(s, s_0) = \int dx_1 dx_2 d\Omega D(x_1, x_2, s_0) \frac{d\sigma}{d\Omega}(x_1, x_2, s, \Omega) O(x_1, x_2, s, \Omega) \quad (18b)$$

Of course, evaluating the two integrals in (18) with comparable accuracy demands four times the calculational effort of the single integral in (17). Therefore, if overwhelming demand arises, support for (17) can be reinstated, but at the price of a considerably more involved API for loading distributions.

5 Algorithms

`Circe2` attempts to recover a probability density $w(x_1, x_2)$ from a finite set of triples $\{(x_{1,i}, x_{2,i}, w_i)\}_{i=1,\dots,N}$ that are known to be distributed according to $w(x_1, x_2)$. This recovery should introduce as little bias as possible. The solution should provide a computable form of $w(x_1, x_2)$ as well as a procedure for generating more sets of triples $\{(x_{1,i}, x_{2,i}, w_i)\}$ with “the same” distribution.

The discrete distribution

$$\hat{w}(x_1, w_2) = \sum_i w_i \delta(x_1 - x_{1,i}) \delta(x_2 - x_{2,i}) \quad (19)$$

adds no bias, but is obviously not an adequate solution of the problem, because it depends qualitatively on the sample. While the sought after distribution may contain singularities, their number and the dimension of their support must not depend on the sample size. There is, of course, no unique solution to this problem and we must allow some prejudices to enter in order to single out the most adequate solution.

The method employed by `Circe1` was to select a family of analytical distributions that are satisfy reasonable criteria suggested by physics [1] and select representatives by fitting the parameters of these distributions. This has been unreasonably successful for modelling the general properties, but must fail eventually if finer details are studied. Enlarging the families is theoretically possible but empirically it turns out that the number of free parameters grows faster than the descriptive power of the families.

Another approach is to forego functions that are defined globally by an analytical expression and to perform interpolation of binned samples, requiring continuity of the distribution and their derivatives. Again, this fails in practice, this time because such interpolations tend to create wild fluctuations for statistically distributed data and the resulting distributions will often violate basic conditions like positivity.

Any attempt to recover the distributions that uses local properties will have to bin the data

$$N_i = \int_{\Delta_i} dx w(x) \quad (20)$$

with

$$\Delta_i \cap \Delta_j = \emptyset \quad (i \neq j), \quad \bigcup_i \Delta_i = [0, 1] \times [0, 1] \quad (21)$$

Therefore it appears to be eminently reasonable to approximate w by a piecewise constant

$$\hat{w}(x) = \sum_i \frac{N_i}{|\Delta_i|} \Theta(x \in \Delta_i). \quad (22)$$

However, this procedure also introduces a bias and if the number of bins is to remain finite, this bias cannot be removed.

Nevertheless, one can tune this bias to the problem under study and obtain better approximations by making use of the well known fact that probability distributions are not invariant under coordinate transformations, as described in section ?? below.

5.1 Histograms

The obvious approach to histogramming is to cover the unit square $[0, 1] \times [0, 1]$ uniformly with n_b^2 squares, but this approach is not economical in its

use of storage. For example, high energy physics studies at a $\sqrt{s} = 500$ GeV LC will require an energy resolution of better than 1 GeV and we should bin each beam in steps of 500 MeV, i.e. $n_b = 500$. This results in a two dimensional histogram of $500^2 = 25000$ bins for each combination of flavor and helicity. Using non-portable binary storage, this amounts to 100 KB for typical single precision floating point numbers and 200 KB for typical double precision floating point numbers.

Obviously, binary storage is not a useful exchange format and we have to use an ASCII exchange format, which in its human readable form uses 14 bytes for single precision and 22 bytes for double precision and the above estimates have to be changed to 350 KB and 550 KB respectively. We have four flavor combinations if pair creation is ignored and nine flavor combinations if it is taken into account. For each flavor combination there are four helicity combinations and we arrive at 16 or 36 combinations.

Altogether, a fixed bin histogram requires up to 20 MB of data for *each* accelerator design at *each* energy step for a mere 1% energy resolution. While this could be handled with modern hardware, we have to keep in mind that the storage requirements grow quadratically with the resolution and that several generations of designs should be kept available for comparison studies.

For background studies, low energy tails down to the pair production threshold $m_e = 511$ KeV $\approx 10^{-6} \cdot \sqrt{s}$ have to be described correctly. Obviously, fixed bin histograms are not an option at all in this case.

 mention 2-D Delauney triangulations here

 mention Staszek's FOAM [14] here

 praise VEGAS/VAMP

5.2 Coordinate Dependence of Sampling Distributions

The contents of this section is well known to all practitioners and is repeated only for establishing notation. For any sufficiently smooth (piecewise differentiable suffices) map

$$\begin{aligned}\phi : D_x &\rightarrow D_y \\ x &\mapsto y = \phi(x)\end{aligned}\tag{23}$$

integrals of distribution functions $w : D_y \rightarrow \mathbf{R}$ are invariant, as long as we apply the correct Jacobian factor

$$\int_{D_y} dy w(y) = \int_{D_x} dx \frac{d\phi}{dx} \cdot (w \circ \phi)(x) = \int_{D_x} dx w^\phi(x)\tag{24a}$$

where

$$w^\phi(x) = (w \circ \phi)(x) \cdot \frac{d\phi}{dx}(x) = \frac{(w \circ \phi)(x)}{\left(\frac{d\phi^{-1}}{dy} \circ \phi\right)(x)} \quad (24b)$$

The fraction can be thought of as being defined by the product, if the map ϕ is not invertible. Below, we will always deal with invertible maps and the fraction is more suggestive for our purposes. Therefore, ϕ induces a pull-back map ϕ^* on the space of integrable functions

$$\begin{aligned} \phi^* : L_1(D_y, \mathbf{R}) &\rightarrow L_1(D_x, \mathbf{R}) \\ w &\mapsto w^\phi = \frac{w \circ \phi}{\left(\frac{d\phi^{-1}}{dy} \circ \phi\right)} \end{aligned} \quad (25)$$

If we find a map ϕ_w with $d\phi^{-1}/dy \sim w$, then sampling the transformed weight w^{ϕ_w} will be very stable, even if sampling the original weight w is not.

On the other hand, the inverse map

$$\begin{aligned} (\phi^*)^{-1} : L_1(D_x, \mathbf{R}) &\rightarrow L_1(D_y, \mathbf{R}) \\ w &\mapsto w^{(\phi^{-1})} = \left(\frac{d\phi^{-1}}{dy}\right) \cdot (w \circ \phi^{-1}) \end{aligned} \quad (26)$$

with $(\phi^{-1})^* = (\phi^*)^{-1}$ can be used to transform a uniform distribution into the potentially much more interesting $d\phi^{-1}/dy$.

5.3 Sampling Distributions With Integrable Singularities

A typical example appearing in `Circe1`

$$\int^1 dx w(x) \approx \int^1 dx (1-x)^\beta \quad (27)$$

converges for $\beta > -1$, while the variance

$$\int^1 dx (w(x))^2 \approx \int^1 dx (1-x)^{2\beta} \quad (28)$$

does not converge for $\beta \leq -1/2$. Indeed, this case is the typical case for realistic beamstrahlung spectra at e^+e^- LCs and has to be covered.

Attempting a naive VEGAS/VAMP adaption fails, because the *nonintegrable* variance density acts as a sink for bins, even though the density itself is integrable.

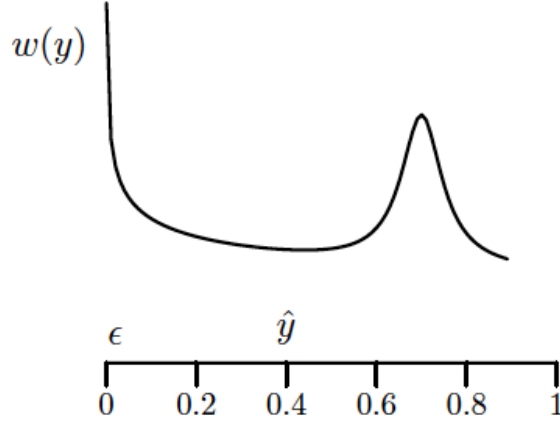


Figure 2: Distribution with both an integrable singularity $\propto x^{-0.2}$ and a peak at finite $x \approx 0.7$.



- examples show that moments of distributions are reproduced *much* better after mapping, even if histograms look indistinguishable.
- biasing doesn't appear to work as well as fences

The distributions that we want to describe can contain integrable singularities and δ -distributions at the endpoints. Since there is always a finite resolution, both contributions can be handled by a finite binsize at the endpoints. However, we can expect to improve the convergence of the grid adaption in neighborhoods of the singularities by canceling the singularities with the Jacobian of a power map. Also the description of the distribution *inside* each bin will be improved for reasonable maps.

5.4 Piecewise Differentiable Maps



blah, blah, blah

Ansatz:

$$\Phi_{\{\phi\}} : [X_0, X_1] \rightarrow [Y_0, Y_1]$$

$$x \mapsto \Phi_{\{\phi\}}(x) = \sum_{i=1}^n \Theta(x_i - x) \Theta(x - x_{i-1}) \phi(x) \quad (29)$$


with $x_0 = X_0$, $x_n = X_1$ and $x_i > x_{i-1}$. In each interval

$$\phi_i : [x_{i-1}, x_i] \rightarrow [y_{i-1}, y_i]$$

$$x \mapsto y = \phi_i(x) \quad (30)$$

with $y_0 = Y_0$, $y_n = Y_1$

5.4.1 Powers

 integrable singularities

$$\begin{aligned} \psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i} : [x_{i-1}, x_i] &\rightarrow [y_{i-1}, y_i] \\ x &\mapsto \psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i}(x) = \frac{1}{b_i}(a_i(x - \xi_i))^{\alpha_i} + \eta_i \end{aligned} \quad (31)$$

We assume $\alpha_i \neq 0$, $a_i \neq 0$ and $b_i \neq 0$. Note that $\psi_{a,b}^{\alpha,\xi,\eta}$ encompasses both typical cases for integrable endpoint singularities $x \in [0, 1]$:

$$\psi_{1,1}^{\alpha,0,0}(x) = x^\alpha \quad (32a)$$

$$\psi_{-1,-1}^{\alpha,1,1}(x) = 1 - (1 - x)^\alpha \quad (32b)$$

The inverse maps are

$$\begin{aligned} (\psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i})^{-1} : [y_{i-1}, y_i] &\rightarrow [x_{i-1}, x_i] \\ y &\mapsto (\psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i})^{-1}(y) = \frac{1}{a_i}(b_i(y - \eta_i))^{1/\alpha_i} + \xi_i \end{aligned} \quad (33)$$

and incidentally:

$$(\psi_{a,b}^{\alpha,\xi,\eta})^{-1} = \psi_{b,a}^{1/\alpha,\eta,\xi} \quad (34)$$

The Jacobians are

$$\frac{dy}{dx}(x) = \frac{a\alpha}{b}(a(x - \xi))^{\alpha-1} \quad (35a)$$

$$\frac{dx}{dy}(y) = \frac{b}{a\alpha}(b(y - \eta))^{1/\alpha-1} \quad (35b)$$

and satisfy, of course,

$$\frac{dx}{dy}(y(x)) = \frac{1}{\frac{dy}{dx}(x)} \quad (36)$$

In order to get a strictly monotonous function, we require

$$\frac{a\alpha}{b} > 0 \quad (37)$$

Since we will see below that almost always in practical applications $\alpha > 0$, this means $\epsilon(a) = \epsilon(b)$.

From (25) and (35b), we see that this map is useful for handling weights²

$$w(y) \propto (y - \eta)^\beta \quad (38)$$

for $\beta > -1$, if we choose $\beta - (1/\alpha - 1) \geq 0$, i. e. $\alpha \gtrsim 1/(1 + \beta)$.

The five parameters $(\alpha, \xi, \eta, a, b)$ are partially redundant. Indeed, there is a one parameter semigroup of transformations

$$(\alpha, \xi, \eta, a, b) \rightarrow (\alpha, \xi, \eta, at, bt^\alpha), \quad (t > 0) \quad (39)$$

that leaves $\psi_{a,b}^{\alpha,\xi,\eta}$ invariant:

$$\psi_{a,b}^{\alpha,\xi,\eta} = \psi_{at,bt^\alpha}^{\alpha,\xi,\eta} \quad (40)$$

Assuming that multiplications are more efficient than sign transfers, the redundant representation is advantageous. Unless sign transfers are implemented directly in hardware, they involve a branch in the code and the assumption appears to be reasonable.

5.4.2 Identity

The identity map

$$\begin{aligned} \iota : [x_{i-1}, x_i] &\rightarrow [y_{i-1}, y_i] = [x_{i-1}, x_i] \\ x &\mapsto \iota(x) = x \end{aligned} \quad (41)$$

is a special case of the power map $\iota = \psi_{1,1}^{1,0,0}$, but, for efficiency, it is useful to provide a dedicated “implementation” anyway.

5.4.3 Resonances



- not really needed in the applications so far, because the variance remains integrable.
- no clear example for significantly reduced numbers of bins for the same quality with mapping.
- added for illustration.

²The limiting case $(y - \eta)^{-1}$ could be covered by maps $x \mapsto e^{a(x-\xi)}/b + \eta$, where the non-integrability of the density is reflected in the fact that the domain of the map is semi-infinite (i. e. $x \rightarrow -\epsilon(a) \cdot \infty$). In physical applications, the densities are usually integrable and we do not consider this case in the following.

$$\begin{aligned}\rho_{a_i, b_i}^{\xi_i, \eta_i} : [x_{i-1}, x_i] &\rightarrow [y_{i-1}, y_i] \\ x &\mapsto \rho_{a_i, b_i}^{\xi_i, \eta_i}(x) = a_i \tan \left(\frac{a_i}{b_i^2} (x - \xi_i) \right) + \eta_i\end{aligned}\quad (42)$$

Inverse

$$\begin{aligned}(\rho_{a_i, b_i}^{\xi_i, \eta_i})^{-1} : [y_{i-1}, y_i] &\rightarrow [x_{i-1}, x_i] \\ y &\mapsto (\rho_{a_i, b_i}^{\xi_i, \eta_i})^{-1}(y) = \frac{b_i^2}{a_i} \operatorname{atan} \left(\frac{y - \eta_i}{a_i} \right) + \xi_i\end{aligned}\quad (43)$$

is useful for mapping *known* peaks, since

$$\frac{d\phi^{-1}}{dy}(y) = \frac{dx}{dy}(y) = \frac{b^2}{(y - \eta)^2 + a^2} \quad (44)$$

5.4.4 Patching Up

Given a collection of intervals with associated maps, it remains to construct a combined map. Since *any* two intervals can be mapped onto each other by a map with constant Jacobian, we have a “gauge” freedom and must treat x_{i-1} and x_i as free parameters in

$$\psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i} : [x_{i-1}, x_i] \rightarrow [y_{i-1}, y_i] \quad (45)$$

i. e.

$$x_j = (\psi_{a_i, b_i}^{\alpha_i, \xi_i, \eta_i})^{-1}(y_j) = \frac{1}{a_i} (b_i(y_j - \eta_i))^{1/\alpha_i} + \xi_i \quad \text{for } j \in \{i-1, i\} \quad (46)$$

Since α and η denote the strength and the location of the singularity, respectively, they are the relevant input parameters and we must solve the constraints (46) for ξ_i , a_i and b_i . Indeed a family of solutions is

$$a_i = \frac{(b_i(y_i - \eta_i))^{1/\alpha_i} - (b_i(y_{i-1} - \eta_i))^{1/\alpha_i}}{x_i - x_{i-1}} \quad (47a)$$

$$\xi_i = \frac{x_{i-1}|y_i - \eta_i|^{1/\alpha_i} - x_i|y_{i-1} - \eta_i|^{1/\alpha_i}}{|y_i - \eta_i|^{1/\alpha_i} - |y_{i-1} - \eta_i|^{1/\alpha_i}} \quad (47b)$$

which is unique up to (39). The degeneracy (39) can finally be resolved by demanding $|b| = 1$ in (47a).

It remains to perform a ‘gauge fixing’ and choose the domains $[x_{i-1}, x_i]$. The minimal solution is $x_i = y_i$ for all i , which maps the boundaries between different mappings onto themselves and we need only to store either $\{x_0, x_1, \dots, x_n\}$ or $\{y_0, y_1, \dots, y_n\}$.

For the resonance map

$$x_j = (\rho_{a_i, b_i}^{\xi_i, \eta_i})^{-1}(y_j) = \frac{b_i^2}{a_i} \operatorname{atan} \left(\frac{y_j - \eta_i}{a_i} \right) + \xi_i \quad \text{for } j \in \{i-1, i\} \quad (48)$$

i. e.

$$b_i = \sqrt{a_i \frac{x_i - x_{i-1}}{\operatorname{atan} \left(\frac{y_i - \eta_i}{a_i} \right) - \operatorname{atan} \left(\frac{y_{i-1} - \eta_i}{a_i} \right)}} \quad (49a)$$


$$\xi_i = \frac{x_{i-1} \operatorname{atan} \left(\frac{y_i - \eta_i}{a_i} \right) - x_i \operatorname{atan} \left(\frac{y_{i-1} - \eta_i}{a_i} \right)}{x_i - x_{i-1}} \quad (49b)$$

as a function of the physical peak location η and width a .

6 Preparing Beam Descriptions with circe2_tool

 rationale

6.1 circe2_tool Files

 { and }

6.1.1 Per File Options

file: a double quote delimited string denoting the name of the output file that will be read by `cir2ld` (in the format described in table 2).

6.1.2 Per Design Options

design: a double quote delimited string denoting a name for the design. See the description of `cir2ld` on page 9 for conventions for these names.

roots: \sqrt{s} /GeV of the accelerator design.

bins: number of bins for the histograms in both directions. `bins/1` and `bins/2` apply only to x_1 and x_2 respectively. This number can be overwritten by channel options.

comment: a double quote delimited string denoting a one line comment that will be copied to the output file. This command can be repeated.

6.1.3 Per Channel Options

If an option can apply to either beam or both, it can be qualified by /1 or /2. For example, `bins` applies to both beams, while `bins/1` and `bins/2` apply only to x_1 and x_2 respectively.

`bins`: number of bins for the histograms. These overwrite the per-design option.

`pid`: particle identification: either a PDG code [11] (see page 3) or one of `gamma`, `photon`, `electron`, `positron`.

`pol`: polarization: one of $\{-1, 0, 1\}$, where 0 means unpolarized (see page 3).

`min`: minimum value of the coordinate(s). The default is 0.

`max`: maximum value of the coordinate(s). The default is 1.

`fix`

`free`

`map`: apply a map to a subinterval. Currently, three types of maps are supported:

`id { n [x_{\min}, x_{\max}] }`: apply an identity map in the interval $[x_{\min}, x_{\max}]$ subdivided into n bins. The non-trivial effect of this map is that the endpoints x_{\min} and x_{\max} are frozen.

`power { n [x_{\min}, x_{\max}] beta = β eta = η }`: apply a power map in the interval $[x_{\min}, x_{\max}]$ subdivided into n bins. $\alpha = 1/(1 + \beta)$, such that an integrable singularity at η with power β is mapped away. This is the most important map in practical applications and manual fine tuning is rewarded.

`resonance { n [x_{\min}, x_{\max}] center = η width = a }`: apply a resonance map in the interval $[x_{\min}, x_{\max}]$ subdivided into n bins. This map is hardly ever needed, since VEGAS/VAMP appears to be able to handle non-singular peaks very well.

`triangle`

`notriangle`

`lumi`: luminosity of the beam design, in units of

$$\text{fb}^{-1}v^{-1} = 10^{32}\text{cm}^{-2}\text{sec}^{-1} \quad (50)$$

where $v = 10^7 \text{ sec} \approx \text{year}/\pi$ is an “effective year” of running with about 30% up-time

`events`: a double quote delimited string denoting the name of the input file.

`ascii`: input file contains formatted ASCII numbers.

`binary`: input file is in raw binary format that can be accessed by fast memory mapped I/O. Such files are not portable and must not contain Fortran record markers.

`columns`: number of columns in a binary file.

`iterations`: maximum number of iterations of the VEGAS/VAMP refinement. It is not necessary to set this parameter, but e.g. `iterations = 0` is useful for illustrating the effect of adaption.

6.2 `circe2_tool` Demonstration

We can use the example of figure 1 (a simulated realistic $\gamma\gamma$ luminosity spectrum (helicities: (+, +)) for a 500 GeV photon collider at TESLA [7]) to demonstrate the effects of different options. In order to amplify the effects, only 20 bins are used in each direction, but figure 8 will show that adequate results are achievable in this case too.

In figure 3, 20 equidistant bins in each direction

`bins = 20 iterations = 0`

produce an acceptable description of the high energy peak but are clearly inadequate for $z < 0.2$. In the blown up region, neither 20 equidistant bins nor 50 equidistant bin produce more than a handful of events and remain almost invisible. The bad low energy behaviour can be understood from the convolution of the obviously coarse approximations in left figure of figure 4. Letting the grid adapt

`bins = 20`

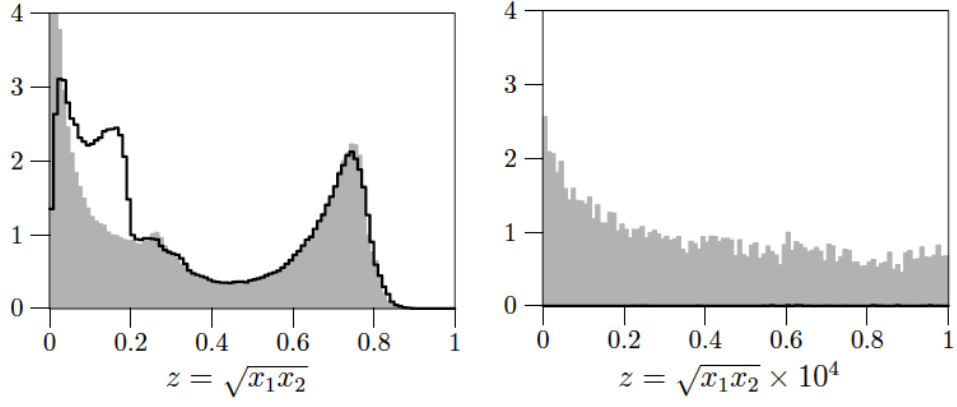


Figure 3: Using 20 equidistant bins in each direction. In the region blown up on the right neither 20 equidistant bins nor 50 equidistant bin produce enough events to be visible. In this and all following plots, the simulated input data is shown as a filled histogram, and the Circe2 parametrization is shown as a solid line.

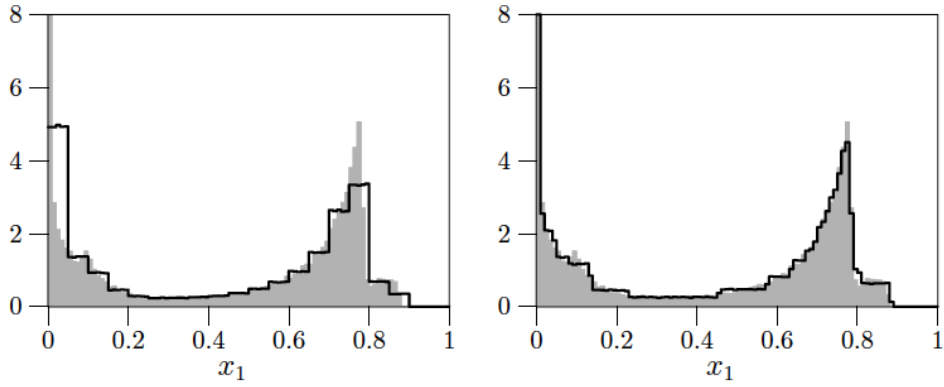


Figure 4: Using 20 bins, both equidistant (left) and adapted (right).

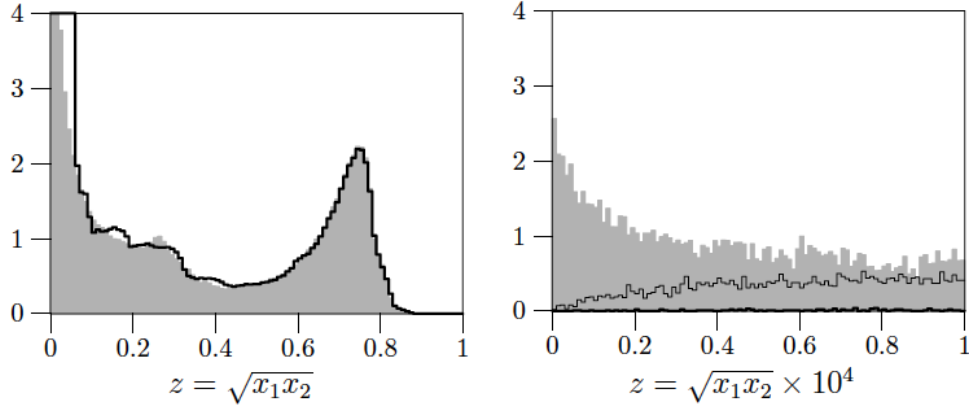


Figure 5: 20 adapted bins. In the blow-up, the 50 bin result is shown for illustration as a thin line, while the 20 bin result remains almost invisible.

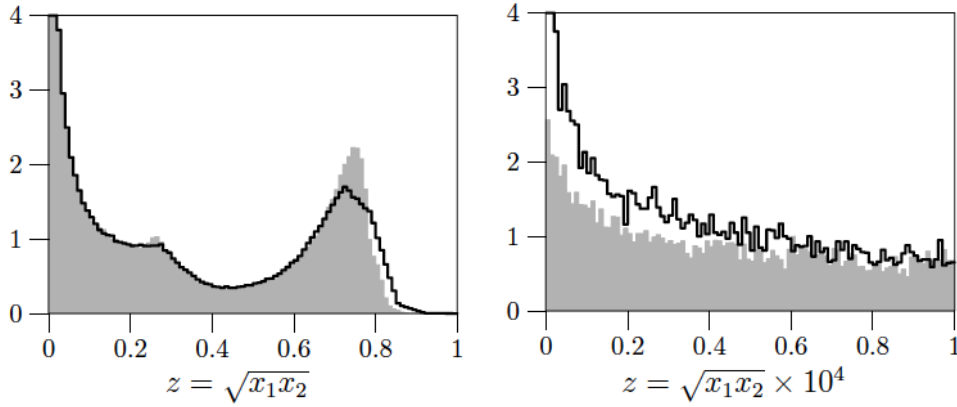


Figure 6: Using 20 equidistant bins in each direction with a power map appropriate for $x^{-0.67}$.

produces a much better approximation in the right figure of figure 4. And indeed, the convolution in figure 5 is significantly improved for $x \lesssim 0.2$, but remains completely inadequate in the very low energy region, blown up on the right hand side.

A better description of the low energy tail requires a power map and figure 6 shows that equidistant bins

```
map = power { 20 [0,1] beta = -0.67 eta = 0 } iterations = 0
```

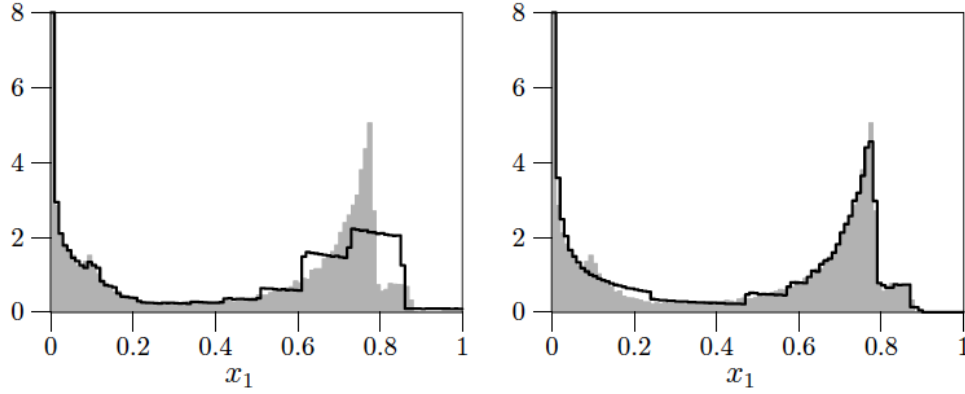


Figure 7: Using 20 bins with a power map appropriate for $x^{-0.67}$, equidistant (left) and adapted (right).

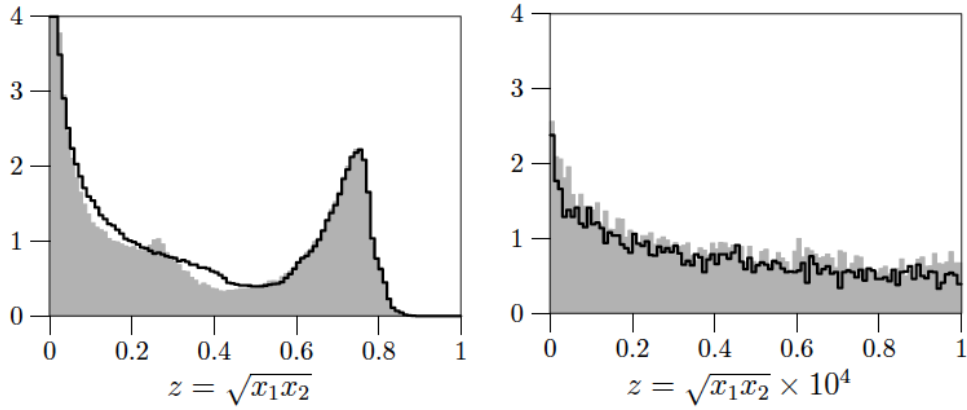


Figure 8: Using 20 adapted bins in each direction with a power map appropriate for $x^{-0.67}$.

already produce a much improved description of the low energy region, including the blow-up on the right hand side. However, the description of the peak has gotten much worse, which is explained by the coarsening of the bins in the high energy region, as shown in figure 7. The best result is obtained by combining a power map with adaption

```
map = power { 20 [0,1] beta = -0.67 eta = 0 }
```

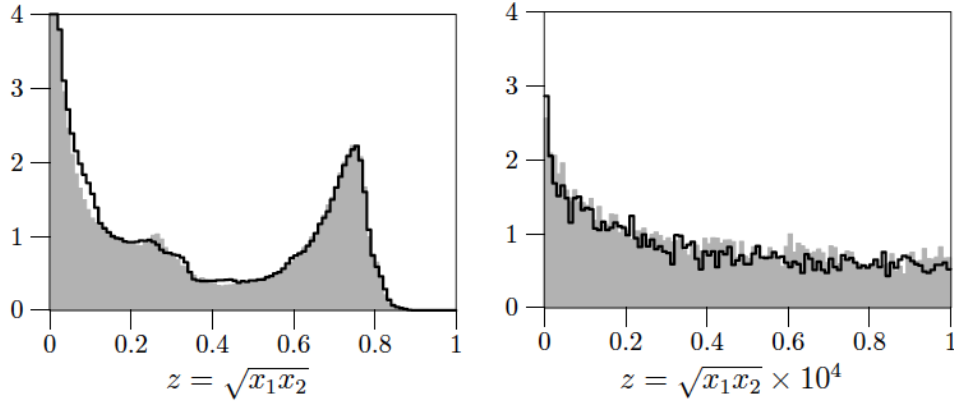


Figure 9: Using 4 + 16 adapted bins in each direction with a power map appropriate for $x^{-0.67}$ in the 4 bins below $x < 0.05$.

with the results depicted in figure 8. Balancing the number of bins used for a neighborhood of the integrable singularity at $x_i \rightarrow 0$ and the remainder can be improved by allocating a fixed number of bins for each

```
map = power { 4 [0,0.05] beta = -0.67 eta = 0 }
map = id { 16 [0.05,1] }
```

as shown in figure 9. If the data were not stochastic, this manual allocation would not be necessary, because the neighborhood of the singularity would not contribute to the variance and consequently use few bins. However, the stochastic variance cannot be suppressed and will pull in more bins than useful. If the power of the map were overcompensating the power of the singularity, instead of being tuned to it, the limit $x_i \rightarrow 0$ would be suppressed automatically. But in this case, the low-energy tail could not be described accurately.

The description with 20 bins in figure 9 is not as precise as the 50 bins

```
map = power { 10 [0,0.05] beta = -0.67 eta = 0 }
map = id { 40 [0.05,1] }
```

in figure 1, but can suffice for many studies and requires less than one sixth of the storage space.

6.3 More circe2_tool Examples

Here is an example that can be used to demonstrate the beneficial effects of powermaps. The simulated events in `teslagg-500.gg++.events` are

processed once with map and once without a map. Both times 50 bins are used in each direction.

```
{ file = "test_mappings.circe"
  { design = "TESLA" roots = 500
    { pid/1 = 22 pid/2 = 11 pol/1 = 1 pol/2 = 1
      events = "teslagg_500.gg.++.events" binary lumi = 110.719
      bins/1 = 50
      map/2 = id { 49 [0,0.9999999999] }
      map/2 = id { 1 [0.9999999999,1] } } }
  { design = "TESLA (mapped)" roots = 500
    { pid/1 = 22 pid/2 = 11 pol/1 = 1 pol/2 = 1
      events = "teslagg_500.gg.++.events" binary lumi = 110.719
      map/1 = power { 50 [0,1] beta = -0.67 eta = 0 }
      map/2 = power { 49 [0,0.9999999999] beta = -0.6 eta = 1 }
      map/2 = id { 1 [0.9999999999,1] } } } }
```

In a second step, the distributions generated from both designs in `test_mappings.circe` can be compared with the original distribution.


7 On the Implementation of `circe2_tool`

7.1 Divisions

 VEGAS/VAMP, basically ...

7.2 Differentiable Maps

7.3 Polydivisions

 patched divisions ...

7.4 Grids

8 The Next Generation

Future generations can try to implement the following features:

<i>! any comment</i>	optional, repeatable
CIRCE2 FORMAT#1	mandatory start line
design, roots	
'name' \sqrt{s}	mandatory quotes!
#channels, pol.support	
n_c 'name'	mandatory quotes!
pid1, pol1, pid2, pol2, lumi] repeat n_c times
$p_1 h_1 p_2 h_2 \int \mathcal{L}$	
#bins1, #bins2, triangle?	
$n_1 n_2 t$	
x1, map1, alpha1, xi1, eta1, a1, b1	
$x_{1,0}$	
$x_{1,1} m_{1,1} \alpha_{1,1} \xi_{1,1} \eta_{1,1} a_{1,1} b_{1,1}$	
...	
$x_{1,n_1} m_{1,n_1} \alpha_{1,n_1} \xi_{1,n_1} \eta_{1,n_1} a_{1,n_1} b_{1,n_1}$	
x2, map2, alpha2, xi2, eta2, a2, b2	
$x_{2,0}$	
$x_{2,1} m_{2,1} \alpha_{2,1} \xi_{2,1} \eta_{2,1} a_{2,1} b_{2,1}$	
...	
$x_{2,n_2} m_{2,n_2} \alpha_{2,n_2} \xi_{2,n_2} \eta_{2,n_2} a_{2,n_2} b_{2,n_2}$	
weights	
$w_1 [w_1 \chi_1^{0,1} w_1 \chi_1^{0,2} \dots w_1 \chi_1^{3,3}]$	optional $w \cdot \chi$
$w_2 [w_1 \chi_2^{0,1} w_1 \chi_2^{0,2} \dots w_1 \chi_2^{3,3}]$	
...	
$w_{n_1 n_2} [w_1 \chi_{n_1 n_2}^{0,1} w_1 \chi_{n_1 n_2}^{0,2} \dots w_1 \chi_{n_1 n_2}^{3,3}]$] end repeat
ECRIC2	
	mandatory end line

Table 2: File format. The variable input lines (except comments) are designed to be readable by FORTRAN90 ‘list-directed’ input. The files are generated from simulation data with the program `circe2_tool` and are read transparently by the procedure `cir2ld`. The format is documented here only for completeness.


```

module type Division =
  sig
    type t
    val copy : t -> t
    val record : t -> float -> float -> unit
    val rebin : ?power:float -> t -> t
    val find : t -> float -> int
    val bins : t -> float array
    val to_channel : out_channel -> t -> unit
  end

```

Figure 10: O’Caml signature for divisions. `Division.t` is the abstract data type for division of a real interval. Note that `Division` does *not* contain a function `create : ... -> t` for constructing maps. This is provided by concrete implementations (see figures 11 and 14), that can be projected on `Diffmap`

```

module type Mono_Division =
  sig
    include Division
    val create : int -> float -> float -> t
  end

```

Figure 11: O’Caml signature for simple divisions of an interval. The `create` function returns an equidistant starting division.

8.1 Variable # of Bins

One can monitor the total variance in each interval of the polydivisions and move bins from smooth intervals to wildly varying intervals, keeping the total number of bins constant.

8.2 Adapting Maps Per-Cell

If there is enough statistics, one can adapt the mapping class and parameters per bin.



There’s a nice duality between adapting bins for a constant mapping on one side and adapting mappings for constant bins. Can one merge the two approaches.

```

module type Diffmap =
  sig
    type t
    type domain
    val x_min : t -> domain
    val x_max : t -> domain
    type codomain
    val y_min : t -> codomain
    val y_max : t -> codomain
    val phi : t -> domain -> codomain
    val ihp : t -> codomain -> domain
    val jac : t -> domain -> float
    val caj : t -> codomain -> float
  end

module type Real_Diffmap =
  T with type domain = float and type codomain = float

```

Figure 12: O’Caml signature for differentiable maps. `Diffmap.t` is the abstract data type for differentiable maps. Note that `Diffmap` does *not* contain a functions like `create : ... -> t` for constructing maps. These are provided by concrete implementations, that can be projected onto `Diffmap`.

```

module type Real_Diffmaps =
  sig
    include Real_Diffmap
    val id : float -> float -> t
  end

```

Figure 13: Collections of real differentiable maps, including at least the identity. The function `id` returns an identity map from a real interval onto itself.

8.3 Non-Factorized Polygrids

One could think of a non-factorized distribution of mappings.

```

module type Poly_Division =
  sig
    include Division
    module M : Real_Diffmaps
    val create :
      (int * M.t) list -> int -> float -> float -> t
  end

module Make_Poly_Division (M : Real_Diffmaps) :
  Poly_Division with module Diffmaps = M

```

Figure 14: O’Caml signature for divisions of an interval, with piecewise differentiable mappings, as specified by the first argument of `create`. The functor `Make_Poly_Division` ...

```

module type Grid =
  sig
    module D : Division
    type t
    val create : D.t -> D.t -> t
    val copy : t -> t
    val record : t -> float -> float -> float -> unit
    val rebin : ?power:float -> t -> t
    val variance : t -> float
    val to_channel : out_channel -> t -> unit
  end

module Make_Grid (D : Division) : Grid with module D = D

```

Figure 15: O’Caml signature for grids. The functor `Make_Grid` can be applied to *any* module of type `Division`, in particular both `Mono_Division` and `Poly_Division`.

9 Conclusions

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10 Implementation of circe2

```

45a  <implicit none 45a>≡
      implicit none

45b  <circe2.f90 45b>≡
      ! circe2.f90 -- beam spectra for linear colliders and photon colliders
      <Copyleft notice 45d>
      <Separator 45c>
      module circe2
        use kinds

        <implicit none 45a>
        private

        <Public procedures 48c>

        <parameter declarations 51a>

        <Declaration: circe2 parameters 48d>

        type(circe2_params_t), public, save :: c2p

        contains

        <Procedures 55b>
      end module circe2

45c  <Separator 45c>≡
      !!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!!

45d  <Copyleft notice 45d>≡
      ! $Id: circe2.nw,v 1.56 2002/10/14 10:12:06 ohl Exp $
      ! Copyright (C) 2001-2011 by
      !   Wolfgang Kilian <kilian@physik.uni-siegen.de>
      !   Thorsten Ohl <ohl@physik.uni-wuerzburg.de>
      !   Juergen Reuter <juergen.reuter@desy.de>
      !   Christian Speckner <christian.speckner@physik.uni-freiburg.de>
      !
      ! Circe2 is free software; you can redistribute it and/or modify it

```

```

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! the Free Software Foundation; either version 2, or (at your option)
! any later version.
!
! Circe2 is distributed in the hope that it will be useful, but
! WITHOUT ANY WARRANTY; without even the implied warranty of
! MERCHANTABILITY or FITNESS FOR A PARTICULAR PURPOSE. See the
! GNU General Public License for more details.
!
! You should have received a copy of the GNU General Public License
! along with this program; if not, write to the Free Software
! Foundation, Inc., 675 Mass Ave, Cambridge, MA 02139, USA.

```

```

46a  <circe2_c.c 46a>≡
      /* circe2_c.c -- beam spectra for linear colliders and photon colliders */
      <Copyleft notice (C) 47a>
      <Separator2 (C) 46b>
      #include <stdio.h>
      #include <stdlib.h>
      #include <string.h>
      #include <errno.h>
      #include <math.h>
      #undef min
      #define min(a,b) ((a) < (b) ? (a) : (b))
      #undef max
      #define max(a,b) ((a) > (b) ? (a) : (b))
      <Separator2 (C) 46b>
      <Macros (C) 62b>
      <Separator2 (C) 46b>
      <Well known constants (C) 56d>
      <Separator2 (C) 46b>
      <Data type declarations (C) 48e>
      <Separator2 (C) 46b>
      <Private Procedures (C) 47b>
      <Separator2 (C) 46b>
      <Public Procedures (C) 55c>

```

```

46b  <Separator2 (C) 46b>≡

```

```

      <Separator (C) 46c>

```

```

46c  <Separator (C) 46c>≡

```

```

      /*****

```

47a *<Copyleft notice (C) 47a>*≡

```
/* $Id: circe2.nw,v 1.56 2002/10/14 10:12:06 ohl Exp $
   Copyright (C) 2002-2011 by
       Wolfgang Kilian <kilian@physik.uni-siegen.de>
       Thorsten Ohl <ohl@physik.uni-wuerzburg.de>
       Juergen Reuter <juergen.reuter@desy.de>
       Christian Speckner <christian.speckner@physik.uni-freiburg.de>
```

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You should have received a copy of the GNU General Public License along with this program; if not, write to the Free Software Foundation, Inc., 675 Mass Ave, Cambridge, MA 02139, USA. */

Can't live without it:

47b *<Private Procedures (C) 47b>*≡

```
void *
xmalloc (size_t size)
{
    void *ptr = malloc (size);
    if (ptr == NULL) {
        fprintf (stderr, "can't get %d bytes ... exiting!\n", size);
        exit (-1);
    }
    return ptr;
}
```

47c *<circe2_cpp.cc 47c>*≡

```
// circe2_cpp.cc -- beam spectra for linear colliders and photon colliders
<Copyleft notice (C++) 48b>
<Separator2 (C++) 47d>
<Data type declarations (C++) (never defined)>
<Procedures (C++) (never defined)>
```

47d *<Separator2 (C++) 47d>*≡

```
//
<Separator (C++) 48a>
```

```

//
48a  <Separator (C++) 48a>≡
// -----
48b  <Copyleft notice (C++) 48b>≡
// $Id: circe2.nw,v 1.56 2002/10/14 10:12:06 ohl Exp $
// Copyright (C) 2002-2011 by
//      Wolfgang Kilian <kilian@physik.uni-siegen.de>
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//
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```

11 Data

The `circe2_params_t` type (old `/circ2cm/` common block which had to be arranged such that the constant `parameters` come first and the variables in order of decreasing alignment constraints):

```

48c  <Public procedures 48c>≡
      public :: circe2_params_t
48d  <Declaration: circe2 parameters 48d>≡
      type :: circe2_params_t
         <8-byte aligned part of circe2 parameters 50a>
         <4-byte aligned part of circe2 parameters 50b>
      end type circe2_params_t

48e  <Data type declarations (C) 48e>≡

```



```

typedef struct
{
    int n;
    <circe2_division components 52e>
} circe2_division;

49a <Private Procedures (C) 47b>+≡
static circe2_division *
circe2_new_division (int nbins)
{
    circe2_division *d;
    d = xmalloc (sizeof (circe2_division));
    d->n = nbins;
    <Allocate circe2_division components *d 52f>
    return d;
}

49b <Data type declarations (C) 48e>+≡
typedef struct
{
    circe2_division *d1, *d2;
    <circe2_channel components 51b>
} circe2_channel;

49c <Private Procedures (C) 47b>+≡
static circe2_channel *
circe2_new_channel (int nbins1, int nbins2)
{
    circe2_channel *p;
    int i;
    p = xmalloc (sizeof (circe2_channel));
    p->d1 = circe2_new_division (nbins1);
    p->d2 = circe2_new_division (nbins2);
    <Allocate circe2_channel components *p 51c>
    return p;
}

49d <Data type declarations (C) 48e>+≡
typedef struct
{
    int n;
    circe2_channel **ch;
    <circe2_channels components 56b>
} circe2_channels;

49e <Private Procedures (C) 47b>+≡

```

x_3^{\max}	$i_2 = n_2$	$n_1(n_2 - 1) + 1$	$n_1(n_2 - 1) + 2$	\dots	$n_1 n_2 - 1$	$n_1 n_2$
\dots		\dots	\dots	\dots	\dots	$n_1(n_2 - 1)$
3		$2n_1 + 1$	\dots	\dots	\dots	\dots
2		$n_1 + 1$	$n_1 + 2$	\dots	\dots	$2n_1$
1		1	2	3	\dots	n_1
x_2^{\min}	x_1^{\min}	$i_1 = 1$	2	3	\dots	n_1
						x_1^{\max}

Figure 16: Enumerating the bins linearly, starting from 1 (Fortran style). Probability distribution functions will have a sentinel at 0 that's always 0.

```

static circe2_channels *
circe2_new_channels (int nchannels, int nbins1, int nbins2)
{
    int i;
    circe2_channels *p;
    p = xmalloc (sizeof (circe2_channels));
    p->n = nchannels;
    p->ch = xmalloc (p->n * sizeof (circe2_channel *));
    for (i = 0; i < p->n; i++)
        p->ch[i] = circe2_new_channel (nbins1, nbins2);
    return p;
}

```

We store the probability distribution function as a one-dimensional array `wgt`³, since this simplifies the binary search used for inverting the distribution. `[wgt(0,ic)]` is always 0 and serves as a convenient sentinel for the binary search. It is *not* written in the file, which contains the normalized weight of the bins.

50a *<8-byte aligned part of circe2 parameters 50a>* \equiv
`real(kind=double), dimension(0:NBMAX*NBMAX,NCMAX) :: wgt`

The actual number of bins in each direction is

50b *<4-byte aligned part of circe2 parameters 50b>* \equiv
`integer, dimension(NCMAX) :: nb1, nb2`

³The second “dimension” is just an index for the channel.

Of course, we can't make *any* exceptions to the rule $\text{nb} \leq \text{NBMAX}$ (similarly for $\text{nc} \leq \text{NCMAX}$ below). $\text{NCMAX} = (3 \cdot 2)^2$ for three flavors ($\{e^+, e^-, \gamma\}$) and two helicity states.

51a $\langle \text{parameter declarations 51a} \rangle \equiv$
`integer, parameter :: NBMAX = 100, NCMAX = 36`

51b $\langle \text{circe2_channel components 51b} \rangle \equiv$
`double *weight;`

51c $\langle \text{Allocate circe2_channel components *p 51c} \rangle \equiv$
`p->weight = xmalloc ((p->d1->n * p->d2->n + 1) * sizeof(double));`

Using figure 16, calculating the index of a bin from the two-dimensional coordinates is straightforward, of course:

51d $\langle i \leftarrow (i_1, i_2) \text{ 51d} \rangle \equiv$
`i = i1 + (i2 - 1) * c2p%nb1(ic)`

51e $\langle i \leftarrow (i_1, i_2) (C) \text{ 51e} \rangle \equiv$
`i = i1 + (i2 - 1) * ch->d1->n`

The inverse

$$i_1 = 1 + ((i - 1) \bmod n_1) \quad (51a)$$

$$i_2 = 1 + \lfloor (i - 1) / n_1 \rfloor \quad (51b)$$

can also be written

$$i_2 = 1 + \lfloor (i - 1) / n_1 \rfloor \quad (52a)$$

$$i_1 = i - (i_2 - 1)n_1 \quad (52b)$$

51f $\langle (i_1, i_2) \leftarrow i \text{ 51f} \rangle \equiv$
`i2 = 1 + (i - 1) / c2p%nb1(ic)`
`i1 = i - (i2 - 1) * c2p%nb1(ic)`

51g $\langle \text{Private Procedures (C) 47b} \rangle + \equiv$
`static inline void`
`split_index (circe2_channel *ch, int *i1, int *i2, int i) {`
`*i2 = 1 + (i - 1) / ch->d1->n;`
`*i1 = i - (*i2 - 1) * ch->d1->n;`
`}`

The density normalized to the bin size

$$v = \frac{w}{\Delta x_1 \Delta x_2}$$

such that

$$\int dx_1 dx_2 v = \sum w = 1$$

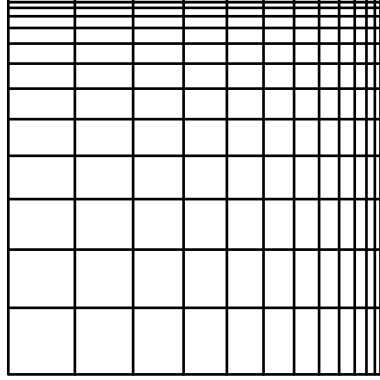


Figure 17: Almost factorizable distributions, like e^+e^- .

For mapped distributions, on the level of bins, we can either use the area of the domain and apply a jacobian or the area of the codomain directly

$$\frac{dx}{dy} \cdot \frac{1}{\Delta x} \approx \frac{1}{\Delta y} \quad (53)$$

We elect to use the former, because this reflects the distribution of the events generated by `cir2gn` *inside* the bins as well. This quantity is more conveniently stored as a true two-dimensional array:

```

52a <8-byte aligned part of circe2 parameters 50a>+≡
    real(kind=double), dimension(NBMAX,NBMAX,NCMAX) :: val

52b <circe2_channel components 51b>+≡
    double **value;

52c <Allocate circe2_channel components *p 51c>+≡
    p->value = xmalloc (p->d1->n * sizeof(double *));
    for (i = 0; i < p->d1->n; i++)
        p->value[i] = xmalloc (p->d2->n * sizeof(double));

52d <8-byte aligned part of circe2 parameters 50a>+≡
    real(kind=double), dimension(0:NBMAX,NCMAX) :: xb1, xb2

52e <circe2_division components 52e>≡
    double *x;

52f <Allocate circe2_division components *d 52f>≡
    d->x = xmalloc ((d->n + 1) * sizeof(double));

```

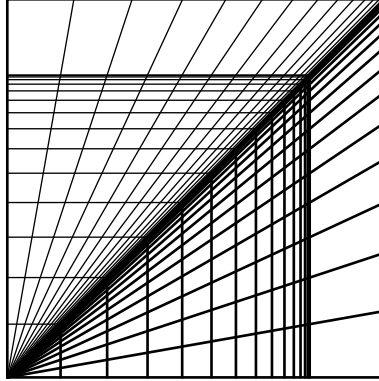


Figure 18: Symmetrical, strongly correlated distributions, e. g. with a ridge on the diagonal, like $\gamma\gamma$ at a $\gamma\gamma$ -collider.

53a $\langle 4\text{-byte aligned part of circe2 parameters } 50b \rangle + \equiv$
`logical, dimension(NCMAX) :: triang`

53b $\langle \text{circe2_channel components } 51b \rangle + \equiv$
`int triangle;`

11.1 Channels

The actual number of channels $\gamma\gamma$, $e^- \gamma$, $e^- e^+$, etc.

53c $\langle 4\text{-byte aligned part of circe2 parameters } 50b \rangle + \equiv$
`integer :: nc`

The particles that are described by this channel and their polarizations:

53d $\langle 4\text{-byte aligned part of circe2 parameters } 50b \rangle + \equiv$
`integer, dimension(NCMAX) :: pid1, pid2`
`integer, dimension(NCMAX) :: pol1, pol2`

53e $\langle \text{circe2_division components } 52e \rangle + \equiv$
`int pid;`
`int pol;`

The integrated luminosity of the channel

53f $\langle 8\text{-byte aligned part of circe2 parameters } 50a \rangle + \equiv$
`real(kind=double), dimension(NCMAX) :: lumi`

53g $\langle \text{circe2_channel components } 51b \rangle + \equiv$
`double lumi;`

The integrated luminosity of the channel

```
54a <8-byte aligned part of circe2 parameters 50a>+≡
    real(kind=double), dimension(0:NCMAX) :: cwgt

54b <circe2_channel components 51b>+≡
    double channel_weight;
```

11.2 Maps

```
54c <4-byte aligned part of circe2 parameters 50b>+≡
    integer, dimension(NBMAX,NCMAX) :: map1, map2

54d <circe2_division components 52e>+≡
    int *map;

54e <Allocate circe2_division components *d 52f>+≡
    d->map = xmalloc (d->n * sizeof(int));

54f <8-byte aligned part of circe2 parameters 50a>+≡
    real(kind=double), dimension(0:NBMAX,NCMAX) :: yb1, yb2

54g <circe2_division components 52e>+≡
    double *y;

54h <Allocate circe2_division components *d 52f>+≡
    d->y = xmalloc ((d->n + 1) * sizeof(double));

54i <8-byte aligned part of circe2 parameters 50a>+≡
    real(kind=double), dimension(NBMAX,NCMAX) :: alpha1, alpha2
    real(kind=double), dimension(NBMAX,NCMAX) :: xi1, xi2
    real(kind=double), dimension(NBMAX,NCMAX) :: eta1, eta2
    real(kind=double), dimension(NBMAX,NCMAX) :: a1, a2
    real(kind=double), dimension(NBMAX,NCMAX) :: b1, b2

54j <circe2_division components 52e>+≡
    double *alpha;
    double *xi, *eta;
    double *a, *b;

54k <Allocate circe2_division components *d 52f>+≡
    d->alpha = xmalloc (d->n * sizeof(double));
    d->xi = xmalloc (d->n * sizeof(double));
    d->eta = xmalloc (d->n * sizeof(double));
    d->a = xmalloc (d->n * sizeof(double));
    d->b = xmalloc (d->n * sizeof(double));
```

12 Event Generation

Generate a two-dimensional distribution for (x_1, x_2) according to the histogram for channel ic .

55a \langle Public procedures 48c $\rangle + \equiv$
 public :: cir2gn

55b \langle Procedures 55b $\rangle \equiv$
 subroutine cir2gn (p1, h1, p2, h2, y1, y2, rng)
 integer :: p1, h1, p2, h2
 real(kind=double) :: y1, y2
 external rng
 integer :: i, ic, i1, i2, ibot, itop
 real(kind=double) :: x1, x2
 real(kind=double) :: u, tmp
 \langle Find ic for p1, h1, p2 and h2 56e \rangle
 \langle Complain and return iff $ic \leq 0$ 57a \rangle
 call rng (u)
 \langle Do a binary search for $wgt(i-1) \leq u < wgt(i)$ 58a \rangle
 \langle (i1, i2) \leftarrow i 51f \rangle
 \langle x1 \in [xb1(i1-1), xb1(i1)] 58c \rangle
 \langle x2 \in [xb2(i2-1), xb2(i2)] 59a \rangle
 \langle y1 \leftarrow x1 59d \rangle
 \langle y2 \leftarrow x2 59e \rangle
 \langle Inverse triangle map 60b \rangle
 end subroutine cir2gn

55c \langle Public Procedures (C) 55c $\rangle \equiv$
 void
 circe2_generate (circe2_channels *channels,
 int p1, int h1, int p2, int h2,
 double *y1, double *y2,
 void (*rng)(double *))
 {
 circe2_channel *ch = NULL;
 int i, i1, i2;
 double u, x1, x2;
 ch = circe2_find_channel (channels, p1, h1, p2, h2);
 \langle Complain and return iff $ch = NULL$ (C) 57b \rangle
 rng (&u);
 i = binary_search (ch->weight, 0, ch->d1->n * ch->d2->n, u);
 split_index (ch, &i1, &i2, i);
 \langle x1 \in [ch->d1->x[i1-1], ch->d1->x[i1]] (C) 59b \rangle
 }

```

    <x2 ∈ [ch- > d2- > x[i2 - 1] , ch- > d2- > x[i2] ] (C) 59c>
    <y1 ← x1 (C) 59f>
    <y2 ← x2 (C) 60a>
    <Inverse triangle map (C) 60c>
  }

56a <4-byte aligned part of circe2 parameters 50b>+≡
      integer :: polspt

56b <circe2_channels components 56b>≡
      int polarization_support;

56c <parameter declarations 51a>+≡
      integer, parameter :: POLAVG = 1, POLHEL = 2, POLGEN = 3

56d <Well known constants (C) 56d>≡
      #define POLAVG 1
      #define POLHEL 2
      #define POLGEN 3

```

A linear search for a matching channel should suffice, because the number of channels `nc` will always be a small number. The most popular channels should be first in the list, anyway.

```

56e <Find ic for p1, h1, p2 and h2 56e>≡
      ic = 0
      if (((c2p%polspt .eq. POLAVG) .or. (c2p%polspt .eq. POLGEN)) &
          .and. ((h1 .ne. 0) .or. (h2 .ne. 0))) then
          write (*, '(2A)') 'circe2: current beam description ', &
              'supports only polarization averages'
      else if ((c2p%polspt .eq. POLHEL) &
          .and. ((h1 .eq. 0) .or. (h2 .eq. 0))) then
          write (*, '(2A)') 'circe2: polarization averages ', &
              'not supported by current beam description'
      else
          do i = 1, c2p%nc
              if ( (p1 .eq. c2p%pid1(i)) .and. (h1 .eq. c2p%pol1(i)) &
                  .and. (p2 .eq. c2p%pid2(i)) .and. (h2 .eq. c2p%pol2(i))) then
                  ic = i
              end if
          end do
      end if

56f <Private Procedures (C) 47b>+≡
      static circe2_channel *
      circe2_find_channel (circe2_channels *channels,
                          int p1, int h1, int p2, int h2)
      {

```



```

int i;
if (((channels->polarization_support == POLAVG)
    || (channels->polarization_support == POLGEN))
    && ((h1 != 0) || (h2 != 0))) {
    fprintf (stderr,
            "circe2: current beam description "
            "supports only polarization averages\n");
    return NULL;
}
if ((channels->polarization_support == POLHEL)
    && ((h1 == 0) || (h2 == 0))) {
    fprintf (stderr,
            "circe2: polarization averages not "
            "supported by current beam description\n");
    return NULL;
}
for (i = 0; i < channels->n; i++) {
    circe2_channel *ch = channels->ch[i];
    if ((p1 == ch->d1->pid) && (h1 == ch->d1->pol)
        && (p2 == ch->d2->pid) && (h2 == ch->d2->pol))
        return ch;
}
return NULL;
}

```

$-3.4 \cdot 10^{38}$ is a very large negative number that can be represented in typical 4-byte floating point numbers:

```

57a  <Complain and return iff ic ≤ 0 57a>≡
      if (ic .le. 0) then
        write (*, '(A,2I4,A,2I3)') &
          'circe2: no channel for particles', p1, p2, &
          ' and polarizations', h1, h2
        y1 = -3.4E+38
        y2 = -3.4E+38
        return
      end if

57b  <Complain and return iff ch = NULL (C) 57b>≡
      if (ch == NULL) {
        fprintf (stderr,
            "circe2: no channel for particles (%d, %d) "
            "and polarizations (%d, %d)\n", p1, p2, h1, h2);
        *y1 = -3.4e+38;
        *y2 = -3.4e+38;
      }

```

```

    return;
}

```

The number of bins is typically *much* larger and we must use a binary search to get a reasonable performance.

58a $\langle \text{Do a binary search for } \text{wgt}(i-1) \leq u < \text{wgt}(i) \text{ 58a} \rangle \equiv$

```

    ibot = 0
    itop = c2p%nb1(ic) * c2p%nb2(ic)
    do
        if (itop .le. (ibot + 1)) then
            i = ibot + 1
            exit
        else
            i = (ibot + itop) / 2
            if (u .lt. c2p%wgt(i,ic)) then
                itop = i
            else
                ibot = i
            end if
        end if
    end do

```

58b $\langle \text{Private Procedures (C) 47b} \rangle + \equiv$

```

static int
binary_search (double *x, int bot, int top, double u)
{
    int low = bot;
    int high = top;
    while (1) {
        if (high <= (low + 1)) {
            return (low + 1);
            break;
        } else {
            int i = (low + high) / 2;
            if (u < x[i])
                high = i;
            else
                low = i;
        }
    }
}

```

58c $\langle x_1 \in [\text{xb1}(i_1-1), \text{xb1}(i_1)] \text{ 58c} \rangle \equiv$

```

    call rng (u)
    x1 = c2p%xb1(i1,ic)*u + c2p%xb1(i1-1,ic)*(1-u)

```

```

59a   $\langle x_2 \in [x_{b2}(i_2 - 1), x_{b2}(i_2)]$  59a)  $\equiv$ 
      call rng (u)
      x2 = c2p%xb2(i2,ic)*u + c2p%xb2(i2-1,ic)*(1-u)

59b   $\langle x_1 \in [ch \rightarrow d1 \rightarrow x[i_1 - 1], ch \rightarrow d1 \rightarrow x[i_1]]$  (C) 59b)  $\equiv$ 
      rng (&u);
      x1 = ch->d1->x[i1]*u + ch->d1->x[i1-1]*(1-u);

59c   $\langle x_2 \in [ch \rightarrow d2 \rightarrow x[i_2 - 1], ch \rightarrow d2 \rightarrow x[i_2]]$  (C) 59c)  $\equiv$ 
      rng (&u);
      x2 = ch->d2->x[i2]*u + ch->d2->x[i2-1]*(1-u);

59d   $\langle y_1 \leftarrow x_1$  59d)  $\equiv$ 
      if (c2p%map1(i1,ic) .eq. 0) then
        y1 = x1
      else if (c2p%map1(i1,ic) .eq. 1) then
        y1 = (c2p%a1(i1,ic)*(x1-c2p%xi1(i1,ic)))*c2p%alpha1(i1,ic) / c2p%b1(i1,ic) &
          + c2p%eta1(i1,ic)
      else if (c2p%map1(i1,ic) .eq. 2) then
        y1 = c2p%a1(i1,ic) * tan(c2p%a1(i1,ic)*(x1-c2p%xi1(i1,ic))/c2p%b1(i1,ic)**2) &
          + c2p%eta1(i1,ic)
      else
        write (*, '(A,I3)') &
          'circe2: internal error: invalid map: ', c2p%map1(i1,ic)
      end if

59e   $\langle y_2 \leftarrow x_2$  59e)  $\equiv$ 
      if (c2p%map2(i2,ic) .eq. 0) then
        y2 = x2
      else if (c2p%map2(i2,ic) .eq. 1) then
        y2 = (c2p%a2(i2,ic)*(x2-c2p%xi2(i2,ic)))*c2p%alpha2(i2,ic) / c2p%b2(i2,ic) &
          + c2p%eta2(i2,ic)
      else if (c2p%map2(i2,ic) .eq. 2) then
        y2 = c2p%a2(i2,ic) * tan(c2p%a2(i2,ic)*(x2-c2p%xi2(i2,ic))/c2p%b2(i2,ic)**2) &
          + c2p%eta2(i2,ic)
      else
        write (*, '(A,I3)') &
          'circe2: internal error: invalid map: ', c2p%map2(i2,ic)
      end if

59f   $\langle y_1 \leftarrow x_1$  (C) 59f)  $\equiv$ 
      switch (ch->d1->map[i1]) {
      case 0:
        *y1 = x1;
      case 1:
        *y1 = pow (ch->d1->a[i1] * (x1 - ch->d1->xi[i1]), ch->d1->alpha[i1])

```

```

        / ch->d1->b[i1]
        + ch->d1->eta[i1];
case 2:
    *y1 = ch->d1->a[i1] * tan (ch->d1->a[i1] * (x1 - ch->d1->xi[i1])
                             / (ch->d1->b[i1] * ch->d1->b[i1]))
        + ch->d1->eta[i1];
default:
    fprintf (stderr, "circe2: internal error: invalid map: %d\n", ch->d1->map[i1]);
}
60a <y2 ← x2 (C) 60a>≡
    switch (ch->d2->map[i2]) {
case 0:
    *y2 = x2;
case 1:
    *y2 = pow (ch->d2->a[i2] * (x2 - ch->d2->xi[i2]), ch->d2->alpha[i2])
           / ch->d2->b[i2]
           + ch->d2->eta[i2];
case 2:
    *y2 = ch->d2->a[i2] * tan (ch->d2->a[i2] * (x2 - ch->d2->xi[i2])
                             / (ch->d2->b[i2] * ch->d2->b[i2]))
           + ch->d2->eta[i2];
default:
    fprintf (stderr, "circe2: internal error: invalid map: %d\n", ch->d2->map[i2]);
}

```



There's still something wrong with *unweighted* events for the case that there is a triangle map *together* with a non-trivial $x_2 \rightarrow y_2$ map. *Fix this!!!*

```

60b <Inverse triangle map 60b>≡
    if (c2p%triang(ic)) then
        y2 = y1 * y2
        <Swap y1 and y2 in 50% of the cases 60d>
    end if
60c <Inverse triangle map (C) 60c>≡
    if (ch->triangle) {
        *y2 = *y1 * *y2;
        <Swap y1 and y2 in 50% of the cases (C) 61a>
    }
60d <Swap y1 and y2 in 50% of the cases 60d>≡
    call rng (u)
    if (2*u .ge. 1) then

```

```

        tmp = y1
        y1 = y2
        y2 = tmp
    end if

```

61a \langle Swap y1 and y2 in 50% of the cases (C) 61a $\rangle \equiv$

```

    rng (&u);
    if (2*u >= 1) {
        double tmp;
        tmp = *y1;
        *y1 = *y2;
        *y2 = tmp;
    }

```

13 Channel selection

We could call `cir2gn` immediately, but then `cir2gn` and `cir2ch` would have the same calling conventions and might have caused a lot of confusion.

61b \langle Public procedures 48c $\rangle + \equiv$

```

    public :: cir2ch

```

61c \langle Procedures 55b $\rangle + \equiv$

```

    subroutine cir2ch (p1, h1, p2, h2, rng)
        integer :: p1, h1, p2, h2
        external rng
        integer :: ic, ibot, itop
        real(kind=double) :: u
        call rng (u)
        ibot = 0
        itop = c2p%nc
        do
            if (itop .le. (ibot + 1)) then
                ic = ibot + 1
                p1 = c2p%pid1(ic)
                h1 = c2p%pol1(ic)
                p2 = c2p%pid2(ic)
                h2 = c2p%pol2(ic)
                exit
            else
                ic = (ibot + itop) / 2
                if (u .lt. c2p%cwgt(ic)) then
                    itop = ic
                else

```

```

        ibot = ic
    end if
end if
end do
write (*, '(A)') 'circe2: internal error'
stop
end subroutine cir2ch

```

62a \langle Public Procedures (C) 55c $\rangle + \equiv$

```

void
circe2_random_channel (circe2_channels *channels,
                      int *p1, int *h1, int *p2, int *h2,
                      void (*rng) (double *))
{
    circe2_channel *ch;
    int ic, ibot, itop;
    double u;
    POINTER_PANIC(circe2_random_channel, channels, "channels");
    rng (&u);
    ibot = 0;
    itop = channels->n;
    while (ibot + 1 < itop) {
        ic = (ibot + itop) / 2;
        if (u < channels->ch[ic]->channel_weight)
            itop = ic;
        else
            ibot = ic;
    }
    ch = channels->ch[ibot + 1];
    POINTER_PANIC(circe2_random_channel, ch, "selected channel");
    *p1 = ch->d1->pid;
    *h1 = ch->d1->pol;
    *p2 = ch->d2->pid;
    *h2 = ch->d2->pol;
}

```

62b \langle Macros (C) 62b $\rangle \equiv$

```

#define POINTER_PANIC(fct,ptr,name) \
    if (ptr == NULL) { \
        fprintf (stderr, "%s: PANIC: %s not initialized!\n", #fct, name); \
        exit (-1); \
    }

```

Below, we will always have $h1 = h2 = 0$. but we don't have to check this explicitly, because `cir2dm` will do it anyway. The procedure could be made more efficient, since most of `cir2dm` is undoing parts of `cir2gn`.

63a \langle Public procedures 48c $\rangle + \equiv$
`public :: cir2gp`

63b \langle Procedures 55b $\rangle + \equiv$
`subroutine cir2gp (p1, p2, x1, x2, pol, rng)`
`integer :: p1, p2`
`real(kind=double) :: x1, x2`
`real(kind=double), dimension(0:3,0:3) :: pol`
`external rng`
`integer :: h1, h2, i1, i2`
`real(kind=double) :: pol00`
`call cir2ch (p1, h1, p2, h2, rng)`
`call cir2gn (p1, h1, p2, h2, x1, x2, rng)`
`call cir2dm (p1, p2, x1, x2, pol)`
`pol00 = pol(0,0)`
`do i1 = 0, 4`
`do i2 = 0, 4`
`pol(i1,i2) = pol(i1,i2) / pol00`
`end do`
`end do`
`end subroutine cir2gp`

14 Luminosity

63c \langle Public procedures 48c $\rangle + \equiv$
`public :: cir2lm`

63d \langle Procedures 55b $\rangle + \equiv$
`function cir2lm (p1, h1, p2, h2)`
`integer :: p1, h1, p2, h2`
`integer :: ic`
`real(kind=double) :: cir2lm`
`cir2lm = 0`
`do ic = 1, c2p%nc`
`if (((p1 .eq. c2p%pid1(ic)) .or. (p1 .eq. 0)) &`
`and. ((h1 .eq. c2p%pol1(ic)) .or. (h1 .eq. 0)) &`
`and. ((p2 .eq. c2p%pid2(ic)) .or. (p2 .eq. 0)) &`
`and. ((h2 .eq. c2p%pol2(ic)) .or. (h2 .eq. 0))) then`
`cir2lm = cir2lm + c2p%lumi(ic)`

```

        end if
    end do
end function cir2lm

```

64a $\langle \text{Public Procedures (C) 55c} \rangle + \equiv$

```

double
circe2_lumi (circe2_channels *channels, int p1, int h1, int p2, int h2)
{
    int i;
    double lumi;
    POINTER_PANIC(circe2_random_channel, channels, "channels");
    lumi = 0;
    for (i = 0; i < channels->n; i++) {
        circe2_channel *c = channels->ch[i];
        if (((p1 == c->d1->pid) || (p1 == 0))
            && ((h1 == c->d1->pol) || (h1 == 0))
            && ((p2 == c->d2->pid) || (p2 == 0))
            && ((h2 == c->d2->pol) || (h2 == 0)))
            lumi += c->lumi;
    }
    return lumi;
}

```

15 2D-Distribution

64b $\langle \text{Public procedures 48c} \rangle + \equiv$

```

public :: cir2dn

```

64c $\langle \text{Procedures 55b} \rangle + \equiv$

```

function cir2dn (p1, h1, p2, h2, yy1, yy2)
    integer :: p1, h1, p2, h2
    real(kind=double) :: yy1, yy2
    real(kind=double) :: y1, y2
    real(kind=double) :: cir2dn
    integer :: i, ic, i1, i2, ibot, itop
     $\langle \text{Find ic for p1, h1, p2 and h2 56e} \rangle$ 
    if (ic .le. 0) then
        cir2dn = 0
        return
    end if
     $\langle (y1, y2) \leftarrow (yy1, yy2) \text{ 67a} \rangle$ 
    if ( (y1 .lt. c2p%yb1(0,ic)) .or. (y1 .gt. c2p%yb1(c2p%nb1(ic),ic)) &

```



```

        .or. (y2 .lt. c2p%yb2(0,ic)) .or. (y2 .gt. c2p%yb2(c2p%nb2(ic),ic))) then
        cir2dn = 0
        return
    end if
    <Do a binary search for  $y_{b1}(i_1 - 1) \leq y_1 < y_{b1}(i_1)$  68b>
    <Do a binary search for  $y_{b2}(i_2 - 1) \leq y_2 < y_{b2}(i_2)$  68c>
    cir2dn = c2p%val(i1,i2,ic)
    <Apply Jacobian for  $y_1$  map 65b>
    <Apply Jacobian for  $y_2$  map 66b>
    <Apply Jacobian for triangle map 67c>
end function cir2dn

```

65a *<Public Procedures (C) 55c>+≡*

```

double
circe2_distribution (circe2_channels *channels,
                    int p1, int h1, int p2, int h2,
                    double yy1, double yy2)
{
    circe2_channel *ch;
    int i, i1, i2;
    double y1, y2, d;
    POINTER_PANIC(circe2_random_channel, channels, "channels");
    ch = circe2_find_channel (channels, p1, h1, p2, h2);
    if (ch == NULL)
        return 0.0;
    <(y1,y2) ← (yy1,yy2) (C) 67b>
    if ((y1 < ch->d1->y[0]) || (y1 > ch->d1->y[ch->d1->n])
        || (y2 < ch->d2->y[0]) || (y2 > ch->d2->y[ch->d2->n]))
        return 0.0;
    i1 = binary_search (ch->d1->y, 0, ch->d1->n, y1);
    i2 = binary_search (ch->d2->y, 0, ch->d2->n, y2);
    d = ch->value[i1][i2];
    <Apply Jacobian for  $y_1$  map (C) 66a>
    <Apply Jacobian for  $y_2$  map (C) 66c>
    <Apply Jacobian for triangle map (C) 68a>
    return d;
}

```

cf. (53)

65b *<Apply Jacobian for y_1 map 65b>≡*

```

    if (c2p%map1(i1,ic) .eq. 0) then
    else if (c2p%map1(i1,ic) .eq. 1) then
        cir2dn = cir2dn * c2p%b1(i1,ic) / (c2p%a1(i1,ic)*c2p%alpha1(i1,ic)) &

```

```

        * (c2p%b1(i1,ic)*(y1-c2p%eta1(i1,ic)))*(1/c2p%alpha1(i1,ic)-1)
    else if (c2p%map1(i1,ic) .eq. 2) then
        cir2dn = cir2dn * c2p%b1(i1,ic)**2 &
            / ((y1-c2p%eta1(i1,ic))**2 + c2p%a1(i1,ic)**2)
    else
        write (*, '(A,I3)') &
            'circe2: internal error: invalid map: ', c2p%map1(i1,ic)
        stop
    end if

```

66a \langle Apply Jacobian for y_1 map (C) 66a $\rangle \equiv$

```

switch (ch->d1->map[i1]) {
case 0:
    /* identity */
case 1:
    d = d * ch->d1->b[i1] / (ch->d1->a[i1] * ch->d1->alpha[i1])
        * pow (ch->d1->b[i1] * (y1 - ch->d1->eta[i1]), 1/ch->d1->alpha[i1] - 1);
case 2:
    d = d * ch->d1->b[i1] * ch->d1->b[i1]
        / ((y1 - ch->d1->eta[i1]) * (y1 - ch->d1->eta[i1])
            + ch->d1->a[i1] * ch->d1->a[i1]);
default:
    fprintf (stderr, "circe2: internal error: invalid map: %d\n", ch->d1->map[i1]);
    exit (-1);
}

```

66b \langle Apply Jacobian for y_2 map 66b $\rangle \equiv$

```

if (c2p%map2(i2,ic) .eq. 0) then
else if (c2p%map2(i2,ic) .eq. 1) then
    cir2dn = cir2dn * c2p%b2(i2,ic) / (c2p%a2(i2,ic)*c2p%alpha2(i2,ic)) &
        * (c2p%b2(i2,ic)*(y2-c2p%eta2(i2,ic)))*(1/c2p%alpha2(i2,ic)-1)
else if (c2p%map2(i2,ic) .eq. 2) then
    cir2dn = cir2dn * c2p%b2(i2,ic)**2 &
        / ((y2-c2p%eta2(i2,ic))**2 + c2p%a2(i2,ic)**2)
else
    write (*, '(A,I3)') &
        'circe2: internal error: invalid map: ', c2p%map2(i2,ic)
    stop
end if

```

66c \langle Apply Jacobian for y_2 map (C) 66c $\rangle \equiv$

```

switch (ch->d2->map[i2]) {
case 0:
    /* identity */
case 1:

```

```

    d = d * ch->d2->b[i2] / (ch->d2->a[i2] * ch->d2->alpha[i2])
    * pow (ch->d2->b[i2] * (y2 - ch->d2->eta[i2]), 1/ch->d2->alpha[i2] - 1);
case 2:
    d = d * ch->d2->b[i2] * ch->d2->b[i2]
    / ((y2 - ch->d2->eta[i2]) * (y2 - ch->d2->eta[i2])
    + ch->d2->a[i2] * ch->d2->a[i2]);
default:
    fprintf (stderr, "circe2: internal error: invalid map: %d\n", ch->d2->map[i2]);
    exit (-1);
}

```

The triangle map

$$\begin{aligned} \tau : \{(x_1, x_2) \in [0, 1] \times [0, 1] : x_2 \leq x_1\} &\rightarrow [0, 1] \times [0, 1] \\ (x_1, x_2) &\mapsto (y_1, y_2) = (x_1, x_1 x_2) \end{aligned} \quad (54)$$

and its inverse

$$\begin{aligned} \tau^{-1} : [0, 1] \times [0, 1] &\rightarrow \{(x_1, x_2) \in [0, 1] \times [0, 1] : x_2 \leq x_1\} \\ (y_1, y_2) &\mapsto (x_1, x_2) = (y_1, y_2/y_1) \end{aligned} \quad (55)$$

```

67a  <(y1,y2) ← (yy1,yy2) 67a>≡
      if (c2p%triang(ic)) then
        y1 = max (yy1, yy2)
        y2 = min (yy1, yy2) / y1
      else
        y1 = yy1
        y2 = yy2
      end if

```

```

67b  <(y1,y2) ← (yy1,yy2) (C) 67b>≡
      if (ch->triangle) {
        y1 = max (yy1, yy2);
        y2 = min (yy1, yy2) / y1;
      } else {
        y1 = yy1;
        y2 = yy2;
      }

```

with the jacobian $J^*(y_1, y_2) = 1/y_2$ from

$$dx_1 \wedge dx_2 = \frac{1}{y_2} \cdot dy_1 \wedge dy_2 \quad (56)$$

```

67c  <Apply Jacobian for triangle map 67c>≡
      if (c2p%triang(ic)) then
        cir2dn = cir2dn / y1
      end if

```

68a \langle Apply Jacobian for triangle map (C) 68a $\rangle \equiv$

```
if (ch->triangle)
  d = d / y1;
```

We avoid name space pollution and speed up things at the same time by explicit inlining:

68b \langle Do a binary search for $y_{b1}(i_1 - 1) \leq y_1 < y_{b1}(i_1)$ 68b $\rangle \equiv$

```
  ibot = 0
  itop = c2p%nb1(ic)
  do
    if (itop .le. (ibot + 1)) then
      i1 = ibot + 1
      exit
    else
      i1 = (ibot + itop) / 2
      if (y1 .lt. c2p%yb1(i1,ic)) then
        itop = i1
      else
        ibot = i1
      end if
    end if
  end do
```

68c \langle Do a binary search for $y_{b2}(i_2 - 1) \leq y_2 < y_{b2}(i_2)$ 68c $\rangle \equiv$

```
  ibot = 0
  itop = c2p%nb2(ic)
  do
    if (itop .le. (ibot + 1)) then
      i2 = ibot + 1
    else
      i2 = (ibot + itop) / 2
      if (y2 .lt. c2p%yb2(i2,ic)) then
        itop = i2
      else
        ibot = i2
      end if
    end if
  end do
```

68d \langle Public procedures 48c $\rangle + \equiv$

```
public :: cir2dm
```

68e \langle Procedures 55b $\rangle + \equiv$

```
subroutine cir2dm (p1, p2, x1, x2, pol)
  integer :: p1, p2
  real(kind=double) :: x1, x2
```

```

real(kind=double) :: pol(0:3,0:3)
  <Test support for density matrices 69a>
  print *, 'circe2: cir2dm not implemented yet!'
end subroutine cir2dm

```

```

69a <Test support for density matrices 69a>≡
  if (c2p%polcpt .ne. POLGEN) then
    write (*, '(2A)') 'circe2: current beam ', &
      'description supports no density matrices'
    return
  end if

```

16 Reading Files

```

69b <Error codes for cir2ld 69b>≡
  integer, parameter :: EOK = 0
  integer, parameter :: EFILE = -1
  integer, parameter :: EMATCH = -2
  integer, parameter :: EFORMAT = -3
  integer, parameter :: ESIZE = -4

69c <Well known constants (C) 56d>+≡
  #define CIRCE2_EOK      0
  #define CIRCE2_EFILE    -1
  #define CIRCE2_EMATCH   -2
  #define CIRCE2_EFORMAT  -3
  #define CIRCE2_ESIZE    -4

69d <Public procedures 48c>+≡
  public :: cir2ld

69e <Procedures 55b>+≡
  subroutine cir2ld (file, design, roots, ierror)
    character(len=*) :: file, design
    real(kind=double) :: roots
    integer :: ierror
    character(len=72) :: buffer
    character(len=72) :: fdesgn
    character(len=72) :: fpolsp
    real(kind=double) :: froots
    integer :: lun, loaded, prefix
    logical :: match
    <Local variables in cir2ld 73a>

```

```

    <Error codes for cir2ld 69b>
    <Find free logical unit for lun 77e>
    loaded = 0
    <Open name for reading on lun 76a>
    if (ierror .gt. 0) then
        write (*, '(2A)') 'cir2ld: $Id: circe2.nw,v 1.56 2002/10/14 10:12:06 ohl Exp $'
    end if
    prefix = index (design, '*') - 1
100 continue
    <Skip comments until CIRCE2 76c>
    if (buffer(8:15) .eq. 'FORMAT#1') then
        read (lun, *)
        read (lun, *) fdesign, froots
        <Check if design and fdesign do match 71>
        if (match .and. (abs (froots - roots) .le. 1d0)) then
            <Load histograms 72a>
            loaded = loaded + 1
        else
            <Skip data until ECRIC2 77a>
            goto 100
        end if
    else
        write (*, '(2A)') 'cir2ld: invalid format: ', buffer(8:72)
        ierror = EFORMT
        return
    end if
    <Check for ECRIC2 77c>
    goto 100
end subroutine cir2ld

```

70 <Public Procedures (C) 55c>+≡

```

void
circe2_load (const char *file, const char *design, double roots, int *error)
{
    char buffer[73];
    char file_design[73];
    char file_polarization_support[73];
    double file_roots;
    int loaded;
    FILE *f;
    if (*error > 0)
        printf ("circe2: %s\n",
            "$Id: circe2.nw,v 1.56 2002/10/14 10:12:06 ohl Exp $");
}

```

```

loaded = 0;
f = fopen (file, "r");
if (f == NULL) {
    fprintf (stderr, "circe2_load: can't open %s: %s\n", file, sys_errlist[errno]);
    *error = CIRCE2_EFILE;
    return;
}
while (loaded == 0) {
    <Skip comments until CIRCE2 (C) 76d>
    if (strncmp ("FORMAT#1", buffer, 8) == 0) {
    }
    <Check for ECRIC2 (C) 77d>
}
}
/*
    integer prefix
    logical match
    prefix = index (design, '*') - 1
100 continue
    <Skip comments until CIRCE2 76c>
    if (buffer(8:15) .eq. 'FORMAT#1') then
        read (lun, *)
        read (lun, *) fdesgn, froots
        <Check if design and fdesgn do match 71>
        if (match .and. (abs (froots - roots) .le. 1d0)) then
            <Load histograms 72a>
            loaded = loaded + 1
        else
            <Skip data until ECRIC2 77a>
            goto 100
        end if
    else
        write (*, '(2A)') 'cir2ld: invalid format: ', buffer(8:72)
        ierror = EFORMAT
        return
    end if
    <Check for ECRIC2 77c>
    goto 100
end
*/

71 <Check if design and fdesgn do match 71>≡
    match = .false.
    if (fdesgn .eq. design) then

```

```

        match = .true.
    else if (prefix .eq. 0) then
        match = .true.
    else if (prefix .gt. 0) then
        if (fdesgn(1:min(prefix,len(fdesgn))) &
            .eq. design(1:min(prefix,len(design)))) then
            match = .true.
        end if
    end if
end if

72a  <Load histograms 72a>≡
    read (lun, *)
    read (lun, *) c2p%nc, fpolsp
    if (c2p%nc .gt. NCMAX) then
        write (*, '(A)') 'cir2ld: too many channels'
        ierror = ESIZE
        return
    end if
    <Decode polarization support 72b>
    c2p%cwgt(0) = 0
    do ic = 1, c2p%nc
        <Load channel ic 73b>
        <Load division xb1 74a>
        <Load division xb2 74b>
        <Calculate yb1 74c>
        <Calculate yb2 75a>
        <Load weights wgt and val 75b>
    end do
    do ic = 1, c2p%nc
        c2p%cwgt(ic) = c2p%cwgt(ic) / c2p%cwgt(c2p%nc)
    end do

72b  <Decode polarization support 72b>≡
    if (      (fpolsp(1:1).eq.'a') &
        .or. (fpolsp(1:1).eq.'A')) then
        c2p%polsp = POLAVG
    else if (      (fpolsp(1:1).eq.'h') &
        .or. (fpolsp(1:1).eq.'H')) then
        c2p%polsp = POLHEL
    else if (      (fpolsp(1:1).eq.'d') &
        .or. (fpolsp(1:1).eq.'D')) then
        c2p%polsp = POLGEN
    else
        write (*, '(A,I5)') &
            'cir2ld: invalid polarization support: ', fpolsp

```



```

        ierror = EFORMT
        return
    end if

73a  <Local variables in cir2ld 73a>≡
        integer :: i, ic

73b  <Load channel ic 73b>≡
        read (lun, *)
        read (lun, *) c2p%pid1(ic), c2p%pol1(ic), &
                     c2p%pid2(ic), c2p%pol2(ic), c2p%lumi(ic)
        c2p%cwgt(ic) = c2p%cwgt(ic-1) + c2p%lumi(ic)
        <Check polarization support 73c>

73c  <Check polarization support 73c>≡
        if (c2p%polspst .eq. POLAVG &
            .and. ( (c2p%pol1(ic) .ne. 0) &
                   .or. (c2p%pol2(ic) .ne. 0))) then
            write (*, '(A)') 'cir2ld: expecting averaged polarization'
            ierror = EFORMT
            return
        else if (c2p%polspst .eq. POLHEL &
            .and. ( (c2p%pol1(ic) .eq. 0) &
                   .or. (c2p%pol2(ic) .eq. 0))) then
            write (*, '(A)') 'cir2ld: expecting helicities'
            ierror = EFORMT
            return
        else if (c2p%polspst .eq. POLGEN) then
            write (*, '(A)') 'cir2ld: general polarizations not supported yet'
            ierror = EFORMT
            return
        else if (c2p%polspst .eq. POLGEN &
            .and. ( (c2p%pol1(ic) .ne. 0) &
                   .or. (c2p%pol2(ic) .ne. 0))) then
            write (*, '(A)') 'cir2ld: expecting pol = 0'
            ierror = EFORMT
            return
        end if

73d  <Load channel ic 73b>+≡
        read (lun, *)
        read (lun, *) c2p%nb1(ic), c2p%nb2(ic), c2p%triang(ic)
        if ((c2p%nb1(ic) .gt. NBMAX) .or. (c2p%nb2(ic) .gt. NBMAX)) then
            write (*, '(A)') 'cir2ld: too many bins'
            ierror = ESIZE
            return

```

```
end if
```

74a $\langle \text{Load division xb1 74a} \rangle \equiv$

```
read (lun, *)
read (lun, *) c2p%xb1(0,ic)
do i1 = 1, c2p%nb1(ic)
  read (lun, *) c2p%xb1(i1,ic), c2p%map1(i1,ic), c2p%alpha1(i1,ic), &
    c2p%xi1(i1,ic), c2p%eta1(i1,ic), c2p%a1(i1,ic), c2p%b1(i1,ic)
end do
```

74b $\langle \text{Load division xb2 74b} \rangle \equiv$

```
read (lun, *)
read (lun, *) c2p%xb2(0,ic)
do i2 = 1, c2p%nb2(ic)
  read (lun, *) c2p%xb2(i2,ic), c2p%map2(i2,ic), c2p%alpha2(i2,ic), &
    c2p%xi2(i2,ic), c2p%eta2(i2,ic), c2p%a2(i2,ic), c2p%b2(i2,ic)
end do
```

The boundaries are guaranteed to be fixed points of the maps only if the boundaries are not allowed to float. This doesn't affect the unweighted events, because they never see the codomain grid, but distribution would be distorted significantly. In the following sums $i1$ and $i2$ run over the maps, while i runs over the boundaries.



An alternative would be to introduce sentinels $\alpha1(0,:)$, $\xi1(0,:)$, etc.

74c $\langle \text{Calculate yb1 74c} \rangle \equiv$

```
do i = 0, c2p%nb1(ic)
  i1 = max (i, 1)
  if (c2p%map1(i1,ic) .eq. 0) then
    c2p%yb1(i,ic) = c2p%xb1(i,ic)
  else if (c2p%map1(i1,ic) .eq. 1) then
    c2p%yb1(i,ic) = &
      (c2p%a1(i1,ic) &
        * (c2p%xb1(i,ic)-c2p%xi1(i1,ic)))*c2p%alpha1(i1,ic) &
        / c2p%b1(i1,ic) + c2p%eta1(i1,ic)
  else if (c2p%map1(i1,ic) .eq. 2) then
    c2p%yb1(i,ic) = c2p%a1(i1,ic) &
      * tan(c2p%a1(i1,ic)/c2p%b1(i1,ic)**2 &
        * (c2p%xb1(i,ic)-c2p%xi1(i1,ic))) &
        + c2p%eta1(i1,ic)
  else
    write (*, '(A,I3)') 'cir2ld: invalid map: ', c2p%map1(i1,ic)
    ierror = EFORMT
    return
  end if
end do
```

```

        end if
    end do

75a  ⟨Calculate yb2 75a⟩≡
    do i = 0, c2p%nb2(ic)
        i2 = max (i, 1)
        if (c2p%map2(i2,ic) .eq. 0) then
            c2p%yb2(i,ic) = c2p%xb2(i,ic)
        else if (c2p%map2(i2,ic) .eq. 1) then
            c2p%yb2(i,ic) &
                = (c2p%a2(i2,ic) &
                    * (c2p%xb2(i,ic)-c2p%xi2(i2,ic)))*c2p%alpha2(i2,ic) &
                    / c2p%b2(i2,ic) + c2p%eta2(i2,ic)
        else if (c2p%map2(i2,ic) .eq. 2) then
            c2p%yb2(i,ic) = c2p%a2(i2,ic) &
                * tan(c2p%a2(i2,ic)/c2p%b2(i2,ic)**2 &
                    * (c2p%xb2(i,ic)-c2p%xi2(i2,ic))) &
                    + c2p%eta2(i2,ic)
        else
            write (*, '(A,I3)') 'cir2ld: invalid map: ', c2p%map2(i2,ic)
            ierror = EFORMT
            return
        end if
    end do

    cf. (53)

75b  ⟨Load weights wgt and val 75b⟩≡
    read (lun, *)
    c2p%wgt(0,ic) = 0
    do i = 1, c2p%nb1(ic)*c2p%nb2(ic)
        read (lun, *) w
        c2p%wgt(i,ic) = c2p%wgt(i-1,ic) + w
        ⟨(i1,i2) ← i 51f⟩
        c2p%val(i1,i2,ic) = w &
            / ( (c2p%xb1(i1,ic) - c2p%xb1(i1-1,ic)) &
                * (c2p%xb2(i2,ic) - c2p%xb2(i2-1,ic)))
    end do
    c2p%wgt(c2p%nb1(ic)*c2p%nb2(ic),ic) = 1

75c  ⟨Local variables in cir2ld 73a⟩+≡
    integer :: i1, i2
    real(kind=double) :: w

```

16.1 Auxiliary Code For Reading Files

76a *⟨Open name for reading on lun 76a⟩*≡
 open (unit = lun, file = file, status = 'old', iostat = status)
 if (status .ne. 0) then
 write (*, '(2A)') 'cir2ld: can''t open ', file
 ierror = EFILE
 return
 end if

76b *⟨Local variables in cir2ld 73a⟩*+≡
 integer :: status

76c *⟨Skip comments until CIRCE2 76c⟩*≡
 20 continue
 read (lun, '(A)', end = 29) buffer
 if (buffer(1:6) .eq. 'CIRCE2') then
 goto 21
 else if (buffer(1:1) .eq. '!') then
 if (ierror .gt. 0) then
 write (*, '(A)') buffer
 end if
 goto 20
 end if
 write (*, '(A)') 'cir2ld: invalid file'
 ierror = EFORMT
 return
 29 continue
 if (loaded .gt. 0) then
 close (unit = lun)
 ierror = EOK
 else
 ierror = EMATCH
 end if
 return
 21 continue

76d *⟨Skip comments until CIRCE2 (C) 76d⟩*≡
 while (1) {
 fgets (buffer, 72, f);
 if (strncmp ("ECRIC2", buffer, 6) == 0) {
 fclose (f);
 if (loaded)
 *error = CIRCE2_EOK;
 else {

```

        fprintf (stderr, "circe2_load: no match in %s\n", file);
        *error = CIRCE2_EMATCH;
    }
    return;
} else if ((buffer[0] == '!') && (*error > 0))
    printf ("circe2: %s\n", buffer);
}
fprintf (stderr, "circe2_load: invalid format %s\n", file);
*error = CIRCE2_EFORMAT;
return;
77a  <Skip data until ECRIC2 77a>≡
    101 continue
        read (lun, *) buffer
        if (buffer(1:6) .ne. 'ECRIC2') then
            goto 101
        end if
77b  <Skip data until ECRIC2 (C) 77b>≡
    while (1) {
        fgets (buffer, 72, f);
        if (strncmp ("ECRIC2", buffer, 6) == 0)
            break;
    }
77c  <Check for ECRIC2 77c>≡
        read (lun, '(A)') buffer
        if (buffer(1:6) .ne. 'ECRIC2') then
            write (*, '(A)') 'cir2ld: invalid file'
            ierror = EFORMAT
            return
        end if
77d  <Check for ECRIC2 (C) 77d>≡
        fgets (buffer, 72, f);
        if (strncmp ("ECRIC2", buffer, 6) != 0) {
            fprintf (stderr, "circe2_load: invalid format %s\n", file);
            *error = CIRCE2_EFORMAT;
            return;
        }
77e  <Find free logical unit for lun 77e>≡
        do lun = 10, 99
            inquire (unit = lun, exist = exists, &
                    opened = isopen, iostat = status)
            if ((status .eq. 0) .and. exists .and. .not.isopen) then

```

```

        goto 11
    end if
end do
write (*, '(A)') 'cir2ld: no free unit'
ierror = ESIZE
stop
11 continue
78a <Local variables in cir2ld 73a>+≡
    logical :: exists, isopen

```

17 Tests and Examples

```

78b <circe2_sample.f90 78b>≡
! circe2_sample.f90 -- testing circe2
<Copyleft notice 45d>
module circe2_sample_routines
    use kinds
    use circe2
    use tao_rng

    implicit none
    private

    <Sample procedures: public 81c>
    <write3_ascii: public 80c>

contains

    <Sample procedures 81d>
    <write3_ascii 80d>

end module circe2_sample_routines

program circe2_sample
    use kinds
    use circe2
    use circe2_sample_routines

    <implicit none 45a>

    integer :: i, p1, h1, p2, h2, n, ierror
    character(len=256) :: file, design, mode

```

```

real(kind=double) :: roots, x1, x2, w
read *, file, design, roots, p1, h1, p2, h2, mode, n
ierror = 0
call cir2ld (file, design, roots, ierror)
if (ierror .ne. 0) then
    print *, 'sample: cir2ld failed!'
    stop
end if
if ((mode(1:1) .eq. 'w') .or. (mode(1:1) .eq. 'W')) then
    <Generate n weighted events 80b>
else
    <Generate n unweighted events 80a>
end if
end program circe2_sample

```

```

79 <circe2_sample_binary.f90 79>≡
    ! circe2_sample_binary.f90 -- testing circe2
    <Copyleft notice 45d>
    module circe2_sample_routines_binary
        use kinds
        use circe2
        use tao_rng

        implicit none
        private

        <Sample procedures: public 81c>

contains

        <Sample procedures 81d>

    end module circe2_sample_routines_binary

    program circe2_sample_binary
        use kinds
        use circe2
        use circe2_sample_routines_binary

        <implicit none 45a>

        integer :: i, p1, h1, p2, h2, n, ierror
        character(len=256) :: file, design, mode

```

```

real(kind=double) :: roots, x1, x2, w
read *, file, design, roots, p1, h1, p2, h2, mode, n
ierror = 0
call cir2ld (file, design, roots, ierror)
if (ierror .ne. 0) then
    print *, 'sample: cir2ld failed!'
    stop
end if
if ((mode(1:1) .eq. 'w') .or. (mode(1:1) .eq. 'W')) then
    <Generate n weighted events 80b>
else
    <Generate n unweighted events 80a>
end if
end program circe2_sample_binary

```

Generation of unweighted events is Circe's home turf

```

80a <Generate n unweighted events 80a>≡
    do i = 1, n
        call cir2gn (p1, h1, p2, h2, x1, x2, random)
        call write3 (x1, x2, 1d0)
    end do

```

while generation of weighted events without any importance sampling is slightly abusive and only useful for checking `cir2dn`.

```

80b <Generate n weighted events 80b>≡
    do i = 1, n
        call random (x1)
        call random (x2)
        w = cir2dn (p1, h1, p2, h2, x1, x2)
        call write3 (x1, x2, w)
    end do

```

We could have written `print *, x, y, w` immediately, but the separate `write3` allows us to create ASCII and binary versions.

```

80c <write3_ascii: public 80c>≡
    public :: write3

80d <write3_ascii 80d>≡
    subroutine write3 (x, y, w)
        real(kind=double), intent(in) :: x, y, w
        print *, x, y, w
    end subroutine write3

```

This is not necessarily portable, but the only way to reliably write binary files without *any* markers uses C. Binary I/O is useful because—on my laptop—

event generation takes about 10 % of the time used by formatted writing of three floating point numbers.

```
81a <write3_binary.c 81a>≡
    #include <stdio.h>
    void write3_ (double *x, double *y, double *w)
    {
        double buf[3]; buf[0] = *x; buf[1] = *y; buf[2] = *w;
        if (fwrite (buf, sizeof (double), 3, stdout) != 3) {
            fprintf (stdin, "write3: fwrite failed!\n");
            exit (1);
        }
    }
}
```

The following bare bones random number generator produces some correlations that have been observed in testing Circe2

```
81b <Unused sample procedures 81b>≡
    subroutine random (r)
        real(kind=double) :: r
        integer, parameter :: M = 259200, A = 7141, C = 54773
        integer, save :: n = 0
        n = mod (n*A + C, M)
        r = real (n, kind=double) / real (M, kind=double)
    end subroutine random
```

therefore, it makes sense to call a more sophisticated one:

```
81c <Sample procedures: public 81c>≡
    public :: random

81d <Sample procedures 81d>≡
    subroutine random (u)
        real(kind=double) :: u
        call taornu (u)
    end subroutine random
```

18 Listing File Contents

Here's a small utility program for listing the contents of Circe2 data files. It performs *no* verification and assumes that the file is in the correct format (cf. table 2).

```
81e <circe2ls.f90 81e>≡
    ! circe2ls.f90 -- beam spectra for linear colliders and photon colliders
```

```

<Copyleft notice 45d>
program circe2ls
  use kinds

  <implicit none 45a>

  integer :: lun
  character(len=72) :: buffer
  character(len=72) :: file
  character(len=60) :: design, polspt
  integer :: pid1, hel1, pid2, hel2, nc
  real(kind=double) :: roots, lumi
  integer :: status
  logical :: exists, isopen
  integer :: ierror
  <Error codes for cir2ld 69b>
  <Find free logical unit for lun 77e>
  write (*, '(A)') 'enter name of Circe2 data file:'
  read (*, '(A)') buffer
  file = buffer
  open (unit = lun, file = file, status = 'old', iostat = status)
  if (status .ne. 0) then
    write (*, '(2A)') 'circe2: can''t open ', file
    stop
  end if
  write (*, '(A,1X,A)') 'file:', file
30  continue
  read (lun, '(A)', end = 39) buffer
  if (buffer(1:7) .eq. 'design,') then
    read (lun, *) design, roots
    read (lun, *)
    read (lun, *) nc, polspt
    <Write design/beam data 82>
    <Write channel header 83a>
  else if (buffer(1:5) .eq. 'pid1,') then
    read (lun, *) pid1, hel1, pid2, hel2, lumi
    <Write channel data 83b>
  end if
  goto 30
39  continue
end program circe2ls

```

82 <Write design/beam data 82>≡

```

        write (*, '(2A)')      '      design: ', design
        write (*, '(A,F7.1)') '      sqrt(s): ', roots
        write (*, '(A,I3)')    '      #channels: ', nc
        write (*, '(2A)')      ' polarization: ', polspt

83a  <Write channel header 83a>≡
        write (*, '(4X,4(A5,2X),A)') &
            'pid#1', 'hel#1', 'pid#2', 'hel#2', &
            'luminosity / (1032cm-2sec-1)'

83b  <Write channel data 83b>≡
        write (*, '(4X,4(I5,2X),F10.2,1X)') pid1, hel1, pid2, hel2, lumi

```

19 Static Data Sets

For those that despise reading files and prefer big ugly block datas:

```

83c  <circe2d.f90 83c>≡
    ! circe2d.f90 -- beam spectra for linear colliders and photon colliders
    <Copleft notice 45d>

    <subroutine cir2lb 83d>

    <block data cir2bd template 85b>

83d  <subroutine cir2lb 83d>≡
    subroutine cir2lb (design, roots, ierror)
    implicit none 45a>
    integer, parameter :: single = &
        & selected_real_kind (precision(1.), range(1.))
    integer, parameter :: double = &
        & selected_real_kind (precision(1._single) + 1, range(1._single) + 1)
    character(len=*), intent(in) :: design
    real(kind=double) :: roots
    integer :: ierror
    <parameter declarations 51a>
    </cir2cd/ 84a>
    external cir2bd
    integer :: ib, ic, i1, i2
    integer :: loaded
    loaded = 0
    do ib = 1, bdnb
        if (design .eq. bddsgn(ib)) then
            print *, 'circe2: CIR2LB not available yet!'

```

```

        loaded = loaded + 1
    end if
end do
if (loaded .gt. 0) then
    ierror = 0
else
    write (*, '(A)') 'circe2: no matching design'
    ierror = -1
end if
end subroutine cir2lb

```

84a *</cir2cd/ 84a>*≡
<8-byte aligned part of /cir2cd/ 84e>
<4-byte aligned part of /cir2cd/ 84c>
<1-byte aligned part of /cir2cd/ 84d>
<Separator 45c>

Three designs with two energies each would be NBMAX = 6, but let's be reasonable here while we're playing:

84b *<parameter declarations 51a>*+≡
 integer, parameter :: NBMMAX = 1

The actual number of parametersets:

84c *<4-byte aligned part of /cir2cd/ 84c>*≡
 integer :: bdnb
 common /cir2cd/ bdnb

84d *<1-byte aligned part of /cir2cd/ 84d>*≡
 character(len=6), dimension(NBMMAX) :: bddsgn
 common /cir2cd/ bddsgn

84e *<8-byte aligned part of /cir2cd/ 84e>*≡
 real(kind=double), dimension(0:NBMAX*NBMAX,NCMAX,NBMMAX) :: bdwgt
 common /cir2cd/ bdwgt
 real(kind=double), dimension(NBMAX,NBMAX,NCMAX,NBMMAX) :: bdval
 common /cir2cd/ bdval
 real(kind=double), dimension(0:NBMAX,NCMAX,NBMMAX) :: bdx1
 real(kind=double), dimension(0:NBMAX,NCMAX,NBMMAX) :: bdx2
 common /cir2cd/ bdx1, bdx2
 real(kind=double), dimension(NCMAX,NBMMAX) :: bdlumi
 common /cir2cd/ bdlumi
 real(kind=double), dimension(0:NCMAX,NBMMAX) :: bdcwgt
 common /cir2cd/ bdcwgt
 real(kind=double), dimension(0:NBMAX,NCMAX,NBMMAX) :: bdy1
 real(kind=double), dimension(0:NBMAX,NCMAX,NBMMAX) :: bdy2

```

common /cir2cd/ bdyb1, bdyb2
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdalf1
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdalf2
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdx11
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdx12
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdeta1
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdeta2
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bda1
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bda2
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdb1
real(kind=double), dimension(NBMAX,NCMAX,NBMMAX) :: bdb2
common /cir2cd/ bdalf1, bdx11, bdeta1, bda1, bdb1
common /cir2cd/ bdalf2, bdx12, bdeta2, bda2, bdb2

```

85a *<4-byte aligned part of /cir2cd/ 84c>+≡*

```

integer, dimension(NCMAX,NBMMAX) :: bdnb1, bdnb2
common /cir2cd/ bdnb1, bdnb2
logical, dimension(NCMAX,NBMMAX) :: bdtria
common /cir2cd/ bdtria
integer, dimension(NBMMAX) :: bdnc
common /cir2cd/ bdnc
integer, dimension(NCMAX,NBMMAX) :: bdpid1, bdpid2
integer, dimension(NCMAX,NBMMAX) :: bdpol1, bdpol2
common /cir2cd/ bdpid1, bdpol1, bdpid2, bdpol2
integer, dimension(NBMAX,NCMAX,NBMMAX) :: bdmapi1, bdmapi2
common /cir2cd/ bdmapi1, bdmapi2

```

In real life, this will be written by circe2_tool:

85b *<block data cir2bd template 85b>≡*

```

block data cir2bd
  <implicit none 45a>
  integer, parameter :: single = &
    & selected_real_kind (precision(1.), range(1.))
  integer, parameter :: double = &
    & selected_real_kind (precision(1._single) + 1, range(1._single) + 1)
  </cir2cm/ 85c>
  </cir2cd/ 84a>
  data bdnb /0/
  data bddsgn(1) /'TESLA '/
end block data cir2bd

```

85c *</cir2cm/ 85c>≡*

```

  <parameter part of /cir2cm/ 86>
  <8-byte aligned part of circe2 parameters 50a>
  common /cir2cm/ wgt

```

```

common /cir2cm/ val
common /cir2cm/ xb1, xb2
common /cir2cm/ lumi
common /cir2cm/ cwgt
common /cir2cm/ yb1, yb2
common /cir2cm/ alpha1, xi1, eta1, a1, b1
common /cir2cm/ alpha2, xi2, eta2, a2, b2
<4-byte aligned part of circe2 parameters 50b>
common /cir2cm/ nb1, nb2
common /cir2cm/ triang
common /cir2cm/ nc
common /cir2cm/ pid1, pol1, pid2, pol2
common /cir2cm/ map1, map2
common /cir2cm/ polspt
save /cir2cm/

```

```

86 <parameter part of /cir2cm/ 86>≡
    integer, parameter :: NBMAX = 100, NCMAX = 36
    integer, parameter :: NBMMAX = 1
    integer, parameter :: POLAVG = 1, POLHEL = 2, POLGEN = 3

```

A Making Grids

A.1 Interface of *Float*

```

module type T =
  sig
    type t
    (* Difference between 1.0 and the minimum float greater than 1.0 *)
    val epsilon : t
    val to_string : t → string
    val input_binary_float : in_channel → float
    val input_binary_floats : in_channel → float array → unit
  end

module Double : T with type t = float

```

A.2 Implementation of *Float*

```

open Printf

```

```

module type T =
  sig
    type t
    val epsilon : t
    val to_string : t → string
    val input_binary_float : in_channel → float
    val input_binary_floats : in_channel → float array → unit
  end

```

```

module Double =
  struct

```

```

    type t = float

```

Difference between 1.0 and the minimum float greater than 1.0



This is the hard coded value for double precision on Linux/Intel. We should determine this *machine dependent* value during configuration.

```

    let epsilon = 2.2204460492503131 · 10-16
    let little_endian = true

    let to_string x =
      let s = sprintf "%.17E" x in
      for i = 0 to String.length s - 1 do
        let c = s.i in
        if c = 'e' ∨ c = 'E' then
          s.i ← 'D'
      done;
      s

```

Identity floatingpoint numbers that are indistinguishable from integers for more concise printing.

```

    type int_or_float =
      | Int of int
      | Float of float

    let float_min_int = float min_int
    let float_max_int = float max_int

```

```

let soft_truncate x =
  let eps = 2.0 *. abs_float x *. epsilon in
  if x ≥ 0.0 then begin
    if x > float_max_int then
      Float x
    else if x - . floor x ≤ eps then
      Int (int_of_float x)
    else if ceil x - . x ≤ eps then
      Int (int_of_float x + 1)
    else
      Float x
  end else begin
    if x < float_min_int then
      Float x
    else if ceil x - . x ≤ eps then
      Int (int_of_float x)
    else if x - . floor x ≤ eps then
      Int (int_of_float x - 1)
    else
      Float x
  end
end

```

```

let to_short_string x =
  match soft_truncate x with
  | Int i → string_of_int i ^ "D0"
  | Float x → to_string x

```

Remark JRR: The function *float_of_string* was part of the C code of OCaml from version 3.01 to version 3.07. In the transition from version 3.06 to 3.07 it was decided to be obsolete and superseded by the routines from the module *Int64*. There I make ThO's functions available and I comment out the external *C* function.

The following code uses the external *C* function:

```

let float_to_bytes x =
  let bytes = String.create 8 in
  let bits = Int64.bits_of_float x in
  let copy i j =
    String.unsafe_set bytes i
    (Char.chr (FF16 land (Int64.to_int (Int64.shift_right_logical bits (8 ×
j)))))) in
  copy 7 0;
  copy 6 1;

```



```

copy 5 2;
copy 4 3;
copy 3 4;
copy 2 5;
copy 1 6;
copy 0 7;
bytes

```

The following three functions make only use of the *Int64* module.

```

let float_of_bytes bytes =
  let copy i j =
    Int64.shift_left (Int64.of_int (Char.code (String.unsafe_get bytes j))) (8 ×
i) in
    Int64.float_of_bits
      (Int64.logor (copy 7 0)
        (Int64.logor (copy 6 1)
          (Int64.logor (copy 5 2)
            (Int64.logor (copy 4 3)
              (Int64.logor (copy 3 4)
                (Int64.logor (copy 2 5)
                  (Int64.logor (copy 1 6)
                    (copy 0 7))))))))))

let input_binary_float ic =
  let buf = String.create 8 in
  really_input ic buf 0 8;
  float_of_bytes buf

let input_binary_floats ic array =
  let n = Array.length array in
  let bytes = 8 × n in
  let buf = String.create bytes in
  really_input ic buf 0 bytes;
  for i = 0 to n - 1 do
    let s = String.sub buf (8 × i) 8 in
    array.(i) ← float_of_bytes s
  done

```

Suggested by Xavier Leroy:

```

let output_float_big_endian oc f =
  let n = ref (Int64.bits_of_float f) in
  for i = 0 to 7 do
    output_byte oc (Int64.to_int (Int64.shift_right_logical !n 56));

```

```

      n := Int64.shift_left !n 8
    done

let output_float_little_endian oc f =
  let n = ref (Int64.bits_of_float f) in
  for i = 0 to 7 do
    output_byte oc (Int64.to_int !n);
    n := Int64.shift_right_logical !n 8
  done

let input_float_big_endian oc =
  let n = ref Int64.zero in
  for i = 0 to 7 do
    let b = input_byte oc in
    n := Int64.logor (Int64.shift_left !n 8) (Int64.of_int b)
  done;
  Int64.float_of_bits !n

let input_float_little_endian oc =
  let n = ref Int64.zero in
  for i = 0 to 7 do
    let b = input_byte oc in
    n := Int64.logor !n (Int64.shift_left (Int64.of_int b) (i × 8))
  done;
  Int64.float_of_bits !n

end

```

A.3 Interface of *Diffmap*

module type *T* =

sig

type *t*

An invertible differentiable map is characterized by its domain $[x_{\min}, x_{\max}]$

type *domain*

val *x_min* : *t* → *domain*

val *x_max* : *t* → *domain*

and codomain $[y_{\min}, y_{\max}]$

type *codomain*

val *y_min* : *t* → *codomain*

val *y_max* : *t* → *codomain*

the map proper

$$\begin{aligned}\phi &: [x_{\min}, x_{\max}] \rightarrow [y_{\min}, y_{\max}] \\ x &\mapsto y = \phi(x)\end{aligned}\tag{57}$$

`val phi : t → domain → codomain`

the inverse map

$$\begin{aligned}\phi^{-1} &: [y_{\min}, y_{\max}] \rightarrow [x_{\min}, x_{\max}] \\ y &\mapsto x = \phi^{-1}(y)\end{aligned}\tag{58}$$

`val ihp : t → codomain → domain`

the jacobian of the map

$$\begin{aligned}J &: [x_{\min}, x_{\max}] \rightarrow \mathbf{R} \\ x &\mapsto J(x) = \frac{d\phi}{dx}(x)\end{aligned}\tag{59}$$

`val jac : t → domain → float`

and finally the jacobian of the inverse map

$$\begin{aligned}J^* &: [y_{\min}, y_{\max}] \rightarrow \mathbf{R} \\ y &\mapsto J^*(y) = \frac{d\phi^{-1}}{dy}(y) = \left(\frac{d\phi}{dx}(\phi^{-1}(y)) \right)^{-1}\end{aligned}\tag{60}$$

`val caj : t → codomain → float`

`with_domain map x_min x_max` takes the map `map` and returns the ‘same’ map with the new domain $[x_{\min}, x_{\max}]$

`val with_domain : t → x_min : domain → x_max : domain → t`

There is also a convention for encoding the map so that it can be read by **Circe2**:

```
val encode : t → string
val as_block_data_to_channel : t →
  out_channel → string → int → int → int → unit
end
```

For the application in **Circe2**, it suffices to consider real maps. Introducing *domain* and *codomain* does not make any difference for the typechecker as long as we only use *Diffmap.Real*, but it provides documentation and keeps the door for extensions open.

`module type Real = T with type domain = float and type codomain = float`

A.4 Testing Real Maps

module type *Test* =

```
sig
  module M : Real
  val domain : M.t → unit
  val inverse : M.t → unit
  val jacobian : M.t → unit
  val all : M.t → unit
end
```

module *Make_Test* (*M* : *Real*) : *Test* with module *M* = *M*

A.5 Specific Real Maps

module *Id* :

```
sig
  include Real

  create x_min x_max y_min y_max creates an identity map  $[x_{\min}, x_{\max}] \rightarrow [y_{\min}, y_{\max}]$ .
```

$$\begin{aligned} \iota : [x_{\min}, x_{\max}] &\rightarrow [x_{\min}, x_{\max}] \\ x &\mapsto \iota(x) = x \end{aligned} \tag{61}$$

Default values for *x_min* and *x_max* are *y_min* and *y_max*, respectively. Indeed, they are the only possible values and other values raise an exception.

```
val create :
  ?x_min : domain → ?x_max : domain → codomain →
  codomain → t
end
```

module *Linear* :

```
sig
  include Real

  create x_min x_max y_min y_max creates a linear map  $[x_{\min}, x_{\max}] \rightarrow [y_{\min}, y_{\max}]$ . The parameters a and b are determined from domain and codomain.
```

$$\begin{aligned} \lambda_{a,b} : [x_{\min}, x_{\max}] &\rightarrow [y_{\min}, y_{\max}] \\ x &\mapsto \lambda_{a,b}(x) = ax + b \end{aligned} \tag{62}$$

Default values for *x_min* and *x_max* are *y_min* and *y_max*, respectively.

```

    val create :
      ?x_min : domain → ?x_max : domain → codomain →
      codomain → t
  end

```

module *Power* :

```

  sig
    include Real

```

create alpha eta x_min x_max y_min y_max creates a power map $[x_{\min}, x_{\max}] \rightarrow [y_{\min}, y_{\max}]$. The parameters ξ , a and b are determined from α , η , domain and codomain.

$$\begin{aligned} \psi_{a,b}^{\alpha,\xi,\eta} : [x_{\min}, x_{\max}] &\rightarrow [y_{\min}, y_{\max}] \\ x &\mapsto \psi_{a,b}^{\alpha,\xi,\eta}(x) = \frac{1}{b}(a(x - \xi))^\alpha + \eta \end{aligned} \quad (63)$$

Default values for x_{\min} and x_{\max} are y_{\min} and y_{\max} , respectively.

```

    val create : alpha : float → eta : float →
      ?x_min : domain → ?x_max : domain → codomain →
      codomain → t
  end

```

module *Resonance* :

```

  sig
    include Real

```

create eta a x_min x_max y_min y_max creates a resonance map $[x_{\min}, x_{\max}] \rightarrow [y_{\min}, y_{\max}]$.

$$\begin{aligned} \rho_{a,b}^{\xi,\eta} : [x_{\min}, x_{\max}] &\rightarrow [y_{\min}, y_{\max}] \\ x &\mapsto \rho_{a,b}^{\xi,\eta}(x) = a \tan\left(\frac{a}{b^2}(x - \xi)\right) + \eta \end{aligned} \quad (64)$$

The parameters ξ and b are determined from η , a , domain and codomain. Default values for x_{\min} and x_{\max} are y_{\min} and y_{\max} , respectively.

```

    val create : eta : float → a : float →
      ?x_min : domain → ?x_max : domain → codomain →
      codomain → t
  end

```

A.6 Implementation of *Diffmap*

open *Printf*

```

module type T =
  sig
    type t
    type domain
    val x_min : t → domain
    val x_max : t → domain
    type codomain
    val y_min : t → codomain
    val y_max : t → codomain
    val phi : t → domain → codomain
    val ihp : t → codomain → domain
    val jac : t → domain → float
    val caj : t → codomain → float
    val with_domain : t → x_min : domain → x_max : domain → t
    val encode : t → string
    val as_block_data_to_channel : t →
      out_channel → string → int → int → int → unit
  end

module type Real = T with type domain = float and type codomain = float

```

A.7 Testing Real Maps

```

module type Test =
  sig
    module M : Real
    val domain : M.t → unit
    val inverse : M.t → unit
    val jacobian : M.t → unit
    val all : M.t → unit
  end

module Make_Test (M : Real) =
  struct
    module M = M

    let steps = 1000
    let epsilon = 1.0 · 10-6
  end

```

```

let diff ?(tolerance = 1.0 · 10-13) x1 x2 =
  let d = (x1 - . x2) in
  if abs_float d < (abs_float x1 + . abs_float x2) * . tolerance then
    0.0
  else
    d

let derive x_min x_max f x =
  let xp = min x_max (x + . epsilon)
  and xm = max x_min (x - . epsilon) in
  (f xp - . f xm) /. (xp - .xm)

let domain m =
  let x_min = M.x_min m
  and x_max = M.x_max m
  and y_min = M.y_min m
  and y_max = M.y_max m in
  let x_min' = M.ihp m y_min
  and x_max' = M.ihp m y_max
  and y_min' = M.phi m x_min
  and y_max' = M.phi m x_max in
  printf "f: [%g,%g] -> [%g,%g] ([%g,%g])\n"
    x_min x_max y_min' y_max' (diff y_min' y_min) (diff y_max' y_max);
  printf "f^-1: [%g,%g] -> [%g,%g] ([%g,%g])\n"
    y_min y_max x_min' x_max' (diff x_min' x_min) (diff x_max' x_max)

let inverse m =
  let x_min = M.x_min m
  and x_max = M.x_max m
  and y_min = M.y_min m
  and y_max = M.y_max m in
  for i = 1 to steps do
    let x = x_min + . Random.float (x_max - . x_min)
    and y = y_min + . Random.float (y_max - . y_min) in
    let x' = M.ihp m y
    and y' = M.phi m x in
    let x'' = M.ihp m y'
    and y'' = M.phi m x' in
    let dx = diff x'' x
    and dy = diff y'' y in
    if dx ≠ 0.0 then
      printf "f^-1 o f: [%g]->[%g]->[%g](%g)\n" x y' x'' dx;
    if dy ≠ 0.0 then

```

```

        printf "f_o_f^-1: %g->%g->%g(%g)\n" y x' y' dy
    done

let jacobian m =
    let x_min = M.x_min m
    and x_max = M.x_max m
    and y_min = M.y_min m
    and y_max = M.y_max m in
    for i = 1 to steps do
        let x = x_min + . Random.float (x_max - . x_min)
        and y = y_min + . Random.float (y_max - . y_min) in
        let jac_x' = derive x_min x_max (M.phi m) x
        and jac_x = M.jac m x
        and inv_jac_y' = derive y_min y_max (M.ihp m) y
        and inv_jac_y = M.caj m y in
        let dj = diff ~tolerance : 1.0 · 10-9 jac_x' jac_x
        and dij = diff ~tolerance : 1.0 · 10-9 inv_jac_y' inv_jac_y in
        if dj ≠ 0.0 then
            printf "dy/dx: %g->%g(%g)\n" x jac_x' dj;
        if dij ≠ 0.0 then
            printf "dx/dy: %g->%g(%g)\n" y inv_jac_y' dij
    done

let all m =
    printf "phi(domain)=codomain and phi(codomain)=domain";
    domain m;
    printf "ihp_o_phi=id(domain) and phi_o_ihp=id(codomain)";
    inverse m;
    printf "jacobian";
    jacobian m

end

```

A.8 Specific Real Maps

```

module Id =
    struct
        type domain = float
        type codomain = float
    end

```



```

type t =
  { x_min : domain;
    x_max : domain;
    y_min : codomain;
    y_max : codomain;
    phi : float → float;
    ihp : float → float;
    jac : float → float;
    caj : float → float }

let encode m = "0_1_0_0_1_1"

let as_block_data_to_channel m oc tag i n_ch n_beam =
  fprintf oc "UUUUUUdata_bdmap%s(%d,%d,%d)_/0/\n" tag i n_ch n_beam;
  fprintf oc "UUUUUUdata_bdalf%s(%d,%d,%d)_/1D0/\n" tag i n_ch n_beam;
  fprintf oc "UUUUUUdata_bdxi%s(%d,%d,%d)_/OD0/\n" tag i n_ch n_beam;
  fprintf oc "UUUUUUdata_bdetas%s(%d,%d,%d)_/OD0/\n" tag i n_ch n_beam;
  fprintf oc "UUUUUUdata_bdas%s(%d,%d,%d)_/1D0/\n" tag i n_ch n_beam;
  fprintf oc "UUUUUUdata_bdb%s(%d,%d,%d)_/1D0/\n" tag i n_ch n_beam

let closure ~x_min ~x_max ~y_min ~y_max =
  let phi x = x
  and ihp y = y
  and jac x = 1.0
  and caj y = 1.0 in
  { x_min = x_min;
    x_max = x_max;
    y_min = y_min;
    y_max = y_max;
    phi = phi;
    ihp = ihp;
    jac = jac;
    caj = caj }

let idmap ~x_min ~x_max ~y_min ~y_max =
  if x_min ≠ y_min ∧ x_max ≠ y_max then
    invalid_arg "Diffmap.Id.idmap"
  else
    closure ~x_min ~x_max ~y_min ~y_max

let with_domain m ~x_min ~x_max =
  idmap ~x_min ~x_max ~y_min : m.y_min ~y_max : m.y_max

```

```

let create ?x_min ?x_max y_min y_max =
  idmap
    ~x_min : (match x_min with Some x → x | None → y_min)
    ~x_max : (match x_max with Some x → x | None → y_max)
    ~y_min ~y_max

let x_min m = m.x_min
let x_max m = m.x_max
let y_min m = m.y_min
let y_max m = m.y_max

let phi m = m.phi
let ihp m = m.ihp
let jac m = m.jac
let caj m = m.caj

end

module Linear =
struct
  type domain = float
  type codomain = float

  type t =
    { x_min : domain;
      x_max : domain;
      y_min : codomain;
      y_max : codomain;
      a : float;
      b : float;
      phi : domain → codomain;
      ihp : codomain → domain;
      jac : domain → float;
      caj : codomain → float }

  let encode m = failwith "Diffmap.Linear: not used in Circe2"
  let as_block_data_to_channel m oc tag i n_ch n_beam =
    failwith "Diffmap.Linear: not used in Circe2"
  let closure ~x_min ~x_max ~y_min ~y_max ~a ~b =

```

$$x \mapsto \lambda_{a,b}(x) = ax + b \quad (65)$$

```

let phi x = a *. x +. b

```

$$y \mapsto (\lambda_{a,b})^{-1}(y) = \frac{y - b}{a} \quad (66)$$

```

and ihp y = (y - . b) /. a
and jac x = a
and caj y = 1.0 /. a in
{ x_min = x_min;
  x_max = x_max;
  y_min = y_min;
  y_max = y_max;
  a = a;
  b = b;
  phi = phi;
  ihp = ihp;
  jac = jac;
  caj = caj }

let linearmap ~x_min ~x_max ~y_min ~y_max =
  let delta_x = x_max - . x_min
  and delta_y = y_max - . y_min in
  let a = delta_y /. delta_x
  and b = (y_min * . x_max - . y_max * . x_min) /. delta_x in
  closure ~x_min ~x_max ~y_min ~y_max ~a ~b

let with_domain m ~x_min ~x_max =
  linearmap ~x_min ~x_max ~y_min : m.y_min ~y_max : m.y_max

let create ?x_min ?x_max y_min y_max =
  linearmap
    ~x_min : (match x_min with Some x → x | None → y_min)
    ~x_max : (match x_max with Some x → x | None → y_max)
    ~y_min ~y_max

let x_min m = m.x_min
let x_max m = m.x_max
let y_min m = m.y_min
let y_max m = m.y_max

let phi m = m.phi
let ihp m = m.ihp
let jac m = m.jac
let caj m = m.caj

```

```

end

module Power =
  struct

    type domain = float
    type codomain = float

    type t =
      { x_min : domain;
        x_max : domain;
        y_min : codomain;
        y_max : codomain;
        alpha : float;
        xi : float;
        eta : float;
        a : float;
        b : float;
        phi : domain → codomain;
        ihp : codomain → domain;
        jac : domain → float;
        caj : codomain → float }

    let encode m =
      sprintf "1_%.15s_%.15s_%.15s_%.15s"
        (Float.Double.to_string m.alpha)
        (Float.Double.to_string m.xi)
        (Float.Double.to_string m.eta)
        (Float.Double.to_string m.a)
        (Float.Double.to_string m.b)

    let as_block_data_to_channel m oc tag i n_ch n_beam =
      fprintf oc "%%%%%%%%data_bmap%s(%d,%d,%d)_/1/\n"
        tag i n_ch n_beam;
      fprintf oc "%%%%%%%%data_bdalf%s(%d,%d,%d)_/%s/\n"
        tag i n_ch n_beam (Float.Double.to_string m.alpha);
      fprintf oc "%%%%%%%%data_bdxs%s(%d,%d,%d)_/%s/\n"
        tag i n_ch n_beam (Float.Double.to_string m.xi);
      fprintf oc "%%%%%%%%data_bdetas%s(%d,%d,%d)_/%s/\n"
        tag i n_ch n_beam (Float.Double.to_string m.eta);
      fprintf oc "%%%%%%%%data_bdas%s(%d,%d,%d)_/%s/\n"
        tag i n_ch n_beam (Float.Double.to_string m.a);
      fprintf oc "%%%%%%%%data_bdb%s(%d,%d,%d)_/%s/\n"
        tag i n_ch n_beam (Float.Double.to_string m.b)

```

let *closure* $\sim x_min \sim x_max \sim y_min \sim y_max \sim alpha \sim xi \sim eta \sim a \sim b =$

$$x \mapsto \psi_{a,b}^{\alpha,\xi,\eta}(x) = \frac{1}{b}(a(x - \xi))^\alpha + \eta \quad (67)$$

let *phi* $x =$

$$(a * (x - . xi)) ** alpha /. b + . eta$$

$$y \mapsto (\psi_{a,b}^{\alpha,\xi,\eta})^{-1}(y) = \frac{1}{a}(b(y - \eta))^{1/\alpha} + \xi \quad (68)$$

and *ihp* $y =$

$$(b * (y - . eta)) ** (1.0 /. alpha) /. a + . xi$$

$$\frac{dy}{dx}(x) = \frac{a\alpha}{b}(a(x - \xi))^{\alpha-1} \quad (69)$$

and *jac* $x =$

$$a * . alpha * (a * (x - . xi)) ** (alpha - . 1.0) /. b$$

$$\frac{dx}{dy}(y) = \frac{b}{a\alpha}(b(y - \eta))^{1/\alpha-1} \quad (70)$$

and *caj* $y =$

$$b * (b * (y - . eta)) ** (1.0 /. alpha - . 1.0) /. (a * . alpha) \text{ in}$$

{ $x_min = x_min;$
 $x_max = x_max;$
 $y_min = y_min;$
 $y_max = y_max;$
 $alpha = alpha;$
 $xi = xi;$
 $eta = eta;$
 $a = a;$
 $b = b;$
 $phi = phi;$
 $ihp = ihp;$
 $jac = jac;$
 $caj = caj$ }

$$a_i = \frac{(b_i(y_i - \eta_i))^{1/\alpha_i} - (b_i(y_{i-1} - \eta_i))^{1/\alpha_i}}{x_i - x_{i-1}} \quad (71a)$$

$$\xi_i = \frac{x_{i-1}|y_i - \eta_i|^{1/\alpha_i} - x_i|y_{i-1} - \eta_i|^{1/\alpha_i}}{|y_i - \eta_i|^{1/\alpha_i} - |y_{i-1} - \eta_i|^{1/\alpha_i}} \quad (71b)$$

The degeneracy (39) can finally be resolved by demanding $|b| = 1$ in (47a).

```

let powermap ~x_min ~x_max ~y_min ~y_max ~alpha ~eta =
  let b =
    if eta ≤ y_min then
      1.
    else if eta ≥ y_max then
      -1.
    else
      invalid_arg "singular" in
  let pow y = (b *. (y - . eta)) ** (1. /. alpha) in
  let delta_pow = pow y_max - . pow y_min
  and delta_x = x_max - . x_min in
  let a = delta_pow /. delta_x
  and xi = (x_min *. pow y_max - . x_max *. pow y_min) /. delta_pow in
  closure ~x_min ~x_max ~y_min ~y_max ~alpha ~xi ~eta ~a ~b

let with_domain m ~x_min ~x_max =
  powermap ~x_min ~x_max ~y_min : m.y_min ~y_max : m.y_max
    ~alpha : m.alpha ~eta : m.eta

let create ~alpha ~eta ?x_min ?x_max y_min y_max =
  powermap
    ~x_min : (match x_min with Some x → x | None → y_min)
    ~x_max : (match x_max with Some x → x | None → y_max)
    ~y_min ~y_max ~alpha ~eta

let x_min m = m.x_min
let x_max m = m.x_max
let y_min m = m.y_min
let y_max m = m.y_max

let phi m = m.phi
let ihp m = m.ihp
let jac m = m.jac
let caj m = m.caj

end

module Resonance =
  struct
    type domain = float
    type codomain = float

```

```

type t =
  { x_min : domain;
    x_max : domain;
    y_min : codomain;
    y_max : codomain;
    xi : float;
    eta : float;
    a : float;
    b : float;
    phi : domain → codomain;
    ihp : codomain → domain;
    jac : domain → float;
    caj : codomain → float }

let encode m =
  sprintf "2_0_s_s_s_s"
    (Float.Double.to_string m.xi)
    (Float.Double.to_string m.eta)
    (Float.Double.to_string m.a)
    (Float.Double.to_string m.b)

let as_block_data_to_channel m oc tag i n_ch n_beam =
  fprintf oc "data_bmap%s(%d,%d,%d)_/2/\n"
    tag i n_ch n_beam;
  fprintf oc "data_bdalf%s(%d,%d,%d)_/0D0/\n"
    tag i n_ch n_beam;
  fprintf oc "data_bdx_i%s(%d,%d,%d)_/%s/\n"
    tag i n_ch n_beam (Float.Double.to_string m.xi);
  fprintf oc "data_bdeta%s(%d,%d,%d)_/%s/\n"
    tag i n_ch n_beam (Float.Double.to_string m.eta);
  fprintf oc "data_bda%s(%d,%d,%d)_/%s/\n"
    tag i n_ch n_beam (Float.Double.to_string m.a);
  fprintf oc "data_bdb%s(%d,%d,%d)_/%s/\n"
    tag i n_ch n_beam (Float.Double.to_string m.b)

let closure ~x_min ~x_max ~y_min ~y_max ~xi ~eta ~a ~b =

```

$$x \mapsto \rho_{a,b}^{\xi,\eta}(x) = a \tan \left(\frac{a}{b^2} (x - \xi) \right) + \eta \quad (72)$$

```

let phi x = a *. tan (a *. (x -. xi) /. (b *. b)) +. eta

```

$$y \mapsto (\rho_{a,b}^{\xi,\eta})^{-1}(y) = \frac{b^2}{a} \operatorname{atan} \left(\frac{y - \eta}{a} \right) + \xi \quad (73)$$

and $ihp\ y = b * . b * . (atan2\ (y - . eta)\ a) /. a + . xi$

$$\frac{dy}{dx}(x(y)) = \frac{1}{\frac{dx}{dy}(y)} = \left(\frac{b^2}{(y - \eta)^2 + a^2} \right)^{-1} \quad (74)$$

and $caj\ y = b * . b /. ((y - . eta) ** 2.0 + . a * . a)$ in

let $jac\ x = 1.0 /. caj\ (phi\ x)$ in

```
{ x_min = x_min;
  x_max = x_max;
  y_min = y_min;
  y_max = y_max;
  xi = xi;
  eta = eta;
  a = a;
  b = b;
  phi = phi;
  ihp = ihp;
  jac = jac;
  caj = caj }
```

$$b_i = \sqrt{a_i \frac{x_i - x_{i-1}}{\operatorname{atan}\left(\frac{y_i - \eta_i}{a_i}\right) - \operatorname{atan}\left(\frac{y_{i-1} - \eta_i}{a_i}\right)}} \quad (75a)$$

$$\xi_i = \frac{x_{i-1} \operatorname{atan}\left(\frac{y_i - \eta_i}{a_i}\right) - x_i \operatorname{atan}\left(\frac{y_{i-1} - \eta_i}{a_i}\right)}{x_i - x_{i-1}} \quad (75b)$$

let $resonancemap\ \tilde{x}_{min}\ \tilde{x}_{max}\ \tilde{y}_{min}\ \tilde{y}_{max}\ \tilde{eta}\ \tilde{a} =$

let $arc\ y = atan2\ (y - . eta)\ a$ in

let $delta_arc = arc\ y_{max} - . arc\ y_{min}$

and $delta_x = x_{max} - . x_{min}$ in

let $b = sqrt\ (a * . delta_x /. delta_arc)$

and $xi = (x_{min} * . arc\ y_{max} - . x_{max} * . arc\ y_{min}) /. delta_arc$ in

$closure\ \tilde{x}_{min}\ \tilde{x}_{max}\ \tilde{y}_{min}\ \tilde{y}_{max}\ \tilde{xi}\ \tilde{eta}\ \tilde{a}\ \tilde{b}$

let $with_domain\ m\ \tilde{x}_{min}\ \tilde{x}_{max} =$

$resonancemap\ \tilde{x}_{min}\ \tilde{x}_{max}\ \tilde{y}_{min} : m.y_{min}\ \tilde{y}_{max} : m.y_{max}$
 $\tilde{eta} : m.eta\ \tilde{a} : m.a$


```

let create ~eta ~a ?x_min ?x_max y_min y_max =
  resonancemap
    ~x_min : (match x_min with Some x → x | None → y_min)
    ~x_max : (match x_max with Some x → x | None → y_max)
    ~y_min ~y_max ~eta ~a

let x_min m = m.x_min
let x_max m = m.x_max
let y_min m = m.y_min
let y_max m = m.y_max

let phi m = m.phi
let ihp m = m.ihp
let jac m = m.jac
let caj m = m.caj

end

```

A.9 Interface of *Diffmaps*

A.10 Combined Differentiable Maps

```

module type T =
  sig
    include Diffmap.T
    val id : ?x_min : domain → ?x_max : domain → codomain →
      codomain → t
  end

module type Real = T with type domain = float and type codomain = float

module type Default =
  sig
    include Real

    val power : alpha : float → eta : float →
      ?x_min : domain → ?x_max : domain → codomain → codomain →
    t

    val resonance : eta : float → a : float →
      ?x_min : domain → ?x_max : domain → codomain → codomain →
    t

  end

module Default : Default

```

A.11 Implementation of *Diffmaps*

```

module type T =
  sig
    include Diffmap.T
    val id : ?x_min : domain → ?x_max : domain → codomain →
      codomain → t
  end

module type Real = T with type domain = float and type codomain = float

module type Default =
  sig
    include Real

    val power : alpha : float → eta : float →
      ?x_min : domain → ?x_max : domain → codomain → codomain →
      t

    val resonance : eta : float → a : float →
      ?x_min : domain → ?x_max : domain → codomain → codomain →
      t

  end

module Default =
  struct
    type domain = float
    type codomain = float

    type t =
      { encode : string;
        as_block_data_to_channel :
          out_channel → string → int → int → int → unit;
        with_domain : x_min : domain → x_max : domain → t;
        x_min : domain;
        x_max : domain;
        y_min : codomain;
        y_max : codomain;
        phi : domain → codomain;
        ihp : codomain → domain;
        jac : domain → float;
        cay : codomain → float }
  end

```

```

let encode m = m.encode
let as_block_data_to_channel m = m.as_block_data_to_channel
let with_domain m = m.with_domain

let x_min m = m.x_min
let x_max m = m.x_max
let y_min m = m.y_min
let y_max m = m.y_max

let phi m = m.phi
let ihp m = m.ihp
let jac m = m.jac
let caj m = m.caj

let rec id ?x_min ?x_max y_min y_max =
  let m = Diffmap.Id.create ?x_min ?x_max y_min y_max in
  let with_domain ~x_min ~x_max =
    id ~x_min ~x_max y_min y_max in
  { encode = Diffmap.Id.encode m;
    as_block_data_to_channel = Diffmap.Id.as_block_data_to_channel m;
    with_domain = with_domain;
    x_min = Diffmap.Id.x_min m;
    x_max = Diffmap.Id.x_max m;
    y_min = Diffmap.Id.y_min m;
    y_max = Diffmap.Id.y_max m;
    phi = Diffmap.Id.phi m;
    ihp = Diffmap.Id.ihp m;
    jac = Diffmap.Id.jac m;
    caj = Diffmap.Id.caj m }

let rec power ~alpha ~eta ?x_min ?x_max y_min y_max =
  let m = Diffmap.Power.create ~alpha ~eta ?x_min ?x_max y_min y_max in
  let with_domain ~x_min ~x_max =
    power ~alpha ~eta ~x_min ~x_max y_min y_max in
  { encode = Diffmap.Power.encode m;
    as_block_data_to_channel = Diffmap.Power.as_block_data_to_channel m;
    with_domain = with_domain;
    x_min = Diffmap.Power.x_min m;
    x_max = Diffmap.Power.x_max m;
    y_min = Diffmap.Power.y_min m;
    y_max = Diffmap.Power.y_max m;
    phi = Diffmap.Power.phi m;
    ihp = Diffmap.Power.ihp m;

```

```

    jac = Diffmap.Power.jac m;
    caj = Diffmap.Power.caj m }

let rec resonance ~eta ~a ?x_min ?x_max y_min y_max =
  let m = Diffmap.Resonance.create ~eta ~a ?x_min ?x_max y_min y_max in
  let with_domain ~x_min ~x_max =
    resonance ~eta ~a ~x_min ~x_max y_min y_max in
  { encode = Diffmap.Resonance.encode m;
    as_block_data_to_channel = Diffmap.Resonance.as_block_data_to_channel m;
    with_domain = with_domain;
    x_min = Diffmap.Resonance.x_min m;
    x_max = Diffmap.Resonance.x_max m;
    y_min = Diffmap.Resonance.y_min m;
    y_max = Diffmap.Resonance.y_max m;
    phi = Diffmap.Resonance.phi m;
    ihp = Diffmap.Resonance.ihp m;
    jac = Diffmap.Resonance.jac m;
    caj = Diffmap.Resonance.caj m }

end

```

A.12 Interface of *Division*

We have divisions (*Mono*) and divisions of divisions (*Poly*). Except for creation, they share the same interface (*T*), which can be used as a signature for functor arguments. In particular, both kinds of divisions can be used with the *Grid.Make* functor.

module type *T* =

sig

type *t*

Copy a division, allocating fresh arrays with identical contents.

val *copy* : *t* → *t*

Using $\{x_0, x_1, \dots, x_n\}$, find *i*, such that $x_i \leq x < x_{i+1}$. We need to export this, if we want to maintain additional histograms in user modules.

val *find* : *t* → float → int

record *d* *x* *f* records the value *f* at coordinate *x*. NB: this function modifies *d*.

val *record* : *t* → float → float → unit

VEGAS style rebinning. The default values for *power* and both *fixed_min*, *fixed_max* are 1.5 and **false** respectively.

```
val rebin : ?power : float → ?fixed_min : bool → ?fixed_max : bool →
t → t
J*(y)
```



Should this include the $1/\Delta y$?

```
val caj : t → float → float
val n_bins : t → int
val bins : t → float array
val to_channel : out_channel → t → unit
val as_block_data_to_channel : out_channel →
string → int → int → t → unit

end

exception Out_of_range of float × (float × float)
exception Rebinning_failure of string
```

A.12.1 Primary Divisions

module type *Mono* =

```
sig
  include T
```

create bias n x_min x_max creates a division with *n* equidistant bins spanning $[x_{\min}, x_{\max}]$. The *bias* is a function that is multiplied with the weights for VEGAS/VAMP rebinning. It can be used to highlight the regions of phasespace that are expected to be most relevant in applications. The default is **fun** *x* → 1.0, of course.

```
val create : ?bias : (float → float) → int → float → float → t

end

module Mono : Mono
```

A.12.2 Polydivisions

```
module type Poly =
  sig
    module M : Diffmaps.Real

    include T

    create n x_min x_max intervals creates a polydivision of the interval
    from x_min to x_max described by the list of intervals, filling the gaps among
    intervals and between the intervals and the outer borders with an unmapped
    divisions with n bins each.

    val create : ?bias : (float → float) →
      (int × M.t) list → int → float → float → t

  end

module Make_Poly (M : Diffmaps.Real) : Poly with module M = M

module Poly : Poly
```

A.13 Implementation of *Division*

```
open Printf

let epsilon_100 = 100.0 *. Float.Double.epsilon

let equidistant n x_min x_max =
  if n ≤ 0 then
    invalid_arg "Division.equidistant: n ≤ 0"
  else
    let delta = (x_max -. x_min) /. (float n) in
    Array.init (n + 1) (fun i → x_min +. delta *. float i)

exception Out_of_range of float × (float × float)
exception Rebinning_failure of string
```

```

let find_raw d x =
  let n_max = Array.length d - 1 in
  let eps = epsilon_100 *. (d.(n_max) - . d.(0)) in
  let rec find' a b =
    if b ≤ a + 1 then
      a
    else
      let m = (a + b) / 2 in
      if x < d.(m) then
        find' a m
      else
        find' m b in
  if x < d.(0) - . eps ∨ x > d.(n_max) + . eps then
    raise (Out_of_range (x, (d.(0), d.(n_max))))
  else if x ≤ d.(0) then
    0
  else if x ≥ d.(n_max) then
    n_max - 1
  else
    find' 0 n_max
module type T =
sig
  type t
  val copy : t → t
  val find : t → float → int
  val record : t → float → float → unit
  val rebin : ?power : float → ?fixed_min : bool → ?fixed_max : bool →
t → t
  val caj : t → float → float
  val n_bins : t → int
  val bins : t → float array
  val to_channel : out_channel → t → unit
  val as_block_data_to_channel : out_channel →
string → int → int → t → unit
end

```

A.13.1 Primary Divisions

```

module type Mono =

```

```

sig
  include T
  val create : ?bias : (float → float) → int → float → float → t
end

module Mono (* : T *) =
  struct
    type t =
      { x : float array;
        mutable x_min : float;
        mutable x_max : float;
        n : int array;
        w : float array;
        w2 : float array;
        bias : float → float }

    let copy d =
      { x = Array.copy d.x;
        x_min = d.x_min;
        x_max = d.x_max;
        n = Array.copy d.n;
        w = Array.copy d.w;
        w2 = Array.copy d.w2;
        bias = d.bias }

    let create ?(bias = fun x → 1.0) n x_min x_max =
      { x = equidistant n x_min x_max;
        x_min = x_max;
        x_max = x_min;
        n = Array.create n 0;
        w = Array.create n 0.0;
        w2 = Array.create n 0.0;
        bias = bias }

    let bins d = d.x
    let n_bins d = Array.length d.x - 1
    let find d = find_raw d.x

    let normal_float x =
      match classify_float x with
      | FP_normal | FP_subnormal | FP_zero → true
      | FP_infinite | FP_nan → false
  end

```



```

let report_denormal x f b what =
  eprintf
    "circe2: Division.record: ignoring %s (x=%g, f=%g, b=%g)\n"
    what x f b;
  flush stderr
let caj d x = 1.0
let record d x f =
  if x < d.x_min then
    d.x_min ← x;
  if x > d.x_max then
    d.x_max ← x;
  let i = find d x in
  d.n.(i) ← succ d.n.(i);
  let b = d.bias x in
  let w = f *. b in
  match classify_float w with
  | FP_normal | FP_subnormal | FP_zero →
    d.w.(i) ← d.w.(i) +. w;
    let w2 = f *. w in
    begin match classify_float w2 with
    | FP_normal | FP_subnormal | FP_zero →
      d.w2.(i) ← d.w2.(i) +. w2
    | FP_infinite → report_denormal x f b "w2=[inf]"
    | FP_nan → report_denormal x f b "w2=[nan]"
    end
  | FP_infinite → report_denormal x f b "w2=[inf]"
  | FP_nan → report_denormal x f b "w2=[nan]"

```

$$\begin{aligned}
d_1 &\rightarrow \frac{1}{2}(d_1 + d_2) \\
d_2 &\rightarrow \frac{1}{3}(d_1 + d_2 + d_3) \\
&\dots \\
d_{n-1} &\rightarrow \frac{1}{3}(d_{n-2} + d_{n-1} + d_n) \\
d_n &\rightarrow \frac{1}{2}(d_{n-1} + d_n)
\end{aligned} \tag{76}$$

```

let smooth3 f =
  match Array.length f with
  | 0 → f
  | 1 → Array.copy f
  | 2 → Array.create 2 ((f.(0) + . f.(1)) /. 2.0)
  | n →
    let f' = Array.create n 0.0 in
    f'.(0) ← (f.(0) + . f.(1)) /. 2.0;
    for i = 1 to n - 2 do
      f'.(i) ← (f.(i - 1) + . f.(i) + . f.(i + 1)) /. 3.0
    done;
    f'.(n - 1) ← (f.(n - 2) + . f.(n - 1)) /. 2.0;
    f'

```

$$m_i = \left(\frac{\frac{\bar{f}_i \Delta x_i}{\sum_j \bar{f}_j \Delta x_j} - 1}{\ln \left(\frac{\bar{f}_i \Delta x_i}{\sum_j \bar{f}_j \Delta x_j} \right)} \right)^\alpha \quad (77)$$

```

let rebinning_weights' power fs =
  let sum_f = Array.fold_left (+.) 0.0 fs in
  if sum_f ≤ 0.0 then
    Array.create (Array.length fs) 1.0
  else
    Array.map (fun f →
      let f' = f /. sum_f in
      if f' < 1.0 · 10-12 then
        0.
      else
        ((f' - . 1.0) /. (log f')) ** power) fs

```

The nested loops can be turned into recursions, of course. But arrays aren't purely functional anyway ...

```

let rebin' m x =
  let n = Array.length x - 1 in
  let x' = Array.create (n + 1) 0.0 in
  let sum_m = Array.fold_left (+.) 0.0 m in
  if sum_m ≤ 0.0 then
    Array.copy x
  else begin
    let step = sum_m /. (float n) in
    let k = ref 0

```

```

and  $\Delta = \text{ref } 0.0$  in
 $x'.(0) \leftarrow x.(0)$ ;
for  $i = 1$  to  $n - 1$  do

```

We increment k until another Δ (a. k. a. *step*) of the integral has been accumulated (cf. figure ??).

```

while  $\Delta < \text{step}$  do
    incr  $k$ ;
     $\Delta := \Delta + .m.(k - 1)$ 
done;

```

Correct the mismatch.

```

 $\Delta := \Delta - .\text{step}$ ;

```

Linearly interpolate the next bin boundary.

```

 $x'.(i) \leftarrow x.(k) - (x.(k) - x.(k - 1)) * \Delta / .m.(k - 1)$ ;

```

```

if  $x'.(i) < x'.(i - 1)$  then

```

```

    raise (Rebinning_failure

```

```

        (sprintf "x(%d)=%g<=%gx(%d)=%g" i x'.(i) (i-1) x'.(i-

```

```

1)))

```

```

done;

```

```

 $x'.(n) \leftarrow x.(n)$ ;

```

```

 $x'$ 

```

```

end

```



Check that x_{min} and x_{max} are implemented correctly!!!!



One known problem is that the second outermost bins hinder the outermost bins from moving.

```

let rebin ?(power = 1.5) ?(fixed_min = false) ?(fixed_max = false) d =
  let n = Array.length d.w in
  let x = rebin' (rebinning_weights' power (smooth3 d.w2)) d.x in
  if ¬ fixed_min then
    x.(0) ← (x.(0) + . min d.x_min x.(1)) /. 2.;
  if ¬ fixed_max then
    x.(n) ← (x.(n) + . max d.x_max x.(n - 1)) /. 2.;
  { x = x;
    x_min = d.x_min;
    x_max = d.x_max;
    n = Array.create n 0;
    w = Array.create n 0.0;
    w2 = Array.create n 0.0;
    bias = d.bias }

let to_channel oc d =
  Array.iter (fun x →
    fprintf oc "%s0100011\n" (Float.Double.to_string x)) d.x

let as_block_data_to_channel oc name n_ch n_beam d =
  for i = 0 to Array.length d.x - 1 do
    fprintf oc "data_%s(%d,%d,%d)/%s\n"
      name i n_ch n_beam (Float.Double.to_string d.x.(i))
  done
end

```

A.13.2 Polydivisions

```

module type Poly =
sig
  module M : Diffmaps.Real
  include T
  val create : ?bias : (float → float) →
    (int × M.t) list → int → float → float → t
end

module Make_Poly (M : Diffmaps.Real) (* : Poly *) =
struct
  module M = M

```

```

type t =
  { x : float array;
    d : Mono.t array;
    n_bins : int;
    ofs : int array;
    maps : M.t array;
    n : int array;
    w : float array;
    w2 : float array }

let copy pd =
  { x = Array.copy pd.x;
    d = Array.map Mono.copy pd.d;
    n_bins = pd.n_bins;
    ofs = Array.copy pd.ofs;
    maps = Array.copy pd.maps;
    n = Array.copy pd.n;
    w = Array.copy pd.w;
    w2 = Array.copy pd.w2 }

let n_bins pd = pd.n_bins

let find pd y =
  let i = find_raw pd.x y in
  let x = M.ihp pd.maps.(i) y in
  pd.ofs.(i) + Mono.find pd.d.(i) x

let bins pd =
  let a = Array.create (pd.n_bins + 1) 0.0 in
  let bins0 = Mono.bins pd.d.(0) in
  let len = Array.length bins0 in
  Array.blit bins0 0 a 0 len;
  let ofs = ref len in
  for i = 1 to Array.length pd.d - 1 do
    let len = Mono.n_bins pd.d.(i) in
    Array.blit (Mono.bins pd.d.(i)) 1 a !ofs len;
    ofs := !ofs + len
  done;
  a

type interval =
  { nbin : int;
    x_min : float;
    x_max : float;

```

```

    map : M.t }

let interval nbin map =
  { nbin = nbin;
    x_min = M.x_min map;
    x_max = M.x_max map;
    map = map }

let id_map n y_min y_max =
  interval n (M.id ~x_min : y_min ~x_max : y_max y_min y_max)

let sort_intervals intervals =
  List.sort (fun i1 i2 → compare i1.x_min i2.x_min) intervals

Fill the gaps between adjacent intervals, using val default : int → float → float → interval to construct intermediate intervals.

let fill_gaps default n x_min x_max intervals =
  let rec fill_gaps' prev_x_max acc = function
    | i :: rest →
      if i.x_min = prev_x_max then
        fill_gaps' i.x_max (i :: acc) rest
      else if i.x_min > prev_x_max then
        fill_gaps' i.x_max
          (i :: (default n prev_x_max i.x_min) :: acc) rest
      else
        invalid_arg "Polydivision.fill_gaps:␣overlapping"
    | [] →
      if x_max = prev_x_max then
        List.rev acc
      else if x_max > prev_x_max then
        List.rev (default n prev_x_max x_max :: acc)
      else
        invalid_arg "Polydivision.fill_gaps:␣sticking␣out"
  in match intervals with
  | i :: rest →
    if i.x_min = x_min then
      fill_gaps' i.x_max [i] rest
    else if i.x_min > x_min then
      fill_gaps' i.x_max (i :: [default n x_min i.x_min]) rest
    else
      invalid_arg "Polydivision.fill_gaps:␣sticking␣out"
  | [] → [default n x_min x_max]

```

```

let create ?bias intervals n x_min x_max =
  let intervals = List.map (fun (n, m) → interval n m) intervals in
  match fill_gaps id_map n x_min x_max (sort_intervals intervals) with
  | [] → failwith "Division.Poly.create: impossible"
  | interval :: _ as intervals →
    let ndiv = List.length intervals in
    let x = Array.of_list (interval.x_min ::
                          List.map (fun i → i.x_max) intervals) in
    let d = Array.of_list
      (List.map (fun i →
        Mono.create ?bias i.nbin i.x_min i.x_max) intervals) in
    let ofs = Array.create ndiv 0 in
    for i = 1 to ndiv - 1 do
      ofs.(i) ← ofs.(i - 1) + Mono.n_bins d.(i - 1)
    done;
    let n_bins = ofs.(ndiv - 1) + Mono.n_bins d.(ndiv - 1) in
    { x = x;
      d = d;
      n_bins = n_bins;
      ofs = ofs;
      maps = Array.of_list (List.map (fun i → i.map) intervals);
      n = Array.create ndiv 0;
      w = Array.create ndiv 0.0;
      w2 = Array.create ndiv 0.0 }

```

We can safely assume that $\text{find_raw } pd.x \ y = \text{find_raw } pd.x \ x$.

$$w = \frac{f}{\frac{dx}{dy}} = f \cdot \frac{dy}{dx} \quad (78)$$

Here, the jacobian make no difference for the final result, but it steers VEGAS/VAMP into the right direction.

```

let caj pd y =
  let i = find_raw pd.x y in
  let m = pd.maps.(i)
  and d = pd.d.(i) in
  let x = M.ihp m y in
  M.caj m y *. Mono.caj d x

```

```

let record pd y f =
  let i = find_raw pd.x y in
  let m = pd.maps.(i) in
  let x = M.ihp m y in
  let w = M.jac m x *. f in
  Mono.record pd.d.(i) x w;
  pd.n.(i) ← succ pd.n.(i);
  pd.w.(i) ← pd.w.(i) +. w;
  pd.w2.(i) ← pd.w2.(i) +. w *. w

```

Rebin the divisions, enforcing fixed boundaries for the inner intervals.

```

let rebin ?(power = 1.5) ?(fixed_min = false) ?(fixed_max = false) pd =
  let ndiv = Array.length pd.d in
  let rebin_mono i d =
    if ndiv ≤ 1 then
      Mono.rebin ~power ~fixed_min ~fixed_max d
    else if i = 0 then
      Mono.rebin ~power ~fixed_min ~fixed_max :true d
    else if i = ndiv - 1 then
      Mono.rebin ~power ~fixed_min :true ~fixed_max d
    else
      Mono.rebin ~power ~fixed_min :true ~fixed_max :true d in
  { x = Array.copy pd.x;
    d = Array.init ndiv (fun i → rebin_mono i pd.d.(i));
    n_bins = pd.n_bins;
    ofs = pd.ofs;
    maps = Array.copy pd.maps;
    n = Array.create ndiv 0;
    w = Array.create ndiv 0.0;
    w2 = Array.create ndiv 0.0 }

let to_channel oc pd =
  for i = 0 to Array.length pd.d - 1 do
    let map = M.encode pd.maps.(i)
    and bins = Mono.bins pd.d.(i)
    and j0 = if i = 0 then 0 else 1 in
    for j = j0 to Array.length bins - 1 do
      fprintf oc "%s%s\n" (Float.Double.to_string bins.(j)) map;
    done
  done

```



```

let as_block_data_to_channel oc tag n_ch n_beam pd =
  let k = ref 0 in
  for i = 0 to Array.length pd.d - 1 do
    let bins = Mono.bins pd.d.(i)
    and j0 = if i = 0 then 0 else 1 in
    for j = j0 to Array.length bins - 1 do
      fprintf oc "~~~~~data_bdx%s(%d,%d,%d)_/%s/\n"
        tag !k n_ch n_beam (Float.Double.to_string bins.(j));
      M.as_block_data_to_channel pd.maps.(i) oc tag !k n_ch n_beam;
      incr k
    done
  done
end

module Poly = Make_Poly (Diffmaps.Default)

```

A.14 Interface of *Grid*

```

module type T =
  sig
    module D : Division.T

    type t
    val copy : t → t

    Create an initial grid.

    val create : ?triangle:bool → D.t → D.t → t

    record grid x1 x2 w records the value w in the bin corresponding to
    coordinates x1 and x2.

    val record : t → float → float → float → unit

    VEGAS style rebinning.

    val rebin : ?power:float →
      ?fixed_x1_min:bool → ?fixed_x1_max:bool →
      ?fixed_x2_min:bool → ?fixed_x2_max:bool → t → t

    The sum of all the weights shall be one.

    val normalize : t → t

```

Adapt an initial grid to data. The *power* controls speed vs. stability of adaption and is passed on to *Division.rebin*. *iterations* provides a hard cutoff for the number of iterations (default: 1000), while *margin* and *cutoff*

control the soft cutoff of the adaption. If the variance grows to the best value multiplied by *margin* or if there are no improvements for *cutoff* steps, the adaption is stopped (defaults: 1.5 and 20). The remaining options control if the boundaries are fixed or allowed to move towards the limits of the dataset. The defaults are all **false**, meaning that the boundaries are allowed to move.

```
val of_bigarray : ?verbose:bool → ?power:float →
  ?iterations:int → ?margin:float → ?cutoff:int →
  ?fixed_x1_min:bool → ?fixed_x1_max:bool →
  ?fixed_x2_min:bool → ?fixed_x2_max:bool →
  (float, Bigarray.float64_elt,
   Bigarray.fortran_layout) Bigarray.Array2.t → t → t
```

Write output that Circe2 can read:

```
type channel =
  { pid1 : int;
    pol1 : int;
    pid2 : int;
    pol2 : int;
    lumi : float;
    g : t }

val to_channel : out_channel → channel → unit

type design =
  { name : string;
    roots : float;
    channels : channel list;
    comments : string list }

val design_to_channel : out_channel → design → unit
val designs_to_channel : out_channel →
  ?comments:string list → design list → unit
val designs_to_file : string →
  ?comments:string list → design list → unit

val design_as_block_data_to_channel :
  out_channel → int × design → unit
val designs_as_block_data_to_channel :
  out_channel → ?comments:string list → (int × design) list →
unit
val designs_as_block_data_to_file :
  string → ?comments:string list → (int × design) list → unit
val variance : t → float
```

```

end

module Make (D : Division.T) : T with module D = D

```

A.15 Implementation of *Grid*

```

open Printf

module type T =
  sig
    module D : Division.T

    type t
    val copy : t → t

    val create : ?triangle : bool → D.t → D.t → t

    val record : t → float → float → float → unit

    val rebin : ?power : float →
      ?fixed_x1_min : bool → ?fixed_x1_max : bool →
      ?fixed_x2_min : bool → ?fixed_x2_max : bool → t → t

    val normalize : t → t

    val of_bigarray : ?verbose : bool → ?power : float →
      ?iterations : int → ?margin : float → ?cutoff : int →
      ?fixed_x1_min : bool → ?fixed_x1_max : bool →
      ?fixed_x2_min : bool → ?fixed_x2_max : bool →
      (float, Bigarray.float64_elt,
       Bigarray.fortran_layout) Bigarray.Array2.t → t → t

    type channel =
      { pid1 : int;
        pol1 : int;
        pid2 : int;
        pol2 : int;
        lumi : float;
        g : t }

    val to_channel : out_channel → channel → unit

    type design =
      { name : string;
        roots : float;
        channels : channel list;
        comments : string list }

```

```

val design_to_channel : out_channel → design → unit
val designs_to_channel : out_channel →
  ?comments : string list → design list → unit
val designs_to_file : string →
  ?comments : string list → design list → unit
val design_as_block_data_to_channel :
  out_channel → int × design → unit
val designs_as_block_data_to_channel :
  out_channel → ?comments : string list → (int × design) list →
unit
val designs_as_block_data_to_file :
  string → ?comments : string list → (int × design) list → unit
val variance : t → float
end

module Make (D : Division.T) =
struct
  module D = D
  type t =
    { d1 : D.t;
      d2 : D.t;
      w : float array;
      var : float array;
      triangle : bool }
  let copy grid =
    { d1 = D.copy grid.d1;
      d2 = D.copy grid.d2;
      w = Array.copy grid.w;
      var = Array.copy grid.var;
      triangle = grid.triangle }
  let create ?(triangle = false) d1 d2 =
    let n = D.n_bins d1 × D.n_bins d2 in
    { d1 = d1;
      d2 = d2;
      w = Array.create n 0.0;
      var = Array.create n 0.0;
      triangle = triangle }

```

Here's the offset-0 variant of the offset-1 Fortran code:

```

let find grid x y =
  D.find grid.d1 x + D.n_bins grid.d1 × D.find grid.d2 y

```

```

let project_triangle triangle x y =
  if triangle then begin
    if x ≥ y then begin
      (x, y /. x)
    end else begin
      (y, x /. y)
    end
  end else
    (x, y)

```

Note that there is *no* jacobian here. It is applied by Fortran program interpreting the grid as distribution. It is not needed for the event generator anyway.

```

let record grid x y f =
  let x', y' = project_triangle grid.triangle x y in
  D.record grid.d1 x' f;
  D.record grid.d2 y' f;
  let n = find grid x' y' in
  grid.w.(n) ← grid.w.(n) + . f;
  grid.var.(n) ← grid.var.(n) + . f /. D.caj grid.d1 x' /. D.caj grid.d2 y'

let rebin ?power ?fixed_x1_min ?fixed_x1_max
  ?fixed_x2_min ?fixed_x2_max grid =
  let n = D.n_bins grid.d1 × D.n_bins grid.d2 in
  { d1 = D.rebin ?power
    ?fixed_min : fixed_x1_min ?fixed_max : fixed_x1_max grid.d1;
    d2 = D.rebin ?power
    ?fixed_min : fixed_x2_min ?fixed_max : fixed_x2_max grid.d2;
    w = Array.create n 0.0;
    var = Array.create n 0.0;
    triangle = grid.triangle }

let normalize grid =
  let sum_w = Array.fold_left (+.) 0.0 grid.w in
  { d1 = D.copy grid.d1;
    d2 = D.copy grid.d2;
    w = Array.map (fun w → w /. sum_w) grid.w;
    var = Array.copy grid.var;
    triangle = grid.triangle }

```

Monitoring the variance in each cell is *not* a good idea for approximating distributions of unweighted events: it always vanishes for unweighted events,

even if they are distributed very unevenly. Therefore, we monitor the *global* variance instead:

```

let variance grid =
  let n = float (Array.length grid.w) in
  let w = Array.fold_left (+.) 0.0 grid.w /. n
  and w2 = Array.fold_left (fun acc w → acc +. w *. w) 0.0 grid.w /. n in
  w2 -. w *. w

let variance grid =
  let n = float (Array.length grid.var) in
  let w = Array.fold_left (+.) 0.0 grid.var /. n
  and w2 = Array.fold_left (fun acc w → acc +. w *. w) 0.0 grid.var /. n in
  w2 -. w *. w

```

Find the grid with the lowest variance. Allow local fluctuations and stop only after moving to twice the lowest value.

```

let start_progress_report verbose var =
  if verbose then begin
    eprintf "adapting variance: %g" var;
    flush stderr
  end

let progress_report verbose soft_limit best_var var =
  if verbose then begin
    if var < best_var then begin
      eprintf ", %g" var;
      flush stderr
    end else begin
      eprintf "[%d]" soft_limit;
      flush stderr
    end
  end

let stop_progress_report verbose =
  if verbose then begin
    eprintf "\ndone.\n";
    flush stderr
  end

```

The main routine constructing an adapted grid.

```

let of_bigarray ?(verbose = false)
  ?power ?(iterations = 1000) ?(margin = 1.5) ?(cutoff = 10)
  ?fixed_x1_min ?fixed_x1_max ?fixed_x2_min ?fixed_x2_max data initial =

```

```

let record_data grid =
  for i2 = 1 to Bigarray.Array2.dim2 data do
    let x = Bigarray.Array2.get data 1 i2
    and y = Bigarray.Array2.get data 2 i2
    and w = Bigarray.Array2.get data 3 i2 in
    try
      record grid x y w
    with
      | Division.Out_of_range (x, (x_min, x_max)) →
        eprintf "internal_error: %g not in [%g,%g]\n" x x_min x_max
  done in

let rebinner grid =
  rebin ?power
    ?fixed_x1_min ?fixed_x1_max ?fixed_x2_min ?fixed_x2_max grid in

let rec improve_bigarray hard_limit soft_limit best_var best_grid grid =
  if soft_limit ≤ 0 ∨ hard_limit ≤ 0 then
    normalize best_grid
  else begin
    record_data grid;
    let var = variance grid in
    progress_report verbose soft_limit best_var var;
    if var ≥ margin *. best_var then
      normalize best_grid
    else
      let best_var, best_grid, soft_limit =
        if var < best_var then
          (var, grid, cutoff)
        else
          (best_var, best_grid, pred soft_limit) in

```

Continuation passing makes recursion with exception handling tail recursive. This is not really needed, because the data structures are not too big and recursion is not expected to be too deep. It doesn't hurt either, since the idiom is sufficiently transparent.

```

let continue =
  try
    let grid' = rebinner grid in
    fun () → improve_bigarray
      (pred hard_limit) soft_limit best_var best_grid grid'
  with

```

```

        | Division.Rebinning_failure msg →
            eprintf "circe2:▯rebinning▯failed:▯%s!\n" msg;
            fun () → best_grid in
        continue ()
    end in

record_data initial;
let var = variance initial in
start_progress_report verbose var;

let result =
    improve_bigarray iterations cutoff var initial (rebinner initial) in
stop_progress_report verbose;
result

type channel =
    { pid1 : int;
      pol1 : int;
      pid2 : int;
      pol2 : int;
      lumi : float;
      g : t }

let to_channel oc ch =
    fprintf oc "pid1,▯pol1,▯pid2,▯pol2,▯lumi\n";
    fprintf oc "▯%d▯%d▯%d▯%d▯%G\n"
        ch.pid1 ch.pol1 ch.pid2 ch.pol2 ch.lumi;
    fprintf oc "#bins1,▯#bins2,▯triangle?\n";
    fprintf oc "▯%d▯%d▯%s\n"
        (D.n_bins ch.g.d1) (D.n_bins ch.g.d2)
        (if ch.g.triangle then "T" else "F");
    fprintf oc "x1,▯map1,▯alpha1,▯xi1,▯eta1,▯a1,▯b1\n";
    D.to_channel oc ch.g.d1;
    fprintf oc "x2,▯map2,▯alpha2,▯xi2,▯eta2,▯a2,▯b2\n";
    D.to_channel oc ch.g.d2;
    fprintf oc "weights\n";
    Array.iter (fun x →
        fprintf oc "▯%s\n" (Float.Double.to_string x)) ch.g.w

let as_block_data_to_channel oc n_beam n_ch ch =
    let print_integer name value =
        fprintf oc "▯▯▯▯▯▯data▯bd%s(%d,%d)▯/%d/\n" name n_ch n_beam value
    and print_float name value =
        fprintf oc "▯▯▯▯▯▯data▯bd%s(%d,%d)▯/%s/\n"

```



```

        name n_ch n_beam (Float.Double.to_string value)
and print_string name value =
    fprintf oc "UUUUUUdata_bds(%d,%d)_/'%s'/\n" name n_ch n_beam value
and print_logical name value =
    fprintf oc "UUUUUUdata_bds(%d,%d)_/%s/\n"
        name n_ch n_beam (if value then ".true." else ".false.") in
print_integer "pid1" ch.pid1;
print_integer "pol1" ch.pol1;
print_integer "pid2" ch.pid2;
print_integer "pol2" ch.pol2;
print_float "lumi" ch.lumi;
print_integer "nb1" (D.n_bins ch.g.d1);
print_integer "nb2" (D.n_bins ch.g.d2);
print_logical "tria" ch.g.triangle;
D.as_block_data_to_channel oc "1" n_ch n_beam ch.g.d1;
D.as_block_data_to_channel oc "2" n_ch n_beam ch.g.d2;
()

type design =
    { name : string;
      roots : float;
      channels : channel list;
      comments : string list }

type polarization_support =
    | Averaged
    | Helicities
    | Density_Matrices

let polarization_support design =
    if List.for_all (fun ch → ch.pol1 = 0 ∧ ch.pol2 = 0)
        design.channels then
        Averaged
    else if List.for_all (fun ch → ch.pol1 ≠ 0 ∧ ch.pol2 ≠ 0)
        design.channels then
        Helicities
    else
        invalid_arg
            "Grid.polarization_support:_mixed_polarization_support!"

let format_polarization_support = function
    | Averaged → "averaged"
    | Helicities → "helicities"

```

```

| Density_Matrices → "density_matrices"

let getlogin () =
  (Unix.getpwuid (Unix.getuid ())).Unix.pw_name

let design_to_channel oc design =
  let utc = Unix.gmtime (Unix.time ()) in
  List.iter (fun s → fprintf oc "!%s\n" s) design.comments;
  fprintf oc "!generated with %s by %s@%s, "
    (Sys.argv.(0)) (getlogin ()) (Unix.gethostname ());
  fprintf oc "%4.4d/%2.2d/%2.2d %2.2d:%2.2d:%2.2d GMT\n"
    (utc.Unix.tm_year + 1900) (utc.Unix.tm_mon + 1) utc.Unix.tm_mday
    utc.Unix.tm_hour utc.Unix.tm_min utc.Unix.tm_sec;
  fprintf oc "CIRCE2_FORMAT#1\n";
  fprintf oc "design, roots\n";
  fprintf oc "%s' %G\n" design.name design.roots;
  fprintf oc "#channels, pol.support\n";
  fprintf oc "%d' %s'\n"
    (List.length design.channels)
    (format_polarization_support (polarization_support design));
  List.iter (to_channel oc) design.channels;
  fprintf oc "ECRIC2\n"

let design_as_block_data_to_channel oc (n_design, design) =
  let utc = Unix.gmtime (Unix.time ()) in
  List.iter (fun s → fprintf oc "c_%s\n" s) design.comments;
  fprintf oc "c_generated with %s by %s@%s, "
    (Sys.argv.(0)) (Unix.getlogin ()) (Unix.gethostname ());
  fprintf oc "%4.4d/%2.2d/%2.2d %2.2d:%2.2d:%2.2d GMT\n"
    (utc.Unix.tm_year + 1900) (utc.Unix.tm_mon + 1) utc.Unix.tm_mday
    utc.Unix.tm_hour utc.Unix.tm_min utc.Unix.tm_sec;
  fprintf oc "UUUUUUdata_bddsgn(%d)UU/'%s'/\n" n_design design.name;
  fprintf oc "UUUUUUdata_bdbrs(%d)UU/%G/\n" n_design design.roots;
  fprintf oc "UUUUUUdata_bdnc(%d)UUU/%d/\n"
    n_design (List.length design.channels);
  let _ =
    List.fold_left (fun n_ch ch →
      as_block_data_to_channel oc n_design n_ch ch;
      succ n_ch) 1 design.channels in
  ()

let designs_to_channel oc ?(comments = []) designs =
  List.iter (fun c → fprintf oc "!%s\n" c) comments;

```

```

    List.iter (design_to_channel oc) designs
let designs_as_block_data_to_channel oc ?(comments = []) designs =
  List.iter (fun c → fprintf oc "%s\n" c) comments;
  List.iter (design_as_block_data_to_channel oc) designs
let designs_to_file name ?comments designs =
  let oc = open_out name in
  designs_to_channel oc ?comments designs;
  close_out oc
let designs_as_block_data_to_file name ?comments designs =
  let oc = open_out name in
  designs_as_block_data_to_channel oc ?comments designs;
  close_out oc
end

```

A.16 Interface of *Events*

We’re dealing with Fortran style `DOUBLE PRECISION` arrays exclusively.

```

type t =
  (float, Bigarray.float64_elt, Bigarray.fortran_layout) Bigarray.Array2.t

```

Read an ASCII representation of a big array from a channel or a file. The array is read in pieces of *chunk* columns each; the default value for *chunk* is 100000. The number of rows is given by the integer argument, while the number of columns is determined by the number of lines in the file. If the *file* argument is present the resulting bigarray is mapped to a file.

```

val of_ascii_channel : ?file:string → ?chunk:int → int → in_channel → t
val of_ascii_file : ?file:string → ?chunk:int → int → string → t

```

Map a file containing a binary representation of a big array. The number of rows is again given by the argument and the number of columns is determined by the size of the file. The first version does a read-only (or rather copy-on-write) map, while the second version allows modifications.

```

val of_binary_file : int → string → t
val shared_map_binary_file : int → string → t

```

Selfexplaining, hopefully ...

```

val to_ascii_channel : out_channel → t → unit
val to_ascii_file : string → t → unit
val to_binary_file : string → t → unit

```

Utilities for reading ASCII representations.

```
val lexer : char Stream.t → Genlex.token Stream.t
val next_float : Genlex.token Stream.t → float
```

A.17 Implementation of *Events*

A.17.1 Reading Bigarrays

Reading big arrays efficiently is not trivial, if we don't know the size of the arrays beforehand. Here we use the brute force approach of reading a list of not-so-big arrays and blitting them into the resulting array later. This avoids a second reading of the file, but temporarily needs twice the memory.

```
open Bigarray
open Printf

type t = (float, float64_elt, fortran_layout) Array2.t
exception Incomplete of int × t
```

Read lines from a channel into the columns of a bigarray. If the file turns out to be short, the exception *Incomplete* (*i2*, *array*) is raised with the number of columns actually read.

```
let read_lines ic reader array i2_first i2_last =
  let i2 = ref i2_first in
  try
    while !i2 ≤ i2_last do
      reader array !i2 (input_line ic);
      incr i2
    done
  with
  | End_of_file → raise (Incomplete (pred !i2, array))
```

Decode a line of floating point numbers into a column of a bigarray.

Fortran allows 'd' and 'D' as exponent starter, but O'Caml's *Genlex* doesn't accept it.

```
let normalize_ascii_floats orig =
  let normalized = String.copy orig in
  for i = 0 to String.length normalized - 1 do
    let c = normalized.[i] in
    if c = 'd' ∨ c = 'D' then
      normalized.[i] ← 'E'
  done;
  normalized
```

```

let lexer = Genlex.make_lexer []

let next_float s =
  match Stream.next s with
  | Genlex.Int n → float n
  | Genlex.Float x → x
  | _ → invalid_arg "Events.int_as_float"

let read_floats array i2 line =
  let tokens = lexer (Stream.of_string (normalize_ascii_floats line)) in
  for i1 = 1 to Array2.dim1 array do
    Array2.set array i1 i2 (next_float tokens)
  done

```

Try to read the columns of a bigarray from a channel. If the file turns out to be short, the exception *Incomplete* (*dim2*, *array*) is raised with the number of columns actually read.

```

let try_of_ascii_channel dim1 dim2 ic =
  let array = Array2.create float64 fortran_layout dim1 dim2 in
  read_lines ic read_floats array 1 dim2;
  (dim2, array)

```

Read a *dim1* floating point numbers per line into the columns of a reverted list of bigarrays, each with a maximum of *chunk* columns.

```

let rev_list_of_ascii_channel chunk dim1 ic =
  let rec rev_list_of_ascii_channel' acc =
    let continue =
      try
        let acc' = try_of_ascii_channel dim1 chunk ic :: acc in
        fun () → rev_list_of_ascii_channel' acc'
      with
      | Incomplete (len, a) → fun () → (len, a) :: acc in
    continue () in
  rev_list_of_ascii_channel' []

```

Concatenate a list of bigarrays $[(l_n, a_n); \dots; (l_2, a_2); (l_1, a_1)]$ in reverse order $a_1 a_2 \dots a_n$. Of each array a_i , only the first l_i columns are used. If the optional *file* name is present, map the corresponding file to the bigarray. We can close the file descriptor immediately, since `close(2)` does *not* `munmap(2)`.

```

let create_array ?file dim1 dim2 =
  match file with
  | None → Array2.create float64 fortran_layout dim1 dim2
  | Some name →
    let fd =
      Unix.openfile name
        [Unix.O_RDWR; Unix.O_CREAT; Unix.O_TRUNC] 6448 in
    let a = Array2.map_file fd float64 fortran_layout true dim1 dim2 in
    Unix.close fd;
    a

let rev_concat ?file arrays =
  let sum_dim2 =
    List.fold_left (fun sum (dim2, _) → sum + dim2) 0 arrays in
  if sum_dim2 ≤ 0 then
    invalid_arg "Events.rev_concat";
  let dim1 = Array2.dim1 (snd (List.hd arrays)) in
  let array = create_array ?file dim1 sum_dim2 in
  let _ = List.fold_right
    (fun (dim2, a) ofs →
      Array2.blit
        (Array2.sub_right a 1 dim2) (Array2.sub_right array ofs dim2);
      ofs + dim2)
    arrays 1 in
  array

let of_ascii_channel ?file ?(chunk = 100000) dim1 ic =
  rev_concat ?file (rev_list_of_ascii_channel chunk dim1 ic)

let of_ascii_file ?file ?chunk dim1 name =
  let ic = open_in name in
  let a = of_ascii_channel ?file ?chunk dim1 ic in
  close_in ic;
  a

```

We can close the file descriptor immediately, since `close(2)` does *not* `munmap(2)`.

```

let of_binary_file dim1 file =
  let fd = Unix.openfile file [Unix.O_RDONLY] 6448 in
  let a = Array2.map_file fd float64 fortran_layout false dim1 (-1) in
  Unix.close fd;
  a

```

```

let shared_map_binary_file dim1 file =
  let fd = Unix.openfile file [Unix.O_RDWR] 6448 in
  let a = Array2.map_file fd float64 fortran_layout true dim1 (-1) in
  Unix.close fd;
  a

let to_ascii_channel oc a =
  let dim1 = Array2.dim1 a
  and dim2 = Array2.dim2 a in
  for i2 = 1 to dim2 do
    for i1 = 1 to dim1 do
      fprintf oc "␣%.17E" (Array2.get a i1 i2)
    done;
    fprintf oc "\n"
  done

let to_ascii_file name a =
  let oc = open_out name in
  to_ascii_channel oc a;
  close_out oc

let to_binary_file file a =
  let fd =
    Unix.openfile file
    [Unix.O_RDWR; Unix.O_CREAT; Unix.O_TRUNC] 6448 in
  let a' =
    Array2.map_file fd float64 fortran_layout true
    (Array2.dim1 a) (Array2.dim2 a) in
  Unix.close fd;
  Array2.blit a a'

```

A.18 Interface of *Commands*

An example for a command file:

```

{ file = "tesla.circe"
  { design = "TESLA" roots = 500
    { pid/1 = electron pid/2 = positron
      events = "tesla_500.electron_positron" }
    { pid = photon
      events = "tesla_500.gamma_gamma" }
    { pid/1 = photon pid/2 = positron
      events = "tesla_500.gamma_positron" }
  }
}

```

```

    { pid/1 = electron pid/2 = photon
      events = "tesla_500.electron_gamma" } }
  { design = "TESLA" roots = 800
    { pid/1 = electron pid/2 = positron
      events = "tesla_800.electron_positron" } }
  { design = "TESLA" roots = 500
    { pid = photon
      events = "tesla_gg_500.gamma_gamma" } }
  { design = "TESLA" roots = 500
    { pid = electron
      events = "tesla_ee_500.electron_electron" } } }

type t
val parse_file : string → t
val parse_string : string → t
val execute : t → unit
exception Parse_Error of string

```

A.19 Implementation of *Commands*

```

open Printf

module Maps = Diffmaps.Default
module Div = Division.Make_Poly (Maps)
module Grid = Grid.Make (Div)

```

A.19.1 Abstract Syntax and Default Values

A channel is uniquely specified by PDG particle ids and polarizations $\{-1, 0, +1\}$, which must match the ‘events’ in the given file; as should the luminosity. The options are for tuning the grid.

```

type channel =
  { pid1 : int;
    pol1 : int;
    pid2 : int;
    pol2 : int;
    lumi : float;
    bins1 : int;
    x1_min : float;

```



```

    x1_max : float;
    fixed_x1_min : bool;
    fixed_x1_max : bool;
    intervals1 : (int × Maps.t) list;
    bins2 : int;
    x2_min : float;
    x2_max : float;
    fixed_x2_min : bool;
    fixed_x2_max : bool;
    intervals2 : (int × Maps.t) list;
    triangle : bool;
    iterations : int;
    events : string;
    binary : bool;
    columns : int }

let default_channel =
{ pid1 = 11 (* e- *);
  pol1 = 0;
  pid2 = -11 (* e+ *);
  pol2 = 0;
  lumi = 0.0;
  bins1 = 20;
  x1_min = 0.0;
  x1_max = 1.0;
  fixed_x1_min = false;
  fixed_x1_max = false;
  intervals1 = [];
  bins2 = 20;
  x2_min = 0.0;
  x2_max = 1.0;
  fixed_x2_min = false;
  fixed_x2_max = false;
  intervals2 = [];
  triangle = false;
  iterations = 1000;
  events = "circe2.events";
  binary = false;
  columns = 3 }

```

A parameter set is uniquely specified by PDG particle ids (*par abus de lan-*
gage), polarizations (now a floating point number for the effective polariza-

tion of the beam), and center of mass energy. This must match the ‘events’ in the files given for the channels. The other options are for tuning the grid.

```
type design =
  { design : string;
    roots : float;
    design_bins1 : int;
    design_bins2 : int;
    channels : channel list;
    comments : string list }

let default_design =
  { design = "TESLA";
    roots = 500.0;
    design_bins1 = default_channel.bins1;
    design_bins2 = default_channel.bins2;
    channels = [];
    comments = [] }
```

One file can hold more than one grid.

```
type file =
  { name : string; block_data : string option; designs : design list }

let default_file =
  { name = "circe2-tool.out"; block_data = None; designs = [] }

type t = file list
```

A.19.2 Processing

```
let report msg =
  prerr_string msg;
  flush stderr

let process_channel ch =
  report ("reading:␣" ^ ch.events ^ "␣...");
  let data =
    if ch.binary then
      Events.of_binary_file ch.columns ch.events
    else
      Events.of_ascii_file 3 ch.events in
  report "␣done.\n";
  let initial_grid =
```

```

    Grid.create ~triangle : ch.triangle
      (Div.create ch.intervals1 ch.bins1 ch.x1_min ch.x1_max)
      (Div.create ch.intervals2 ch.bins2 ch.x2_min ch.x2_max) in
let grid =
  Grid.of_bigarray ~verbose :true ~iterations : ch.iterations
    ~fixed_x1_min : ch.fixed_x1_min ~fixed_x1_max : ch.fixed_x1_max
    ~fixed_x2_min : ch.fixed_x2_min ~fixed_x2_max : ch.fixed_x2_max
    data initial_grid in
{ Grid.pid1 = ch.pid1;
  Grid.pol1 = ch.pol1;
  Grid.pid2 = ch.pid2;
  Grid.pol2 = ch.pol2;
  Grid.lumi = ch.lumi;
  Grid.g = grid }

module S = Set.Make (struct type t = string let compare = compare end)

let channel_prerequisites acc ch =
  S.add ch.events acc

let process_design oc name block_data design =
  let channels = List.rev_map process_channel design.channels
  and comments = List.rev design.comments in
  let acc =
    { Grid.name = design.design;
      Grid.roots = design.roots;
      Grid.channels = channels;
      Grid.comments = comments } in
  report ("writing:␣" ^ name ^ "␣...");
  Grid.design_to_channel oc acc;
  report "␣done.\n";
  match block_data with
  | Some (oc, name, nb) →
    report ("writing:␣" ^ name ^ "␣...");
    Grid.design_as_block_data_to_channel oc (nb, acc);
    report "␣done.\n";
  | None → ()

let design_prerequisites acc design =
  List.fold_left (channel_prerequisites) acc design.channels

let write_file file =
  let oc = open_out file.name in
  begin match file.block_data with

```

```

| Some name →
  let bd_oc = open_out name in
  let _ =
    List.fold_left (fun nb design →
      process_design oc file.name (Some (bd_oc, name, nb)) design;
      succ nb) 1 file.designs in
  close_out bd_oc
| None → List.iter (process_design oc file.name None) file.designs
end;
close_out oc

let file_prerequisites acc file =
  List.fold_left (design_prerequisites) acc file.designs

let prerequisites files =
  List.fold_left (file_prerequisites) S.empty files

let unreadable name =
  try
    Unix.access name [Unix.R_OK];
    false
  with
  | Unix.Unix_error (_, _, _) → true

let execute files =
  let missing = S.filter unreadable (prerequisites files) in
  if S.is_empty missing then
    List.iter write_file files
  else
    eprintf "circe2_tool:␣unreadable␣input␣files:␣%s!\n"
      (String.concat ",␣" (S.elements missing))

```

A.19.3 Concrete syntax.

```

open Genlex

let lexer =
  Genlex.make_lexer
    ["file"; "block_data"; "events"; "binary"; "ascii"; "columns";
     "design"; "roots"; "pid"; "pol"; "unpol"; "lumi";
     "fix"; "free"; "min"; "max";
     "bins"; "triangle"; "notriangle"; "iterations";

```

```

    "electron"; "positron"; "photon"; "gamma";
    "map"; "id"; "power"; "resonance";
    "beta"; "eta"; "width"; "center";
    "comment"; "/" ; "[" ; " , " ; "]" ; "{" ; "}" ; "=" ; "*" ]

exception Parse_Error of string

let expecting s =
  raise (Parse_Error ("expecting_" ^ s))

let int_as_float = parser
  [⟨ 'Float x ⟩] → x
  | [⟨ 'Int n ⟩] → float n

let interval_cmd = parser
  | [⟨ 'Int n;
    'Kwd "["; x_min = int_as_float;
    'Kwd ","; x_max = int_as_float;
    'Kwd "]" ⟩] → (n, x_min, x_max)
  | [⟨ ⟩] → expecting "interval:_n_bins_[x_min,_x_max]"

let power_cmd (n, x_min, x_max) = parser
  | [⟨ 'Kwd "beta"; 'Kwd "="; beta = int_as_float;
    'Kwd "eta"; 'Kwd "="; eta = int_as_float ⟩] →
    if beta ≤ -1.0 then begin
      eprintf "circe2: ignoring invalid beta: %g<=-1\n" beta;
      flush stderr;
      (n, Maps.id x_min x_max)
    end else
      let alpha = 1.0 /. (1.0 +. beta) in
      (n, Maps.power ~alpha ~eta x_min x_max)
  | [⟨ ⟩] → expecting "power_map_parameters:_beta=_float_eta=_float"

let resonance_cmd (n, x_min, x_max) = parser
  | [⟨ 'Kwd "center"; 'Kwd "="; eta = int_as_float;
    'Kwd "width"; 'Kwd "="; a = int_as_float ⟩] →
    (n, Maps.resonance ~eta ~a x_min x_max)
  | [⟨ ⟩] → expecting "resonance_map_parameters:_center=_float_width=_float"

let map_cmd = parser
  | [⟨ 'Kwd "id";
    'Kwd "{"; (n, x_min, x_max) = interval_cmd; 'Kwd "}" ⟩] →
    (n, Maps.id x_min x_max)
  | [⟨ 'Kwd "power";
    'Kwd "{"; (n, x_min, x_max) = interval_cmd;

```

```

        m = power_cmd (n, x_min, x_max); 'Kwd "}" >] → m
| [⟨ 'Kwd "resonance";
    'Kwd "{"; (n, x_min, x_max) = interval_cmd;
    m = resonance_cmd (n, x_min, x_max); 'Kwd "}" >] → m
| [⟨ >] → expecting "map:␣'id',␣'power'␣or␣'resonance'"

let particle_as_int = parser
| [⟨ 'Int pid >] → pid
| [⟨ 'Kwd "electron" >] → 11
| [⟨ 'Kwd "positron" >] → -11
| [⟨ 'Kwd "photon" >] → 22
| [⟨ 'Kwd "gamma" >] → 22

let polarization_as_int = parser
| [⟨ 'Int pol >] → pol
| [⟨ 'Kwd "unpol" >] → 0
| [⟨ >] → expecting "normalized␣helicity:␣integer␣or␣'unpol'"

let polarization_as_float = parser
| [⟨ pol = int_as_float >] → pol
| [⟨ 'Kwd "unpol" >] → 0.0
| [⟨ >] → expecting "polarization:␣float␣or␣'unpol'"

type coord = X1 | X2 | X12
let coord = parser
| [⟨ 'Kwd "/" ; 'Int c >] →
    begin match c with
    | 1 → X1
    | 2 → X2
    | - →
        eprintf "circe2:␣ignoring␣dimension␣%d␣(not␣1,␣2,␣or␣*)\n" c;
        X12
    end
| [⟨ >] → X12

type side = Min | Max | Minmax
let side = parser
| [⟨ 'Kwd "min" >] → Min
| [⟨ 'Kwd "max" >] → Max
| [⟨ 'Kwd "*" >] → Minmax
| [⟨ >] → expecting "'min',␣'max'␣or␣'*'"

```

```

type channel_cmd =
| Pid of int × coord
| Pol of int × coord
| Lumi of float
| Xmin of float × coord
| Xmax of float × coord
| Bins of int × coord
| Diffmap of (int × Maps.t) × coord
| Triangle of bool
| Iterations of int
| Events of string
| Binary of bool
| Columns of int
| Fix of bool × coord × side

let channel_cmd = parser
| [⟨ 'Kwd "pid"; c = coord;
    'Kwd "="; n = particle_as_int ⟩] → Pid (n, c)
| [⟨ 'Kwd "pol"; c = coord;
    'Kwd "="; p = polarization_as_int ⟩] → Pol (p, c)
| [⟨ 'Kwd "fix"; c = coord; 'Kwd "="; s = side ⟩] → Fix (true, c, s)
| [⟨ 'Kwd "free"; c = coord; 'Kwd "="; s = side ⟩] → Fix (false, c, s)
| [⟨ 'Kwd "bins"; c = coord; 'Kwd "="; 'Int n ⟩] → Bins (n, c)
| [⟨ 'Kwd "min"; c = coord; 'Kwd "="; x = int_as_float ⟩] →
Xmin (x, c)
| [⟨ 'Kwd "max"; c = coord; 'Kwd "="; x = int_as_float ⟩] →
Xmax (x, c)
| [⟨ 'Kwd "map"; c = coord; 'Kwd "="; m = map_cmd ⟩] →
Diffmap (m, c)
| [⟨ 'Kwd "lumi"; 'Kwd "="; l = int_as_float ⟩] → Lumi l
| [⟨ 'Kwd "columns"; 'Kwd "="; 'Int n ⟩] → Columns n
| [⟨ 'Kwd "triangle" ⟩] → Triangle true
| [⟨ 'Kwd "nottriangle" ⟩] → Triangle false
| [⟨ 'Kwd "iterations"; 'Kwd "="; 'Int i ⟩] → Iterations i
| [⟨ 'Kwd "events"; 'Kwd "="; 'String s ⟩] → Events s
| [⟨ 'Kwd "binary" ⟩] → Binary true
| [⟨ 'Kwd "ascii" ⟩] → Binary false

let rec channel_cmd_list = parser
| [⟨ cmd = channel_cmd; cmd_list = channel_cmd_list ⟩] →
    cmd :: cmd_list
| [⟨ ⟩] → []

```

```

type design_cmd =
  | Design of string
  | Roots of float
  | Design_Bins of int × coord
  | Channels of channel_cmd list
  | Comment of string

let design_cmd = parser
  | [⟨ 'Kwd "bins"; c = coord; 'Kwd "="; 'Int n ⟩] → Design_Bins (n, c)
  | [⟨ 'Kwd "design"; 'Kwd "="; 'String s ⟩] → Design s
  | [⟨ 'Kwd "roots"; 'Kwd "="; x = int_as_float ⟩] → Roots x
  | [⟨ 'Kwd "{"; cmds = channel_cmd_list; 'Kwd "}" ⟩] → Channels cmds
  | [⟨ 'Kwd "comment"; 'Kwd "="; 'String c ⟩] → Comment c

let rec design_cmd_list = parser
  | [⟨ cmd = design_cmd; cmd_list = design_cmd_list ⟩] →
    cmd :: cmd_list
  | [⟨ ⟩] → []

type file_cmd =
  | File of string
  | Block_data of string
  | Designs of design_cmd list

let file_cmd = parser
  | [⟨ 'Kwd "file"; 'Kwd "="; 'String s ⟩] → File s
  | [⟨ 'Kwd "block_data"; 'Kwd "="; 'String s ⟩] → Block_data s
  | [⟨ 'Kwd "{"; cmds = design_cmd_list; 'Kwd "}" ⟩] → Designs cmds

let rec file_cmd_list = parser
  | [⟨ cmd = file_cmd; cmd_list = file_cmd_list ⟩] →
    cmd :: cmd_list
  | [⟨ ⟩] → []

let rec file_cmds = parser
  | [⟨ 'Kwd "{"; cmd = file_cmd_list; 'Kwd "}" ⟩] →
    cmd_list = file_cmds ] →
    cmd :: cmd_list
  | [⟨ ⟩] → []

type file_cmds = file_cmd list

```


A.19.4 Translate.

```
let rec update_fix acc = function
  | b, X12, s → update_fix (update_fix acc (b, X2, s)) (b, X1, s)
  | b, c, Minmax → update_fix (update_fix acc (b, c, Max)) (b, c, Min)
  | b, X1, Min → { acc with fixed_x1_min = b }
  | b, X1, Max → { acc with fixed_x1_max = b }
  | b, X2, Min → { acc with fixed_x2_min = b }
  | b, X2, Max → { acc with fixed_x2_max = b }

let rec update_pid acc = function
  | n, X12 → update_pid (update_pid acc (n, X2)) (n, X1)
  | n, X1 → { acc with pid1 = n }
  | n, X2 → { acc with pid2 = n }

let rec update_pol acc = function
  | n, X12 → update_pol (update_pol acc (n, X2)) (n, X1)
  | n, X1 → { acc with pol1 = n }
  | n, X2 → { acc with pol2 = n }

let rec update_bins acc = function
  | n, X12 → update_bins (update_bins acc (n, X2)) (n, X1)
  | n, X1 → { acc with bins1 = n }
  | n, X2 → { acc with bins2 = n }

let rec update_x_min acc = function
  | x, X12 → update_x_min (update_x_min acc (x, X2)) (x, X1)
  | x, X1 → { acc with x1_min = x }
  | x, X2 → { acc with x2_min = x }

let rec update_x_max acc = function
  | x, X12 → update_x_max (update_x_max acc (x, X2)) (x, X1)
  | x, X1 → { acc with x1_max = x }
  | x, X2 → { acc with x2_max = x }

let rec update_map acc = function
  | m, X12 → update_map (update_map acc (m, X2)) (m, X1)
  | m, X1 → { acc with intervals1 = m :: acc.intervals1 }
  | m, X2 → { acc with intervals2 = m :: acc.intervals2 }

let channel design cmds =
  List.fold_left
    (fun acc → function
      | Pid (n, c) → update_pid acc (n, c)
      | Pol (p, c) → update_pol acc (p, c)
```

```

| Lumi l → { acc with lumi = l }
| Diffmap (m, c) → update_map acc (m, c)
| Bins (n, c) → update_bins acc (n, c)
| Xmin (x, c) → update_x_min acc (x, c)
| Xmax (x, c) → update_x_max acc (x, c)
| Fix (b, c, s) → update_fix acc (b, c, s)
| Triangle b → { acc with triangle = b }
| Iterations i → { acc with iterations = i }
| Events s → { acc with events = s }
| Columns n →
  if n < 3 then
    invalid_arg "#columns_<_3"
  else
    { acc with columns = n }
| Binary b → { acc with binary = b })
default_channel cmds

let rec update_design_bins acc = function
| n, X12 → update_design_bins (update_design_bins acc (n, X2)) (n, X1)
| n, X1 → { acc with design_bins1 = n }
| n, X2 → { acc with design_bins2 = n }

let design_cmds =
  List.fold_left
    (fun acc → function
      | Design s → { acc with design = s }
      | Roots r → { acc with roots = r }
      | Design_Bins (n, c) → update_design_bins acc (n, c)
      | Channels cmds →
          { acc with channels = channel acc cmds :: acc.channels }
      | Comment c → { acc with comments = c :: acc.comments })
    default_design_cmds

let file_cmds =
  List.fold_right
    (fun cmd acc →
      match cmd with
      | File s → { acc with name = s }
      | Block_data s → { acc with block_data = Some s }
      | Designs cmds → { acc with designs = design_cmds :: acc.designs })
    cmds default_file

```

A.19.5 API

```
let parse_file name =  
  let ic = open_in name in  
  let tokens = lexer (Stream.of_channel ic) in  
  let cmds = List.map file (file_cmds tokens) in  
  close_in ic;  
  cmds  
  
let parse_string s =  
  let tokens = lexer (Stream.of_string s) in  
  List.map file (file_cmds tokens)
```

A.20 Interface of *Histogram*

```
type t  
val create : int → float → float → t  
val record : t → float → float → unit  
val normalize : t → t  
val to_channel : out_channel → t → unit  
val to_file : string → t → unit  
val as_bins_to_channel : out_channel → t → unit  
val as_bins_to_file : string → t → unit  
  
val regression : t → (float → bool) →  
  (float → float) → (float → float) → float × float
```

A.21 Implementation of *Histogram*

```
open Printf  
  
type t =  
  { n_bins : int;  
    n_bins_float : float;  
    x_min : float;  
    x_max : float;  
    x_min_eps : float;  
    x_max_eps : float;  
    mutable n_underflow : int;  
    mutable underflow : float;  
    mutable underflow2 : float;  
    mutable n_overflow : int;
```

```

    mutable overflow : float;
    mutable overflow2 : float;
    n : int array;
    w : float array;
    w2 : float array }

let create n_bins x_min x_max =
  let eps = 100. *. Float.Double.epsilon *. abs_float (x_max -. x_min) in
  { n_bins = n_bins;
    n_bins_float = float n_bins;
    x_min = x_min;
    x_max = x_max;
    x_min_eps = x_min -. eps;
    x_max_eps = x_max +. eps;
    n_underflow = 0;
    underflow = 0.0;
    underflow2 = 0.0;
    n_overflow = 0;
    overflow = 0.0;
    overflow2 = 0.0;
    n = Array.create n_bins 0;
    w = Array.create n_bins 0.0;
    w2 = Array.create n_bins 0.0 }

let record h x f =
  let i =
    truncate
      (floor (h.n_bins_float *. (x -. h.x_min) /. (h.x_max -. h.x_min))) in
  let i =
    if i < 0 ∧ x > h.x_min_eps then
      0
    else if i ≥ h.n_bins - 1 ∧ x < h.x_max_eps then
      h.n_bins - 1
    else
      i in
  if i < 0 then begin
    h.n_underflow ← h.n_underflow + 1;
    h.underflow ← h.underflow +. f;
    h.underflow2 ← h.underflow2 +. f *. f
  end else if i ≥ h.n_bins then begin
    h.n_overflow ← h.n_overflow + 1;
    h.overflow ← h.overflow +. f;

```

```

    h.overflow2 ← h.overflow2 + . f * . f
end else begin
    h.n.(i) ← h.n.(i) + 1;
    h.w.(i) ← h.w.(i) + . f;
    h.w2.(i) ← h.w2.(i) + . f * . f
end
end

let normalize h =
let sum_w = Array.fold_left (+.) (h.underflow + . h.overflow) h.w in
let sum_w2 = sum_w * . sum_w in
{ n_bins = h.n_bins;
  n_bins_float = h.n_bins_float;
  x_min = h.x_min;
  x_max = h.x_max;
  x_min_eps = h.x_min_eps;
  x_max_eps = h.x_max_eps;
  n_underflow = h.n_underflow;
  underflow = h.underflow /. sum_w;
  underflow2 = h.underflow2 /. sum_w2;
  n_overflow = h.n_overflow;
  overflow = h.overflow /. sum_w;
  overflow2 = h.overflow2 /. sum_w2;
  n = Array.copy h.n;
  w = Array.map (fun w' → w' /. sum_w) h.w;
  w2 = Array.map (fun w2' → w2' /. sum_w2) h.w2 }

let to_channel oc h =
for i = 0 to h.n_bins - 1 do
let x_mid = h.x_min
  +. (h.x_max - . h.x_min) * . (float i + . 0.5) /. h.n_bins_float in
if h.n.(i) > 1 then
let n = float h.n.(i) in
let var1 = (h.w2.(i) /. n - . (h.w.(i) /. n) ** 2.0) /. (n - . 1.0)
and var2 = h.w.(i) ** 2.0 /. (n * . (n - . 1.0)) in
let var = var2 in
fprintf oc "%17E%17E%17E\n" x_mid h.w.(i) (sqrt var)
else if h.n.(i) = 1 then
fprintf oc "%17E%17E%17E\n" x_mid h.w.(i) h.w.(i)
else
fprintf oc "%17E%17E\n" x_mid h.w.(i)
done

```

```

let as_bins_to_channel oc h =
  for i = 0 to h.n_bins - 1 do
    let x_min = h.x_min
      +. (h.x_max - . h.x_min) *. (float i) /. h.n_bins_float
    and x_max = h.x_min
      +. (h.x_max - . h.x_min) *. (float i + . 1.0) /. h.n_bins_float in
    fprintf oc "%%.17e%%%.17e\n" x_min h.w.(i);
    fprintf oc "%%.17e%%%.17e\n" x_max h.w.(i)
  done
let to_file name h =
  let oc = open_out name in
  to_channel oc h;
  close_out oc
let as_bins_to_file name h =
  let oc = open_out name in
  as_bins_to_channel oc h;
  close_out oc

```

A.22 Naive Linear Regression

```

type regression_moments =
  { mutable n : int;
    mutable x : float;
    mutable y : float;
    mutable xx : float;
    mutable xy : float }
let init_regression_moments =
  { n = 0;
    x = 0.0;
    y = 0.0;
    xx = 0.0;
    xy = 0.0 }
let record_regression m x y =
  m.n ← m.n + 1;
  m.x ← m.x + . x;
  m.y ← m.y + . y;
  m.xx ← m.xx + . x * . x;
  m.xy ← m.xy + . x * . y

```

Minimize

$$f(a, b) = \sum_i w_i (ax_i + b - y_i)^2 = \langle (ax + b - y)^2 \rangle \quad (79)$$

i. e.

$$\frac{1}{2} \frac{\partial f}{\partial a}(a, b) = \langle x(ax + b - y) \rangle = a\langle x^2 \rangle + b\langle x \rangle - \langle xy \rangle = 0 \quad (80a)$$

$$\frac{1}{2} \frac{\partial f}{\partial b}(a, b) = \langle ax + b - y \rangle = a\langle x \rangle + b - \langle y \rangle = 0 \quad (80b)$$

and

$$a = \frac{\langle xy \rangle - \langle x \rangle \langle y \rangle}{\langle x^2 \rangle - \langle x \rangle^2} \quad (81a)$$

$$b = \langle y \rangle - a\langle x \rangle \quad (81b)$$

```

let linear_regression m =
  let n = float m.n in
  let x = m.x /. n
  and y = m.y /. n
  and xx = m.xx /. n
  and xy = m.xy /. n in
  let a = (xy - . x *. y) /. (xx - . x *. x) in
  let b = y - . a *. x in
  (a, b)

let regression h chi fx fy =
  let m = init_regression_moments in
  for i = 0 to h.n_bins - 1 do
    let x_mid = h.x_min
      +. (h.x_max - . h.x_min) *. (float i +. 0.5) /. h.n_bins_float in
    if chi x_mid then
      record_regression m (fx x_mid) (fy h.w.(i))
  done;
  linear_regression m

```

A.23 Implementation of *Circe2_tool*

A.23.1 Large Numeric File I/O

```

type input_file =
  | ASCII_ic of in_channel
  | ASCII_inf of string
  | Binary_inf of string

```

```

type output_file =
  | ASCII_oc of out_channel
  | ASCII_outf of string
  | Binary_outf of string

let read_columns = function
  | ASCII_ic ic → Events.of_ascii_channel columns ic
  | ASCII_inf inf → Events.of_ascii_file columns inf
  | Binary_inf inf → Events.of_binary_file columns inf

let write_output array =
  match output with
  | ASCII_oc oc → Events.to_ascii_channel oc array
  | ASCII_outf outf → Events.to_ascii_file outf array
  | Binary_outf outf → Events.to_binary_file outf array

```

The special case of writing a binary file with mapped I/O can be treated most efficiently:

```

let cat_columns input output =
  match input, output with
  | ASCII_ic ic, Binary_outf outf →
    ignore (Events.of_ascii_channel ~file : outf columns ic)
  | -, - → write_output (read_columns input)

let map_xy fx fy columns input output =
  let a = read_columns input in
  for i2 = 1 to Bigarray.Array2.dim2 a do
    Bigarray.Array2.set a 1 i2 (fx (Bigarray.Array2.get a 1 i2));
    Bigarray.Array2.set a 2 i2 (fy (Bigarray.Array2.get a 2 i2))
  done;
  write_output a

let log10_xy = map_xy log10 log10
let exp10_xy = map_xy (fun x → 10.0 ** x) (fun y → 10.0 ** y)

```

A.23.2 Histogramming

```

let scan_string s =
  let tokens = Events.lexer (Stream.of_string s) in
  let t1 = Events.next_float tokens in
  let t2 = Events.next_float tokens in
  let t3 = Events.next_float tokens in
  (t1, t2, t3)

```



```

let histogram_ascii name histograms =
  let ic = open_in name
  and histos =
    List.map (fun (tag, f, n, x_min, x_max) →
      (tag, f, Histogram.create n x_min x_max)) histograms in
  begin try
    while true do
      let x, y, w = scan_string (input_line ic) in
      List.iter (fun (_, f, h) → Histogram.record h (f x y) w) histos
    done
  with
  | End_of_file → ()
  end;
  close_in ic;
  List.map (fun (t, _, h) → (t, h)) histos

let histogram_binary_channel ic histograms =
  let histos =
    List.map (fun (tag, f, n, x_min, x_max) →
      (tag, f, Histogram.create n x_min x_max)) histograms in
  begin try
    while true do
      let x = Float.Double.input_binary_float ic
      and y = Float.Double.input_binary_float ic
      and w = Float.Double.input_binary_float ic in
      List.iter (fun (_, f, h) → Histogram.record h (f x y) w) histos
    done
  with
  | End_of_file → ()
  end;
  List.map (fun (t, _, h) → (t, h)) histos

let histogram_binary name histograms =
  let a = Events.of_binary_file 3 name
  and histos =
    List.map (fun (tag, f, n, x_min, x_max) →
      (tag, f, Histogram.create n x_min x_max)) histograms in
  for i2 = 1 to Bigarray.Array2.dim2 a do
    let x = Bigarray.Array2.get a 1 i2
    and y = Bigarray.Array2.get a 2 i2
    and w = Bigarray.Array2.get a 3 i2 in
    List.iter (fun (_, f, h) → Histogram.record h (f x y) w) histos

```

```

done;
List.map (fun (t, _, h) → (t, h)) histos
let histogram_data to_file n reader suffix =
  let histograms = reader
    [ ("x", (fun x y → x), n, 0.0, 1.0);
      ("x_low", (fun x y → x), n, 0.0, 1.0 · 10-4);
      ("1-x_low", (fun x y → 1.0 - . x), n, 0.0, 1.0 · 10-2);
      ("1-x_low2", (fun x y → 1.0 - . x), n, 1.0 · 10-10, 1.0 · 10-2);
      ("y", (fun x y → y), n, 0.0, 1.0);
      ("y_low", (fun x y → y), n, 0.0, 1.0 · 10-4);
      ("1-y_low", (fun x y → 1.0 - . y), n, 0.0, 1.0 · 10-2);
      ("1-y_low2", (fun x y → 1.0 - . y), n, 1.0 · 10-10, 1.0 · 10-2);
      ("xy", (fun x y → x * . y), n, 0.0, 1.0);
      ("xy_low", (fun x y → x * . y), n, 0.0, 1.0 · 10-8);
      ("z", (fun x y → sqrt (x * . y)), n, 0.0, 1.0);
      ("z_low", (fun x y → sqrt (x * . y)), n, 0.0, 1.0 · 10-4);
      ("x-y", (fun x y → x - . y), n, -1.0, 1.0);
      ("x_fine", (fun x y → x), n, 0.75, 0.85);
      ("y_fine", (fun x y → y), n, 0.75, 0.85);
      ("xy_fine", (fun x y → x * . y), n, 0.5, 0.7);
      ("x-y_fine", (fun x y → x - . y), n, -0.1, 0.1) ] in
  List.iter (fun (tag, h) →
    to_file (tag ^ suffix) (Histogram.normalize h))
    histograms

```

A.23.3 Moments

```

let moments_ascii name moments =
  let ic = open_in name
  and f = Array.of_list (List.map (fun (tag, f) → f) moments)
  and m = Array.of_list (List.map (fun (tag, f) → 0.0) moments)
  and sum_w = ref 0.0 in
  begin try
    while true do
      let x, y, w = scan_string (input_line ic) in
      sum_w := !sum_w + . w;
      for i = 0 to Array.length f - 1 do
        m.(i) ← m.(i) + . w * . (f.(i) x y)
      done
    end
  end

```

```

    done
  with
  | End_of_file → ()
  end;
  close_in ic;
  List.map2 (fun (tag, f) m → (tag, m /. !sum_w)) moments (Array.to_list m)

let moments_binary name moments =
  let a = Events.of_binary_file 3 name in
  let f = Array.of_list (List.map (fun (tag, f) → f) moments)
  and m = Array.of_list (List.map (fun (tag, f) → 0.0) moments)
  and sum_w = ref 0.0 in
  for i2 = 1 to Bigarray.Array2.dim2 a do
    let x = Bigarray.Array2.get a 1 i2
    and y = Bigarray.Array2.get a 2 i2
    and w = Bigarray.Array2.get a 3 i2 in
    sum_w := !sum_w + . w;
    for i = 0 to Array.length f - 1 do
      m.(i) ← m.(i) + . w * . (f.(i) x y)
    done
  done;
  List.map2 (fun (tag, f) m → (tag, m /. !sum_w)) moments (Array.to_list m)

let fmt var = function
  | 0 → ""
  | 1 → var
  | n → var ^ "^" ^ string_of_int n

let moment nx ny =
  (fmt "x" nx ^ fmt "y" ny, (fun x y → x ** (float nx) *. y ** (float ny)))

let diff_moment n =
  (fmt "|x-y|" n, (fun x y → (abs_float (x - . y)) ** (float n)))

let moments_data reader =
  let moments = reader
    (List.map (moment 0) [1; 2; 3; 4; 5; 6] @
     List.map (moment 1) [0; 1; 2; 3; 4; 5] @
     List.map (moment 2) [0; 1; 2; 3; 4] @
     List.map (moment 3) [0; 1; 2; 3] @
     List.map (moment 4) [0; 1; 2] @
     List.map (moment 5) [0; 1] @
     List.map (moment 6) [0] @
     List.map diff_moment [1; 2; 3; 4; 5; 6]) in

```

List.iter (fun (tag, m) → Printf.printf "%s□=□%g\n" tag m) moments

A.23.4 Regression

```

let regression_interval (tag, h) (log_min, log_max) =
  let a, b =
    Histogram.regression h
    (fun x → x ≥ log_min ∧ x ≤ log_max) (fun x → x) (fun x →
log x) in
    Printf.printf "%g<%s<%g:□a□=□%g,□b□=□%g\n" log_min tag log_max a b
let intervals =
  [ (-7.0, -6.0);
    (-6.0, -5.0);
    (-5.0, -4.0);
    (-4.0, -3.0);
    (-3.0, -2.0);
    (-7.0, -5.0);
    (-6.0, -4.0);
    (-5.0, -3.0);
    (-4.0, -2.0);
    (-7.0, -4.0);
    (-6.0, -3.0);
    (-5.0, -2.0);
    (-7.0, -3.0);
    (-6.0, -2.0) ]
let intervals =
  [ (-7.0, -4.0);
    (-6.0, -3.0);
    (-7.0, -3.0);
    (-6.0, -2.0) ]
let regression_data n reader =
  let histograms = reader
    [ ("log(x1)", (fun x1 x2 → log x1), n, -8.0, 0.0);
      ("log(x2)", (fun x1 x2 → log x2), n, -8.0, 0.0) ] in
  List.iter (fun (tag, h) →
    List.iter (regression_interval (tag, h)) intervals) histograms

```

A.23.5 Visually Adapting Powermaps

```

let power_map beta eta =
  Diffmap.Power.create (1.0 /. (1.0 + . beta)) eta 0.0 1.0

let power_data to_file n center resolution reader suffix =
  let histograms = reader
    (List.flatten
      (List.map (fun p →
        let pm = power_map p 0.0 in
        let ihp = Diffmap.Power.ihp pm in
        [((Printf.sprintf "1-x_low%.2f" p), (fun x1 x2 → ihp (1.0 -
.x1))), n, 0.0, ihp 1.0 · 10-4);
        ((Printf.sprintf "1-y_low%.2f" p), (fun x1 x2 → ihp (1.0 -
.x2))), n, 0.0, ihp 1.0 · 10-4);
        ((Printf.sprintf "x_low%.2f" p), (fun x1 x2 → ihp x1), n, 0.0, ihp 1.0 ·
10-4);
        ((Printf.sprintf "y_low%.2f" p), (fun x1 x2 → ihp x2), n, 0.0, ihp 1.0 ·
10-4)]))
      [center -. 2.0 * . resolution;
        center -. resolution; center; center + . resolution;
        center + . 2.0 * . resolution])) in
  List.iter (fun (tag, h) →
    to_file (tag ^ suffix) (Histogram.normalize h)) histograms

```

A.23.6 Testing

```

let make_test_data n (x_min, x_max) (y_min, y_max) f =
  let delta_x = x_max -. x_min
  and delta_y = y_max -. y_min in
  let array =
    Bigarray.Array2.create Bigarray.float64 Bigarray.fortran_layout 3 n in
  for i = 1 to n do
    let x = x_min + . Random.float delta_x
    and y = y_min + . Random.float delta_y in
    Bigarray.Array2.set array 1 i x;
    Bigarray.Array2.set array 2 i y;
    Bigarray.Array2.set array 3 i (f x y)
  done;
  array

```

```

module Div = Division.Mono
module Grid = Grid.Make (Div)

let test_design grid =
  let channel =
    { Grid.pid1 = 22; Grid.pol1 = 0;
      Grid.pid2 = 22; Grid.pol2 = 0;
      Grid.lumi = 0.0; Grid.g = grid } in
  { Grid.name = "TEST";
    Grid.roots = 500.0;
    Grid.channels = [ channel ];
    Grid.comments = [ "unphysical_test" ] }

let test_verbose triangle shrink nbins name f =
  let data = make_test_data 100000 (0.4, 0.9) (0.2, 0.7) f in
  let initial_grid =
    Grid.create ~triangle
      (Div.create nbins 0.0 1.0)
      (Div.create nbins 0.0 1.0) in
  let grid =
    Grid.of_bigarray ~verbose
      ~fixed_x1_min : (¬ shrink) ~fixed_x1_max : (¬ shrink)
      ~fixed_x2_min : (¬ shrink) ~fixed_x2_max : (¬ shrink)
      data initial_grid in
    Grid.designs_to_file name [test_design grid]

let random_interval () =
  let x1 = Random.float 1.0
  and x2 = Random.float 1.0 in
  (min x1 x2, max x1 x2)

module Test_Power = Diffmap.Make_Test (Diffmap.Power)
module Test_Resonance = Diffmap.Make_Test (Diffmap.Resonance)

let test_maps seed =
  Random.init seed;
  let x_min, x_max = random_interval ()
  and y_min, y_max = random_interval () in
  let alpha = 1.0 +. Random.float 4.0
  and eta =
    if Random.float 1.0 > 0.5 then
      y_max +. Random.float 5.0
    else
      y_min -. Random.float 5.0 in

```

```

Test_Power.all
  (Diffmap.Power.create ~alpha ~eta ~x_min ~x_max y_min y_max);
let a = Random.float 1.0
and eta = y_min + . Random.float (y_max - . y_min) in
Test_Resonance.all
  (Diffmap.Resonance.create ~eta ~a ~x_min ~x_max y_min y_max)

```

A.23.7 Main Program

```

type format = ASCII | Binary
type action =
  | Nothing
  | Command_file of string
  | Commands of string
  | Cat
  | Histo of format × string
  | Moments of format × string
  | Regression of format × string
  | Test of string × (float → float → float)
  | Test_Diffmaps of int
  | Log10
  | Exp10
  | Power of format × string
let _ =
  let usage = "usage:␣" ^ Sys.argv.(0) ^ "␣[options]" in
  let nbins = ref 100
  and triangle = ref false
  and shrink = ref true
  and verbose = ref false
  and action = ref Nothing
  and suffix = ref ".histo"
  and input = ref (ASCII_ic stdin)
  and output = ref (ASCII_oc stdout)
  and columns = ref 3
  and block_data = ref None
  and histogram_to_file = ref Histogram.to_file
  and center = ref 0.0
  and resolution = ref 0.01 in
  Arg.parse

```

```

[("-c", Arg.String (fun s → action := Commands s), "commands");
 ("-f", Arg.String (fun f → action := Command_file f), "command_file");
 ("-ia", Arg.String (fun n → input := ASCII_inf n),
  "ASCII_input_file");
 ("-ib", Arg.String (fun n → input := Binary_inf n),
  "Binary_input_file");
 ("-oa", Arg.String (fun n → output := ASCII_outf n),
  "ASCII_output_file");
 ("-ob", Arg.String (fun n → output := Binary_outf n),
  "Binary_output_file");
 ("-cat", Arg.Unit (fun () →
  input := ASCII_ic stdin; output := ASCII_oc stdout;
  action := Cat), "copy_stdin_to_stdout");
 ("-log10", Arg.Unit (fun () →
  input := ASCII_ic stdin; output := ASCII_oc stdout;
  action := Log10), "");
 ("-exp10", Arg.Unit (fun () →
  input := ASCII_ic stdin; output := ASCII_oc stdout;
  action := Exp10), "");
 ("-ha", Arg.String (fun s → action := Histo (ASCII, s)),
  "ASCII_histogramming_tests");
 ("-hb", Arg.String (fun s → action := Histo (Binary, s)),
  "binary_histogramming_tests");
 ("-ma", Arg.String (fun s → action := Moments (ASCII, s)),
  "ASCII_moments_tests");
 ("-mb", Arg.String (fun s → action := Moments (Binary, s)),
  "binary_moments_tests");
 ("-pa", Arg.String (fun s → action := Power (ASCII, s)), "");
 ("-pb", Arg.String (fun s → action := Power (Binary, s)), "");
 ("-C", Arg.Float (fun c → center := c), "");
 ("-R", Arg.Float (fun r → resolution := r), "");
 ("-Pa", Arg.String (fun s → action := Regression (ASCII, s)), "");
 ("-Pb", Arg.String (fun s → action := Regression (Binary, s)), "");
 ("-p", Arg.String (fun s → suffix := s), "histogram_name_suffix");
 ("-h", Arg.Unit (fun () →
  histogram_to_file := Histogram.as_bins_to_file), "");
 ("-bd", Arg.String (fun s → block_data := Some s), "");
 ("-b", Arg.Int (fun n → nbins := n), "#bins");
 ("-s", Arg.Set shrink, "shrinkwrap_interval[default]");
 ("-S", Arg.Clear shrink, "don't_shrinkwrap_interval");
 ("-t", Arg.Set triangle,

```



```

    "project_symmetrical_distribution_onto_triangle");
  ("-v", Arg.Set verbose, "verbose");
  ("-test1", Arg.String (fun s →
    action := Test (s, fun x y → 1.0)), "testing");
  ("-test2", Arg.String (fun s →
    action := Test (s, fun x y → x *. y)), "testing");
  ("-test3", Arg.String (fun s →
    action := Test (s, fun x y → 1.0 /. x +. 1.0 /. y)), "testing");
  ("-testm", Arg.Int (fun seed → action := Test_Diffmaps seed),
    "testing_maps" ]
  (fun names → prerr_endline usage; exit 2)
  usage;
begin try
  match !action with
  | Nothing → ()
  | Commands name → Commands.execute (Commands.parse_string name)
  | Command_file name → Commands.execute (Commands.parse_file name)
  | Histo (ASCII, name) →
    histogram_data !histogram_to_file !nbins
    (histogram_ascii name) !suffix
  | Histo (Binary, "-") →
    histogram_data !histogram_to_file !nbins
    (histogram_binary_channel stdin) !suffix
  | Histo (Binary, name) →
    histogram_data !histogram_to_file !nbins
    (histogram_binary name) !suffix
  | Moments (ASCII, name) → moments_data (moments_ascii name)
  | Moments (Binary, name) → moments_data (moments_binary name)
  | Power (ASCII, name) →
    power_data !histogram_to_file !nbins !center !resolution
    (histogram_ascii name) !suffix
  | Power (Binary, name) →
    power_data !histogram_to_file !nbins !center !resolution
    (histogram_binary name) !suffix
  | Regression (ASCII, name) → regression_data !nbins (histogram_ascii name)
  | Regression (Binary, name) → regression_data !nbins (histogram_binary name)
  | Cat → cat !columns !input !output
  | Log10 → log10_xy !columns !input !output
  | Exp10 → exp10_xy !columns !input !output
  | Test (name, f) → test !verbose !triangle !shrink !nbins name f
  | Test_Diffmaps seed → test_maps seed

```

```

with
| Commands.Parse_Error msg →
    Printf.eprintf "%s:␣parse␣error:␣%s␣\n" Sys.argv.(0) msg;
    exit 1
end;
exit 0

```

Identifiers

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 KK: [183c](#), [183d](#), [183e](#), [183c](#), [184b](#), [184c](#)
 L: [180d](#), [181e](#), [181f](#), [182a](#), [180d](#), [180d](#), [184b](#), [184c](#), [185a](#), [185c](#)
 M: [81b](#), [176a](#), [177d](#), [177f](#), [181e](#), [181f](#), [182a](#), [183e](#), [184c](#), [185a](#)
 MAGICO: [177a](#), [177b](#), [181b](#), [182c](#)
 NN: [176d](#), [176e](#), [177a](#), [178a](#), [179a](#), [179e](#), [180c](#)
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 circe2_sample_binary: [79](#)
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 cir2gp: [63a](#), [63b](#)
 cir2lb: [83d](#)
 random: [80a](#), [80b](#), [81b](#), [81c](#), [81d](#), [180c](#)
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B taorng: The Portable Random Number Generator from The Art of Computer Programming

B.1 User's Manual

The second editions of volume two of Donald E. Knuth' *The Art of Computer Programming* [12] had always been celebrated as a prime reference for random number generation. In 1996, Don Knuth made his notes for future editions available on the internet in the form of errata, which have in the meantime have been incorporated in the third edition.

These notes contain a gem of a *portable* random number generator. It generates 30-bit integers with the following desirable properties

- they pass all the tests from George Marsaglia's "diehard" suite of tests for random number generators [13].
- they can be generated with portable signed 32-bit arithmetic (Fortran can't do unsigned arithmetic)
- it is faster than other lagged Fibonacci generators
- it can create at least $2^{30} - 2$ independent sequences

Functions returning single reals and integers:

```
174a <API documentation 174a>≡  
      double precision u  
      integer i  
      call taornu (u)  
      call taorni (i)
```

Subroutines filling arrays of reals and integers:

```
174b <API documentation 174a>+≡  
      integer i(n), n  
      integer u(n)  
      subroutine taornv (i, n)  
      subroutine taornj (u, n)
```

Subroutine for changing the seed:

```
174c <API documentation 174a>+≡  
      integer seed  
      subroutine taorns (seed)
```

Subroutine for changing the luxury:

```
175a <API documentation 174a>+≡
      integer luxury
      subroutine taornl (luxury)
```

B.2 Implementation

```
175b <taorng.f90 175b>≡
! $Id: postlude.nw,v 1.24 2001/10/30 11:47:54 ohl Exp $
! Copyright (C) 1996-2011 by
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! along with this program; if not, write to the Free Software
! Foundation, Inc., 675 Mass Ave, Cambridge, MA 02139, USA.
module tao_rng
  use kinds

  implicit none
  private

  <taorng.f90: public 176b>

  contains

  <taorng.f90: subroutines 176c>
end module tao_rng
```

B.2.1 High Level Routines

Single Random Numbers A modulus of 2^{30} is the largest we can handle in *portable* (i.e. *signed*) 32-bit arithmetic

```
176a  <Modulus M 176a>≡
      integer , parameter :: M = 2**30
A random integer  $r$  with  $0 \leq r < 2^{30} = 1073741824$ :
176b  <taorng.f90: public 176b>≡
      public :: taorni
176c  <taorng.f90: subroutines 176c>≡
      subroutine taorni (r)
        integer :: r
        <Buffer 176d>
        <Check magic number 177a>
        <Step i and reload a iff necessary 176e>
        r = a(i)
      end subroutine taorni
```

The low level routine `taorng` will fill an array a_1, \dots, a_N , which will be consumed and refilled like an input buffer. We need at least $N \geq K = 100$ for the call to `taorng`. Higher values don't change the results, but make `taorng` more efficient (about a factor of two, asymptotically). DEK recommends $N \geq 1000$.

```
176d  <Buffer 176d>≡
      integer, parameter :: NN = 1000
      integer, dimension(NN), save :: a(NN)
      integer :: i, n
      !!! common /taornb/ a, i, n
      !!! save /taornb/
```

Increment the index `i` and reload the array `a`, iff this buffer is exhausted. Throughout these routines, `i` will point to random number that has just been consumed. For the array filling routines below, this is simpler than pointing to the next waiting number.

```
176e  <Step i and reload a iff necessary 176e>≡
      i = i + 1
      if (i .gt. n) then
        call taorng (a, NN)
        i = 1
      end if
```

We add an integer to the common block which we can check for initialization by filling it with an unlikely “magic” number.

```
176f  <Buffer 176d>+≡
```



```

    <Magic number MAGIC0 177b>
    integer :: magic
    !!! common /taornb/ magic

```

Iff the magic number is not found, trigger a buffer refill.

```

177a <Check magic number 177a>≡
    if (magic .ne. MAGIC0) then
        n = NN
        i = n
        magic = MAGIC0
    end if

```

Incidentally, the magic number is the date on which DEK wrote down the routines discussed below.

```

177b <Magic number MAGIC0 177b>≡
    integer MAGIC0
    parameter (MAGIC0 = 19950826)

```

A random real $r \in [0, 1)$. This is almost identical to `taorni`, but we duplicate the code to avoid the function call overhead for speed.

```

177c <taorng.f90: public 176b>+≡
    public :: taornu

177d <taorng.f90: subroutines 176c>+≡
    subroutine taornu (r)
        real(kind=double) :: r
        <Modulus M 176a>
        real(kind=double), parameter :: INVM = 1D0/M
        <Buffer 176d>
        <Check magic number 177a>
        <Step i and reload a iff necessary 176e>
        r = INVM * a(i)
    end subroutine taornu

```

Arrays of Random Numbers Fill the array v_1, \dots, v_ν with uniform deviates $v_i \in [0, 1)$. This has to be done such that the underlying array length in `taorng` is transparent to the user. At the same time we want to avoid the overhead of calling `taornu` ν times.

```

177e <taorng.f90: public 176b>+≡
    public :: taornv

177f <taorng.f90: subroutines 176c>+≡
    subroutine taornv (v, nu)
        real(kind=double), dimension(:) :: v

```

```

integer :: nu
  ⟨Modulus M 176a⟩
real(kind=double), parameter :: INVM = 1D0/M
integer :: done, todo, chunk, k
  ⟨Buffer 176d⟩
  ⟨Check magic number 177a⟩
  ⟨Prepare array a and done, todo, chunk 178a⟩
  ⟨Get first chunk of reals 178b⟩
do
  ⟨Update i, done and todo and set new chunk 178c⟩
  if (chunk .le. 0) then
    exit
  else
    ⟨Get another chunk of reals 179a⟩
  end if
end do
end subroutine taornv

```

i is used as an offset into the buffer *a*, as usual. *done* is an offset into the target. We still have to process all *nu* numbers. The first chunk can only use what's left in the buffer.

178a *⟨Prepare array a and done, todo, chunk 178a⟩*≡

```

  if (i .ge. n) then
    call taornv (a, NN)
    i = 0
  endif
  done = 0
  todo = nu
  chunk = min (todo, n - i)

```

178b *⟨Get first chunk of reals 178b⟩*≡

```

  do k = 1, chunk
    v(k) = INVM * a(i+k)
  end do

```

This logic is a bit weird, but after the first chunk, *todo* will either vanish (in which case we're done) or we have consumed all of the buffer and must reload. In any case we can pretend that the next chunk can use the whole buffer.

178c *⟨Update i, done and todo and set new chunk 178c⟩*≡

```

  i = i + chunk
  done = done + chunk
  todo = todo - chunk
  chunk = min (todo, n)

```

As just mentioned, when we get here, we have to reload.

```
179a  <Get another chunk of reals 179a>≡
      call taorng (a, NN)
      i = 0
      do k = 1, chunk
        v(done+k) = INVM * a(k)
      end do
```

Fill the array j_1, \dots, j_ν with random integers $0 \leq j_i < 2^{30} = 1073741824$. Again, this has to be done such that the underlying array length in `taorng` is transparent to the user and we want to avoid the overhead of calling `taorni` ν times.

```
179b  <taorng.f90: public 176b>+≡
      public :: taornj

179c  <taorng.f90: subroutines 176c>+≡
      subroutine taornj (j, nu)
        integer, dimension(:) :: j
        integer :: nu
        integer :: done, todo, chunk, k
        <Buffer 176d>
        <Check magic number 177a>
        <Prepare array a and done, todo, chunk 178a>
        <Get first chunk of integers 179d>
        do
          <Update i, done and todo and set new chunk 178c>
          if (chunk .le. 0) then
            exit
          else
            <Get another chunk of integers 179e>
          end if
        end do
      end subroutine taornj

179d  <Get first chunk of integers 179d>≡
      do k = 1, chunk
        j(k) = a(i+k)
      end do

179e  <Get another chunk of integers 179e>≡
      call taorng (a, NN)
      i = 0
      do k = 1, chunk
        j(done+k) = a(k)
      end do
```

```

180a  <taorng.f90: public 176b>+≡
      public :: taornl

180b  <taorng.f90: subroutines 176c>+≡
      subroutine taornl (luxury)
        integer :: luxury
        <Buffer 176d>
        <Check magic number 177a>
        <Set n from luxury 180c>
      end subroutine taornl

180c  <Set n from luxury 180c>≡
      if (luxury .gt. NN) then
        print *, 'taornl: luxury ', luxury, ' too high!'
        print *, 'taornl: will use 1 random number out of ', NN, '!'
        n = 1
      else if (luxury .lt. 1) then
        print *, 'taornl: luxury ', luxury, ' invalid!'
        print *, 'taornl: will use every random number!'
        n = NN
      else
        n = NN / luxury
      end if
      i = min (i, n)

```

B.2.2 30-Bit Low Level Routines

Generation

$$X_j = (X_{j-100} - X_{j-37}) \mod 2^{30} \quad (82)$$

```

180d  <Lags K, L 180d>≡
      integer, parameter :: K = 100, L = 37

```

Fill the array a_1, \dots, a_n with random integers $0 \leq a_i < 2^{30}$. As mentioned above, we *must* have $n \geq K$, while higher values don't change the results and make thing more efficient. Since users are not expected to call **taorng** directly, we do *not* check for $n \geq K$ and assume that the caller knows what (s)he's doing ...

```

180e  <taorng.f90: public 176b>+≡
      public :: taorng

```

```

181a  <taorng.f90: subroutines 176c>+≡
      subroutine taorng (a, n)
        integer :: n
        integer, dimension(n) :: a
        <Lags K, L 180d>
        <Modulus M 176a>
        <State 181c>
        integer :: j
        <Load a and refresh ranx 181b>
      end subroutine taorng

```

First make sure that `taorns` has been called to initialize the generator state:

```

181b  <Load a and refresh ranx 181b>≡
      if (magic .ne. MAGIC0) call taorns (0)

181c  <State 181c>≡
      <Magic number MAGIC0 177b>
      integer ranx(K), magic
      common /taornc/ ranx, magic
      save /taornc/

```

`ranx(1:K)` is already set up properly:

```

181d  <Load a and refresh ranx 181b>+≡
      do 10 j = 1, K
        a(j) = ranx(j)
      10 continue

```

The remaining $n - K$ random numbers can be gotten directly from the recursion (82):

```

181e  <Load a and refresh ranx 181b>+≡
      do 11 j = K+1, n
        a(j) = a(j-K) - a(j-L)
        if (a(j) .lt. 0) a(j) = a(j) + M
      11 continue

```

Do the recursion (82) K more times to prepare `ranx(1:K)` for the next invocation of `taorng`.

```

181f  <Load a and refresh ranx 181b>+≡
      do 20 j = 1, L
        ranx(j) = a(n+j-K) - a(n+j-L)
        if (ranx(j) .lt. 0) ranx(j) = ranx(j) + M
      20 continue
      do 21 j = L+1, K
        ranx(j) = a(n+j-K) - ranx(j-L)
        if (ranx(j) .lt. 0) ranx(j) = ranx(j) + M

```

21 continue

In the future, we will be able to save four of the above 15 lines, by using Fortran90's array assignments. While the terse syntax might be a matter of taste, it is certainly useful for suggesting aggressive optimizations to the compiler. The two other loops implement the lagged Fibonacci and *can not* be replaced by array assignments because the assignments overlap.

182a \langle Load **a** and refresh **ranx** (Fortran90) 182a $\rangle \equiv$
 a(1:K) = **ranx**(1:K)
 do j = K+1, n
 a(j) = **a**(j-K) - **a**(j-L)
 if (**a**(j) < 0) **a**(j) = **a**(j) + M
 end do
 ranx(1:L) = **a**(n+1-K:n+L-K) - **a**(n+1-L:n)
 where (**ranx**(1:L) < 0) **ranx**(1:L) = **ranx**(1:L) + M
 do j = L+1, K
 ranx(j) = **a**(n+j-K) - **ranx**(j-L)
 if (**ranx**(j) < 0) **ranx**(j) = **ranx**(j) + M
 end do

Initialization The non-trivial and most beautiful part is the algorithm to initialize the random number generator state **ranx** with the first 100 numbers. I haven't studied algebra over finite fields in sufficient depth to consider the mathematics behind it straightforward. The commentary below is rather verbose and reflects my understanding of DEK's rather terse remarks (solution to exercise 3.6-8 [12]).

182b \langle taorng.f90: public 176b $\rangle + \equiv$
 public :: taorns

182c \langle taorng.f90: subroutines 176c $\rangle + \equiv$
 subroutine taorns (seedin)
 integer, intent(in) :: seedin
 integer :: seed
 \langle Lags K, L 180d \rangle
 \langle Modulus M 176a \rangle
 \langle Other parameters 183a \rangle
 \langle State 181c \rangle
 \langle Local variables 183d \rangle
 \langle Verify seed 183b \rangle
 \langle Bootstrap the x buffer 183e \rangle
 \langle Set up s and t 183g \rangle
 do
 $\langle p(z) \rightarrow p(z)^2 \text{ (modulo 2 and } z^{100} + z^{37} + 1) \text{ 184a} \rangle$

```

       $\langle p(z) \rightarrow zp(z) \text{ (modulo 2 and } z^{100} + z^{37} + 1) \text{ 185a} \rangle$ 
       $\langle \text{Shift s or t 185b} \rangle$ 
      if (t .le. 0) exit
    end do
     $\langle \text{Fill ranx from x 185c} \rangle$ 
    magic = MAGIC0
  end subroutine taorns

```

183a $\langle \text{Other parameters 183a} \rangle \equiv$

```
integer, parameter :: SEEDMX = 2**30 - 3
```

183b $\langle \text{Verify seed 183b} \rangle \equiv$

```

seed = seedin
if ((seed .lt. 0) .or. (seed .gt. SEEDMX)) then
  print *, 'taorns: seed (', seed, ') not in [0,', SEEDMX, ']'
  seed = mod (abs (seed), SEEDMX+1)
  print *, 'taorns: seed set to ', seed, '!'
end if

```

183c $\langle \text{Other parameters 183a} \rangle + \equiv$

```
integer, parameter :: TT= 70, KK = K+K-1
```

183d $\langle \text{Local variables 183d} \rangle \equiv$

```
integer x(KK), j, s, t
```

Fill the array $x_1, \dots, x_{K=100}$ with even integers, shifted cyclically by 29 bits.

183e $\langle \text{Bootstrap the x buffer 183e} \rangle \equiv$

```

s = seed - mod (seed, 2) + 2
do j = 1, K
  x(j) = s
  s = s + s
  if (s .ge. M) s = s - M + 2
end do
do j = K+1, KK
  x(j) = 0
end do

```

Make x_2 (and only x_2) odd:

183f $\langle \text{Bootstrap the x buffer 183e} \rangle + \equiv$

```
x(2) = x(2) + 1
```

183g $\langle \text{Set up s and t 183g} \rangle \equiv$

```

s = seed
t = TT - 1

```

Consider the polynomial

$$p(z) = \sum_{n=1}^K x_n z^{n-1} = x_{100} z^{99} + \dots + x_2 z + x_1 \quad (83)$$


We have $p(z)^2 = p(z^2) \pmod{2}$ because cross terms have an even coefficient and $x_n^2 = x_n \pmod{2}$. Therefore we can square the polynomial by shifting the coefficients. The coefficients for $n > K$ will be reduced $\pmod{2}$ below.

184a $\langle p(z) \rightarrow p(z)^2 \pmod{2 \text{ and } z^{100} + z^{37} + 1} \text{ 184a} \rangle \equiv$
do j = K, 2, -1
x(j+j-1) = x(j)
end do

The coefficients of the odd powers (those with the even indices) have not been changed yet. Set them to a flipped version

$$\begin{aligned} x_2 &\leftarrow \text{even } x_{2K-1=199} \\ x_4 &\leftarrow \text{even } x_{2K-3=197} \\ &\dots \\ x_{K+L-1=136} &\leftarrow \text{even } x_{K-L+2=65} \end{aligned} \quad (84)$$

of the other coefficients with the least significant bit set to 0.

 DEK's notes contain an (insignificant) typo here do 21 j = KK, K-L+1, -2, because K is even and L is odd. (If it is on purpose to accomodate simultaneously odd lags, then the C version is wrong.)

184b $\langle p(z) \rightarrow p(z)^2 \pmod{2 \text{ and } z^{100} + z^{37} + 1} \text{ 184a} \rangle + \equiv$
do j = KK, K-L+2, -2
x(KK-j+2) = x(j) - mod (x(j), 2)
end do

Let's return to the coefficients for $n > K$ generated by the shifting above. Subtract $z^n(z^{100} + z^{37} + 1)$ iff the coefficient of $z^n z^{100}$ doesn't vanish $\pmod{2}$ after squaring. The coefficient of $z^n z^{100}$ is left alone, because it doesn't belong to $p(z)$ anyway.

184c $\langle p(z) \rightarrow p(z)^2 \pmod{2 \text{ and } z^{100} + z^{37} + 1} \text{ 184a} \rangle + \equiv$
do j = KK, K+1, -1
if (mod (x(j), 2) .eq. 1) then
x(j-(K-L)) = x(j-(K-L)) - x(j)
if (x(j-(K-L)) .lt. 0) x(j-(K-L)) = x(j-(K-L)) + M
x(j-K) = x(j-K) - x(j)
if (x(j-K) .lt. 0) x(j-K) = x(j-K) + M
end if
end do


```

185a   $\langle p(z) \rightarrow zp(z) \text{ (modulo 2 and } z^{100} + z^{37} + 1) \text{ 185a)} \equiv$ 
      if (mod (s, 2) .eq. 1) then
        do j = K, 1, -1
          x(j+1) = x(j)
        end do
        x(1) = x(K+1)
        if (mod (x(K+1), 2) .eq. 1) then
          x(L+1) = x(L+1) - x(K+1)
          if (x(L+1) .lt. 0) x(L+1) = x(L+1) + M
        end if
      end if

185b   $\langle \text{Shift s or t 185b} \rangle \equiv$ 
      if (s .ne. 0) then
        s = s / 2
      else
        t = t - 1
      end if

185c   $\langle \text{Fill ranx from x 185c} \rangle \equiv$ 
      do j = 1, L
        ranx(j+K-L) = x(j)
      end do
      do j = L+1, K
        ranx(j-L) = x(j)
      end do

```

B.2.3 Testing

```

185d   $\langle \text{taorng.f90: public 176b} \rangle + \equiv$ 
      public :: taornt

185e   $\langle \text{taorng.f90: subroutines 176c} \rangle + \equiv$ 
      subroutine taornt ()
        implicit none
         $\langle \text{Buffer 176d} \rangle$ 
        integer :: j, r
        integer, dimension(10), save :: expect = &
          (/ 640345214, 443605255, 411993687, 618952382, 123106306, &
            949854402, 429877922, 261135009, 574783260, 1043288376 /)
        write (*, 100) 'testing taorng ...'
        write (*, 100) ' call taornl (luxury=1)'
100   format (1X, A)
        call taornl (1)
        write (*, 100) ' call taorns (seed=0)'

```

```

call taorns (0)
<Reset the buffer 186a>
print *, ' 10000 warmup calls to taorni'
do j = 1, 10000
    call taorni (r)
end do
do j = 1, 10
    call taorni (r)
    if (r .eq. expect(j)) then
        write (*, 101) 10000+j, r
101      format (3X, I5, ': ', I10, ' OK.')
    else
        write (*, 102) 10000+j, r, expect(j)
102      format (3X, I5, ': ', I10, ' not OK, (expected ', I10, ')!')
    end if
end do
write (*, 100) 'done.'
stop
end subroutine taornt

```

This is crucial, in case the buffer has been used:

```

186a <Reset the buffer 186a>≡
      i = N

```

B.3 Testing

```

186b <sample_tao_rng.f90 186b>≡
program circe2_tao_tst
  use kinds
  use tao_rng

  implicit none
  integer :: i, N, S
  real(kind=double) :: r
  real(kind=double) :: sum30
  call taornt ()
  S = 0
  N = 10000000
  sum30 = 0
  call taorns (S)
  do i = 1, N
      call taornu (r)

```

```
        sum30 = sum30 + r
    end do
    print *, 'sum30 = ', sum30
end program circe2_taotst
```